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Spatial Distribution of Traffic in a Cellular Mobile Data Network

by J.P.M.G. Linnartz

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Abstract

The position of a mobile terminal has a significant influence on its probability to capture the central receiver in the base station of a cellular radio system using slotted ALOHA for multiple access. Integral transforms of the probability density function for the received power prove a useful tool for analysing the relation between the spatial distributions of offered and throughput packet traffic in a mobile radio network with Rayleigh fading channels.

A newly developed method to obtain the spatial distribution of throughput traffic from a prescribed spatial distribution of offered traffic is presented and illustrated with examples. Incoherent and coherent addition of interference signals is considered. The channel behaviour for heavy traffic loads is studied. In both the incoherent and coherent case, the spatial distribution of offered traffic required to ensure a prescribed spatially uniform throughput is synthesised numerically.

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Only frequently used symbols are contained in this list

<u>symbol</u>		equation
f(x)	probability density function of random variable X	
F_	capture probability given Z_0 and n	4.48
z,n g(v)	Laplace image of the area mean power pdf	4.1
G	total offered traffic (packets per slot= pps)	1.9
G(p)	offered traffic per unit area and per slot s	ec 1.4.2
Gn	uniform offered traffic distribution in unit circ	le 5.22
·	N.B. in some special cases: traffic per unit area	4.28
Ι(ρ)	capture probability, given Z_0 , n and ρ	4.49
n z,n	number of interferers in the test time slot	1.1
P	actual value of the test packet power	2.1
P	area mean value of the test packet power	1.8
P	actual value of the joint interference power	sec 2.2
P_	mean value of the joint interference power	sec 2.2
R	probability of n contenders in the test time slot	1.1
s(v)	image of throughput traffic	6.11
S	total throughput traffic	1.10
S(p)	throughput traffic per slot and per unit area s	ec 1.4.2
s _o	uniform traffic throughput distribution per unit	area 3.1
S	throughput traffic if the total offered traffic i	S
	increased without limit	sec 5.5
t,	synchronisation window	1.4
v	argument of the image functions $(watt^{-1})$	4.1
W _z (.)	traffic weighting function in incoherent analysis	5.7
z	receiver threshold in the event of n interferers	1.4
z_0^{n}	universal receiver threshold	5.3
R	nath loss exponent	15
Р Р	small distance from the base station optoppo	5 3 2
11	k-th moment of mean power pdf	J•J2
^µ k	normalized distance between terminal and have the	4.7
ν τ	normalised distance between terminal and base sta	$\begin{array}{c} 1 \\ 1 \\ 1 \\ 1 \\ 2 \\ 2 \\ 2 \\ 2 \\ 2 \\ 2 \\$
ນ	k-th moment of instantaneous power pdf	
ົk ሐ(ນ)	Lanlace image of instantaneous power off	/ 36
¥*/	makrace image of fuscantaneous hower but	4.30

N.B. $g^{n}(v)$ n-th power of the function g(v) $g^{(k)}(v)$ k-th derivative of the function g(v)

1 INTRODUCTION TO CELLULAR DATA COMMUNICATION

1.1 Mobile data communication

Most of today's mobile radio systems offer analogue (speech) communication facilities. However, in land-mobile radio, messages are often short and stereotyped. Most user categories require message lenghts of approximately 15 seconds, except in the taxi service (with shorter messages-about 8 sec) and some services with longer messages [21]. For many of these categories, introduction of transmission of digital (non-voice) messages is a result of an increased demand for mobile radio and the need to use the radio spectrum more efficiently. Data messages can be sent more quickly and reliably, with less operator involvement. For example, names and addresses are notoriously difficult to receive correctly with speech and usually involve the operator in repetitions and errors. With data communication, new facilities are possible, such as vehicle printers and automatic repetition of messages if the driver has been away from the vehicle. Coding and processing of messages become possible, too.



Système de gestion de flotte.

Figure 1.1: Example of a typical fleet management system [33].

Direct access to a control computer can enable a fleet of vehicles to operate more efficiently [33]. Figure 1.1 gives an example of the fleet management system of the Paris bus service RATP, installed in 1974. Many mobile users are interested in data stored in computer files. Radio communication has emerged as a flexible method for providing remote terminal access to computers.

- 1 -

Packet radio technology [22] [3] offers a highly efficient way of sharing a multiple access radio channel among a potentially large number of mobile subscribers, for instance to support computer communications or to provide local distribution of information. Data from each user is buffered, address and control information is added in a "header", and the resulting bit sequence, or "packet", is transmitted over the shared radio channel.

Although in many cases the more powerful facilities offered by data systems may seem attractive, it is often difficult to make a real case to justify the extra cost. However this picture is changing as an increasing number of users complain about congested channels and so begin to experience a loss in efficiency while waiting for a channel to become available.

1.2 <u>Multiple access</u>

In a mobile communication service with many users with "bursty" messages, some kind of collision-type multiple access is unavoidable. The call request and set-up signalling channel of a mobile telephone service is a typical example of such a data channel. Preller and Koch [20] reported on the MATS-E telephone system, where one control channel is assigned to the base station (BS) on which all functions emanating from (or directed toward) the many mobile stations (MS's) in the cell are handled concurrently. Digital dialogue initiation by a MS leads to one of the most severe problems of control-channel design, because of the vast need for access capacity to serve the randomly occuring, numerous and different service functions initiated by MS's. Message collisions can result in limited channel throughput, and simulation efforts are used to optimise the access capacity.

Channel protocols for packet radio described by Sinha and Gupta [22] reduce the collision problem by carrier-sense methods. Basic properties of many multiple access schemes can be understood by reducing the collision-type channel to its elementary form: the ALOHA-system.

- 2 -

1.2.1 The ALOHA-system

The simplest possible solution to the multiple access problem is employed. Each user transmits over the packet broadcasting channel in a completely unsynchronised manner. All active terminals are assumed to transmit their messages to a single receiver over a common channel in packets of duration τ , regardless of the activity of competing terminals. If each individual user of the common channel is required to have a low activity, the probability of a packet from one user interfering with a packet from another user is small as long as the total number of users is not too large. As the number of users increases, however, the number of packet overlaps increases and the probability that a packet will be lost due to an overlap also increases. In figure 1.2 we show a packet broadcasting channel with two overlapping packets.



Figure 1.2: Packets offered to the multiple access channel [3].

An unsuccessful packet will be retransmitted after waiting a random period of time. The multiple-access system is memoryless, i.e., a retransmitted packet experiences overlaps uncorrelated with its previous attempts to capture the receiver.

Additional aspects of the ALOHA-system studied in this thesis are slotted transmission of packets and the fact that a collision of packets does not always lead to loss of all messages involved.

1.3 Slotted ALOHA and capture effect

In slotted ALOHA, the only network discipline imposed on transmitters is that all dispatched packets must fit into common timeslots of length τ . If messages conflict they will overlap completely rather than partially. Compared with unslotted ALOHA, this strategy thus yields an increased throughput of the channel [3].

- 3 -

1.3.1 Channel throughput

Let the number of packets generated in the network be Poisson distributed. The probability of an arbitrary test packet being overlapped by n other packets is then [43]

$$\mathbf{R}_{n} = \frac{\mathbf{G}^{n}}{n!} \exp\{-\mathbf{G}\}, \qquad (1.1)$$

with G the mean offered total channel traffic expressed in packets per time slot. The pessimistic assumption made in studies of standard ALOHA [44] networks is that any overlap of packets invariably leads to mutual destruction of all n+1 packets present in that slot. In this event the probability for a test packet to capture the receiver becomes

$$P_{capt} = R_0 = 1 - \sum_{n=1}^{\infty} R_n$$
 (1.2)

The total traffic throughput S can be found from [3][44]

$$S = G P_{capt} = G e^{-G},$$
 (1.3)

which is illustrated in figure 1.3.



Figure 1.3: Throughput S as a function of the offered traffic G for slotted ALOHA.

Metzner [2] has shown that intentional division of the users in two categories: users transmitting at high power ("loud talkers") and users transmitting at low power ("quiet talkers"), increases the capacity of the multiple access system, as a packet of a loud talker survives a collision with packets from quiet talkers. Namislo [24] has studied the dynamic behaviour of an ALOHA multiple access system where not all packets experiencing collisions are lost, using a Markov chain model. He demonstrated that the differences in received power between various packets (due to fading and path loss), increase channel capacity and that the system can be very stable under overload. Kuperus and Arnbak [35] studied the throughput properties of the mobile ALOHA channel with the offered traffic distributed in a circular tape centered on the base station receiver. Numerical results show that fading "softens" the channel compared with the contentions of pure ALOHA. The probability of destruction of a packet is modelled as the probability that the signal to interference ratio (SIR) exceeds a certain limit [1] [13] [35].

1.3.2 Capture effect

We shall assume a radio receiver which can be captured by a test packet in the presence of n interfering packets, if the power of the former (P_s) sufficiently exceeds the joint interference power (P_n) during a certain section (the sync. window, of duration t_w) of the timeslot τ . Consequently, the test packet is considered destroyed in the collision if (and only if)

$$P_{g}/P_{n} < Z_{n}$$
 during t, with $n > 0$. (1.4)

As the statistic properties of the joint interference signal may depend on the number of interferers n, the receiver threshold Z_n might also depend on n. In chapters 5 and 6 we will assume a universal threshold (i.e., independent of n), which leads to interesting conclusions for the spatial distribution of traffic.

Montomery [36] has given an analytic solution for the performance of a perfect demodulator if the interference behaves like bandlimited Gaussian noise.

As the received power will be assumed constant at least during t,, typical values of the receiver threshold will be more optimistic than in many reports on digital mobile communication where usually fading of the signal during the capture period is assumed [39]. Literature on the characteristics of modulation techniques for data communication and their thresholds has been summarised by Oetting [40]. For large numbers of interferers, the resulting signal may resemble band-limited Gaussian noise. The capture performance in this case is illustrated for various modulation schemes in figure 1.4 and expressed in the energy per bit E_{h} divided by the interference spectral density N_0 , assuming instant synchronisation (t =0) and a capture criterion of an error rate of $P_a \leq 10^{-4}$.

TYPE	MODULATION SCHEME	SPEED (b/s PER Hz)	E.M. (48)*
	OOK - COHERENT DETECTION	0.8	12.5
	OOK - ENVELOPE DETECTION		
~	QAM	1.7	9.5
_	OPB .	2.25	11.7
	FSK - NONCOMERENT DETECTION	0.8	31.8**
~	CP-FSK - COHERENT DETECTION	<u></u>	
r HA	CP FSK - NONCOHERENT DETECTION	1.0	10.7
	MSK (d = .5)	19	1.4
	MSK - DIFFERENTIAL ENCODING (d + .5)	1.9	10.4
	BPSK - CONERENT DETECTION	0.8	9.4
	DE BPSK	0.8	2.9
	DPSK	08	10.6
DL A	OPSK	19 .	9.9
	DOPSK	1.8	\$1.8
	OK-OPSK		
	Bary PSK - COHERENT DETECTION	2.6	12.8
	16-ary PSK - COHERENT DETECTION	2.9	17.2
AM 'PM	16 WY APK	3.1	13.4

d * FM MODULATION INDEX

1 CALCULATED FROM RESULTS FOR BASK

Figure 1.4: Performance of representative modulation schemes [40].

The given $E_{h}^{N_{0}}$ rate can be transferred to signal interference ratios by multiplying by R/W, where R the data rate and W the bandwidth [40].

The receiver threshold becomes

$$Z_{\infty} = \frac{E}{N_0} b \frac{R}{W}.$$
 (1.5)

In this thesis, thermal noise effects will be neglected throughout, corresponding to an "ideal", interference-limited design of the network. In practice, this ideal can be reached by raising all transmit powers of the mobile terminals by a suitable gain factor.

1.4 Cell model

Spectrum efficiency is one of the most important aspects in modern radio service planning. The increasing demand for more communication facilities makes effective frequency reuse necessary. Frequencies allocated to the service are reused in a regular pattern of (usually hexagonal) areas called "cells". In figure 1.5 the cell structure for the Dutch radio telephone service at 150 and 450 MHz is depicted [42]. Cellular engineering has become an important discipline of mobile radio system design. It combines traffic engineering, interference management and spectrum conservation [19][29]. Cellular mobile radio differs from previous mobile radio designs in two critical areas: frequency reuse and cell splitting.

With conventional mobile radio systems, the objective is to have each fixed base station cover as large an area as possible by using antennas mounted in high towers and the maximum affordable power. A group of disjoint channels is assigned to the base station and the system configuration does not change for the lifetime of the system.

With cellular systems, the service area is divided in a large number of cells, each with its own base station. Power radiated by the base stations is kept to a minimum and the antennas are located just high enough to achieve the desired coverage. These procedures enable non-adjacent cells to use the same set of frequencies, which is the frequency reuse feature mentioned above [26].



Cell structure for the Dutch radio telephone service at 150 and 450 MHz.

As the demand for services increases, the number of channels assigned to a cell will become insufficient to provide the required grade of service. At this point, cell splitting can be used to increase the number of customers that can be served in a given area without increasing the number of available channels. This process works by subdividing the congested cell into smaller cells (each with its own base station), reducing the antenna height and transmitted power of the new base stations, and reusing the same frequencies in some efficient pattern.

Gosling [23] described the interdependence between frequency reuse distance and required protection ratio, considering only one single co-channel interferer. Diakoku and Ohdate obtained theoretical results for optimal patterns for channel reuse [25]. Many cell structures have been studied. Basic repetition patterns with four, seven and twelve cells are often used [26]. A typical cell radius in a small-cell system can be 3 to 5 km. Improvements can be carried out by using directional antennas, so that cells can be divided in (usually three or six) angular sectors. This makes reuse patterns with only three or four cells possible and increases spectrum efficiency. Reuse partitioning [30] is a technique used to increase capacity. In practical environments with non-uniform data traffic distributions and significant propagation impairments in certain parts of the service area, optimal solutions lead to tailor-made structures with cells of different size. Stocker [28] described the cell structure of the mobile telephone systems in Chicago, Baltimore and Washington D.C., and Tokyo. Often, computer aids have been developed using a topological database [31].

In this thesis the spatial distribution of traffic inside one individual cell will be studied. Initially this distribution will be transformed into the probability density function of the received packet power. The generally accepted propagation model, based on field measurements, will be described in section 2.1 [10] [11] [27] [39] [42].

1.4.1 Attenuation law

The most general propagation aspect in cellular engineering is the attenuation law, for the mean received power as a function of distance.

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The area mean power of a packet received from a mobile terminal at a distance r from the receiving base station is of the general form [27]

$$\bar{P}_{s} = \alpha_{i} r^{-\beta}.$$
(1.6)

The exponent β gives the path attenuation law for the channel considered ($2 \leq \beta < 5$). In the event of UHF propagation in cellular radio, a typical value is $\beta=4$. The rapid fluctuations of the received power due to fading if the terminal is moved over small distances are introduced in the model at a later stage. In the event of ground-wave propagation without shadowing [11, (2.1-8)]

$$\alpha_{i} \stackrel{\Delta}{=} P_{T_{i}} G_{T_{i}} G_{R} \stackrel{H^{2}}{T_{i}} \stackrel{H^{2}}{R}, \qquad (1.7)$$

where P_{T_i} , G_{T_i} and H_{T_i} are the transmit power, antenna gain and antenna height (above ground), respectively, of the mobile terminal sending slot packet i. G_R and H_R are the gain and height above ground of the base station antenna.



Figure 1.6: A circular cell with radius r max The mobile station MS transmits a packet to the base station BS from a distance r.

If all mobile terminals are assumed identical, and if antennas with omnidirectional radiation patterns in the horizontal plane are used, we may take α_i equal to any suitable normalising constant α_0 , since the receiver capture is determined by a ratio (1.4) of signal powers.

Take $\alpha_0 = r_{max}^{\beta}$ where r_{max} is the radius of the cellular area in which the associated mobile terminals are expected to move. A circular cell, centered on the base station BS, is depicted in figure 1.6.

Although frequently used in mobile telephone systems, we do not assume adaptive transmitter power control, except perhaps to remove the shadowing effects not accounted for in this thesis. With these assumptions, both power and distance in (1.6) are normalised as

$$\bar{P}_{\rm s} = \rho^{-\beta}, \qquad (1.8)$$

with $0 < \rho \leq 1$, and $\overline{P}_{c} \geq 1$ for mobile terminals inside the cell.

1.4.2 Spatial distribution of traffic

As distinct from [24], we do not assume a discrete number of users, but use a continuous description: a traffic density per unit area at a (normalised) distance ρ from the central receiver is defined analogous to Abramson [3], Kuperus and Arnbak [35] and Arnbak and Van Blitterswijk [1].

- $G(\rho)^{\Delta}$ offered packet traffic per normalised unit area at a normalised distance ρ .
- $S(\rho)^{\Delta}$ throughput of (successful) packets sent from a normalised unit area at a normalised distance ρ .

Both spatial distributions have the dimension packets per slot per normalised unit area. Here as elsewhere, all distributions are assumed stationary. Consequently, transition and set-up phenomena and the behaviour of the channel in the event of instability cannot be studied from this model. We assume the multiple-access channel to be in equilibrium. In a typical communications environment both distributions will usually be obtained as a time average of the traffic distribution in the memoryless channel. Assuming packet generation to be an ergodic process, in this thesis these distributions will be applied to individual timeslots and thus regarded as the ensemble average. Considering one circular cell, the total traffic offered to and captured by the receiver, respectively, become

$$G = 2\pi \int_{0}^{\infty} G(\rho) \rho d\rho \qquad (1.9)$$

and
$$S = 2\pi \int_{0}^{\infty} S(\rho) \rho d\rho$$
, (1.10)

expressed in packets per slot. (With k-sector cells, the factor 2π would have to be replaced by $2\pi/k$).

The spatial distribution function for the random generation of packets trying to access the base station considered

 $F_{\rho}(\rho)^{\Delta} = Prob\{the packet is generated within distance <math>\rho\}$

$$= \frac{2\pi}{G} \int_{0}^{\rho} G(x) x dx. \qquad (1.11)$$

The corresponding pdf is

$$f_{\rho}(\rho) = \frac{2\pi}{G} G(\rho) \rho. \qquad (1.12)$$

As packets transmitted from a normalised distance ρ are received with a mean power \overline{P}_s , the pdf for the mean received packet power can be found by applying (1.8)

$$f_{\overline{P}_{s}}(\overline{p}_{s}=\rho^{-\beta}) = f_{\rho}(\rho) \left| \frac{d\rho}{d\overline{p}_{s}} \right| = f_{\rho}(\rho) \frac{\rho^{\beta+1}}{\beta}$$
(1.13)

Using (1.12) and (1.13), from the traffic density G(ρ) the pdf $f_{\vec{P}}(\vec{p}_s)$ of the mean power can be obtained as

$$f_{\overline{P}_{S}}(\overline{\rho}_{S}=\rho^{-\beta}) = \frac{2\pi}{\beta} \rho^{\beta+2} \frac{G(\rho)}{G}. \qquad (1.14)$$

1.5 Outline of the thesis

In this thesis, relations between the spatial distributions $G(\rho)$ and $S(\rho)$ will be established. As the receiver capture probability is expressed in terms of a power ratio, these spatial distributions will be transformed to appropriate received power pdf's. In chapter 4, integral transforms will be applied to these pdf's to yield mathematically more tractable equations. Given a certain distribution of the offered traffic $G(\rho)$, the throughput $S(\rho)$ can be formulated. This will be called "analysis" of the multiple access channel. Conversely, "synthesis" gives the traffic load $G(\rho)$ to be offered, if the resulting throughput $S(\rho)$ is prescribed. Both methods will be presented in chapters 5 and 6, where incoherent and coherent interference signals are considered, respectively. In chapter 2 the communication properties of the assumed mobile common radio channel will be described. In chapter 3, a discussion of the objectives of this study will be given, and previous studies of the relation between offered and throughput traffic distributions will be summarised.

2 PROPAGATION AND INTERFERENCE IN THE MOBILE CHANNEL

2.1 The mobile data radio channel

When the participants of a network are mobile, communication has to be established under most adverse propagation conditions. A microwave signal transmitted from a moving vehicle to a fixed base station in a typical urban environment exhibits extreme variations in both amplitude and apparent frequency.



Figure 2.1: Multipath reception from a mobile station MS.

The generally accepted model of mobile radio propagation is based on field experiments and involves three main aspects: path loss, shadowing and multipath fading. The path loss is described in the previous section by equation (1.8) and gives the mean received power level, averaged over an area located at a normalised distance ρ from the base station. This mean power level will be called the area mean power.

The second aspect, shadowing (slow fading) of the radio signal by buildings and hills, leads to gradual changes of the local mean received signal power as the vehicle moves. This local mean level, averaged over a distance of about 50 m is found to vary with a lognormal distribution about the area mean level. By lognormal is meant that the local mean expressed in dB is normally distributed. The standard deviation σ depends on the topography [42]. This effect, however, is not considered in this thesis, and so area mean power and local mean power are used synonymously. The introduction of shadowing in the propagation model is recommended (Rec. 2 in chapter 7) [10].

The third aspect, (rapid) fading, is caused by multipath propagation (fig. 2.1), which causes the received signal level to fluctuate rapidly as the vehicle moves along the street. The envelope $r_i(t)$ of the received electrical field strength is Rayleigh distributed.



Figure 2.2 [27]: Signal envelope pdf with Rayleigh fading and shadowing.

Figure 2.2 gives the pdf of received signal envelope in a mobile system with both Rayleigh fading and a certain degree σ of shadowing.

In this thesis "(area) mean power \overline{P}_{s} " is used to indicate the expectation value $E(P_{s}|\rho)$ of the instantaneous power P_{s} , given the distance ρ at which the test packet is transmitted. The mean power thus stands for the (ensemble) mean value of the statistical process of Rayleigh fading

$$E(P_{s}|\rho) = E(P_{s}|\vec{P}_{s}) = \int_{0}^{\infty} p_{s} f_{P_{s}}(p_{s}|\vec{P}_{s}) dp_{s} = \vec{P}_{s}.$$

$$\mu_1 \stackrel{\Delta}{=} E(\overline{P}_s) \stackrel{\Delta}{=} \int_0^{\infty} \overline{P}_s f_{\overline{P}_s}(\overline{P}_s) d\overline{P}_s.$$

With the "mean joint interference power" of n packets, which will be introduced later, we assume all n distances $\rho_1 \cdots \rho_n$ of the n terminals contributing to the interference to be known.

2.1.1 The signal received from a mobile station

With a propagation model without shadowing, the pdf's of received powers are now considered in detail. Given a normalised distance ρ between base and mobile station, the pdf of the instantaneous packet power P_s will be exponentially distributed, with area mean \overline{P}_s found from the attenuation law (1.8) [10][11], i.e.

$$f_{p_{s}}(p_{s}|\bar{p}_{s}) = \frac{1}{\bar{p}_{s}} \exp\{-\frac{p_{s}}{\bar{p}_{s}}\}$$
 (2.1)

and so

$$f_{P_{s}}(p_{s}) = \int_{\overline{P}_{s,\min}}^{\overline{P}_{s,\max}} \frac{1}{\overline{p}_{s}} \exp\{-\frac{p_{s}}{\overline{p}_{s}}\} f_{\overline{P}_{s}}(\overline{p}_{s}) d\overline{p}_{s}$$
(2.2)

The signal of the i-th packet can be written as the real part of

$$X_{i}(t) = R_{i} \exp\{j\omega_{c}t + \theta_{i}(t) + \psi_{i}(t)\}$$
(2.3)

The phase term $\theta_i(t)$ is due to random carrier phase plus Doppler shifts due to movements of the vehicle. Assuming phase modulation, the baseband data of the i-th packet in the slot is carried by the modulation angle $\psi_i(t)$.

2.1.2 Constraints on packet length

During the capture of a packet, the amplitude R_i and the power P_i are assumed to be constant with time. **Consequently**, the sync. window duration t_w has to be restricted, as can be studied from Jakes [11].



Figure 2.3 [11]: Normalised envelope autocorrelation of the electrical field strength.

The envelope $r_i(t)$ of the electrical field strength has the autocorrelation

$$R_{r_{i}}(s) \stackrel{\Delta}{=} E\{r_{i}(t) r_{i}(t+s)\},\$$

where s is the time difference between the sample points. Using the equations [11, (1.3-12) to (1.3-16)], for signals at the frequency of ω_{c} radians per second, this can be approximated with good accuracy by

$$R_{r_{i}}(s) \approx \frac{\pi}{2} \frac{3}{4} E_{0}^{2} \left[1 + \frac{1}{4} J_{0}^{2}(\omega_{c} v s/c)\right], \qquad (2.4)$$

with c the speed of light, and $J_0(.)$ the zero-order Bessel function of the first kind. The electric field strength corresponding to the area mean power is E_0 . Removing the constant term in (2.4), one obtains the covariance

$$L(s) \stackrel{\Delta}{=} E\{(r_{i}(t) - \bar{r}_{i})(r_{i}(t+s) - \bar{r}_{i})\} = R_{r_{i}}(s) - \bar{r}_{i}^{2}.$$

This is directly proportional to $J_{C}^{2}(\omega_{c}vs/c)$, which is depicted in figure 2.3. From this figure it can be concluded that, in the 900 MHz band, with vehicle speeds of 20 m/sec (72 km/h), the received power remains nearly constant during the sync. window, if

$$t_w < c / \omega_c v \approx \frac{3 \ 10^8}{2\pi \ 900 \ 10^6 \ 20} \text{ sec } \approx 2.6 \text{ msec.}$$
 (2.5)

Consequently one must restrict the distance d the vehicle may move during the sync. window, to be smaller than a fraction of the wavelength [39], say $\lambda/2\pi$, thus

$$d = vt_w < \frac{\lambda}{2\pi} = \frac{c}{\omega_c} \approx 5 cm,$$

with λ the wavelength ($\lambda \approx 0.3$ m). This result is in agreement with the typical packet duration of about 1 msec proposed by Henry and Glance [32]. Although the packet length τ can be larger than t_w , it is believed that this constraint on packet length leads to shorter packets than proposed by DaSilva et al.[34], where the packets are assumed to be received correctly if (and only if) the whole packet can be contained in a non-fade interval, i.e., the received signal level may fluctuate but must remain above a fixed threshold, determined by the modulation method and the background noise.

Recommendation 1

A study on the interdependence of the sync. window t_w, the packet duration τ and the modulation scheme and the threshold Z_n , and application of the results to the equations derived in this thesis is recommended.

2.2 Interference signals

The total interference power P_n experienced by the receiver in a particular sync. window is generally not the long-term mean \overline{P}_n , but an average taken over the (short) time interval t_w .

The joint interference power P_n of n packets is made up of n^2 terms, namely

$$P_{n} = \frac{1}{t} \int_{w}^{t_{0}+t} \sum_{i=1}^{n} X_{i}(t) \int_{j=1}^{n} X_{j}^{*}(t) dt. \qquad (2.6)$$

2.2.1 Incoherent addition

In mobile cellular radio where packets are transmitted by many different terminals without any mutual control of carrier signals, the received signals add incoherently. In this event the phase terms of the signals may vary sufficiently fast (e.g. due to differences in carrier frequencies, Doppler shifts or modulation) to assume all crossproducts to vanish. The joint interference power, $P_n^{incoherent}$, now equals

$$P_{n}^{i} = \sum_{i=1}^{n} \frac{1}{t} \int_{w}^{t_{0}+t_{w}} X_{i}(t) X_{i}^{*}(t) dt = \sum_{i=1}^{n} P_{i}.$$
 (2.7)

From this equation, the mean joint interference power is found by summing the individual area mean signal powers. The pdf of the joint interference power is then the n-fold convolution of f $_{P_s}$

$$f_{P_n}^i(p_n) = \{f_{P_s}(p_n)\}^{*n}$$
 (2.8)

The statistical behaviour of the joint interference signal depends on the number of interferers. For n=1, the interference is a phase modulated sine-wave signal, while for $n \rightarrow \infty$ the interference resembles (bandlimited) Gaussian noise. The latter follows from the central limit theorem.

Boomars [14] reported on the pdf of incoherently interfering signals from different cells, and demonstrated the dependence of the interference pdf on the number of signals.

2.2.2 Coherent addition

So far we have assumed incoherent addition of the received signals. However, mathematical calculation shows [1] that the channel throughput can be increased if the interfering signals would add coherently during the packet. For example, in a state-of-art mobile network, the individual mobile stations could slave their carrier signal to some signal from the base station by means of a phase locked loop, so coherent addition of interfering signals may become more appropriate. If the phase terms $\theta_i(t)$ and $\psi_i(t)$ remain nearly constant during the capture time t_w , the coherent sum

$$\mathbf{X}_{n} = \sum_{i=1}^{n} \mathbf{X}_{i}$$
(2.9)

is also a Rayleigh phasor, with ensemble mean power given by (2.7). Carrier phases may be random but remain constant during t_w . Achieving coherent addition puts even more emphasis on the necessity to keep the packet duration τ short, and also demands tight control of carrier phase and frequency of packets transmitted from distinct transmitters. Doppler shifts due to the movements of vehicles make this control complicated. Furthermore the phase modulation index needs to be small ($\psi_i(t) << 1$). In this (quasi-static) model, the pdf for P_n^c , given the mean power \overline{P}_n during the capture window, is the exponential distribution

$$f_{p_n}^c(p_n|\bar{p}_n) = \frac{1}{\bar{p}_n} \exp\{-\frac{p_n}{\bar{p}_n}\}.$$
 (2.10)

2.2.2.1 Coherent signals compared with one single interferer

In the coherent case, both the signal and interference power during the packet are assumed to have (comparatively slow) Rayleigh fading characteristics.

In fact, the model of Rayleigh fading for one moving terminal assumes the addition of a large number of plane waves with random amplitudes, phases and angles of departure [39]. This phenomenon is illustrated in figure 2.1. As the distance d the transmitting vehicle moves during t_w , has been restricted to be much smaller than $\lambda/2\pi$, the fase shift $\Delta\theta_{i,j}$ of the j-th wave from transmitter i will be small [11]:

$$\Delta \theta_{i,j} \leq 2\frac{\pi}{\lambda} d \ll 1 radian.$$

Figure 2.4 illustrates the case where these waves are generated by a set of different but coherent transmitters. If none of the vehicles moves more than $\lambda/2\pi$, the fase shift of any of the numerous plane waves from the n different transmitters will be small (much less than one radian). The experienced shift is limited to

$$\Delta \theta_{1,j} \leq 2\frac{\pi}{\lambda} d_{max} \ll 1 \text{ radian},$$

where d the distance the fastest moving vehicle moves. Any max static spreading of carrier frequencies increases the phase shifts between waves from different terminals. This effect is assumed negligible.



Figure 2.4: Multipath signals from two coherent sources.

It appears that the envelope of the resulting joint interference signal of n coherent transmitters remains highly correlated if none of the vehicles moves more than $\lambda/2\pi$ during t. The coherent model, assuming coherent reception of signals, thus may be interpreted as adding extra paths to a multipath scenario with one transmitter, if only the interfering carriers are transmitted with sufficient stability within the sync. window t. This "multi-multipath" model suggests that Doppler shifts need not always be corrected.

2.2.2.2 Pdf of joint mean coherent interference

The pdf of the ensemble mean interference power \overline{P}_n is the n-fold convolution of the pdf $f_{\overline{P}_s}(\overline{p}_s)$ of the individual mean packet power \overline{P}_s as given by (1.14):

$$f_{\overline{p}_{n}}(\overline{p}_{n}) = \left\{ f_{\overline{p}_{s}}(\overline{p}_{n}) \right\}^{*n}$$
 (2.12)

Furthermore, removing the area mean power by integration of the conditional pdf (2.10) analogous to (2.2), the unconditional pdf of the coherent joint interference power becomes

$$f_{P_n}^{c}(p_n) = \int_{0}^{\infty} \frac{1}{\lambda} \exp\left\{-\frac{P_n}{\lambda}\right\} f_{\overline{P}_n}(\lambda) d\lambda , \qquad (2.13)$$

in which (2.12) can be substituted. In general, this equation (2.13) differs from the result (2.8) for incoherent signals [1].

3. LITERATURE ON SPATIAL DISTRIBUTIONS IN A CELLULAR AREA

As noted in section 1.4, in many papers optimum cell structures to carry a given traffic distribution have been proposed. The spatial distribution of traffic <u>inside</u> a cell, although affected by unsuccesful attempts of transmitters to capture the base station, received relatively little attention.

3.1 <u>The critical circle model</u> [3]

Abramson [3] described the capture probability for a packet transmitted at a certain distance from the central receiver in the base station. His model was very simple and straightforward, ignoring all aspects of fading, shadowing and interference addition. He assumed any packet transmitted at a distance p from the central receiver to be lost if at least one other terminal transmits a packet in the same time period from a distance less than ap, with a a system constant. The circle with radius ap will be called the "critical circle" for the test packet. With this model mathematically tractable results were derived. The throughput S(p) of a uniform distribution of offered traffic, $G(\rho)=G_0$, was found to have a Gaussian shape: this will be confirmed by calculations with a more accurate model in this thesis. A uniform throughput distribution $S(\rho)=S_0$ has been synthesised, by finding the corresponding distribution of offered traffic $G(\rho)$ in the event of a perfect-capture receiver (a=1). The shape of the established distribution can be described mathematically as

$$G(\rho) = \frac{S_0}{1 - (\rho^2 / \rho_\sigma^2)} \quad \text{and} \quad \rho_\sigma \stackrel{\Delta}{=} 1 / \sqrt{2\pi S_0}. \quad (3.1)$$

The "Sisyphus distance" ρ_{σ} , a singularity somewhat outside the cell boundary ($\rho_{\sigma} \ge 1$), is a distance beyond which no traffic offered would ever capture the receiver in Abramson's model [3].

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3.2 Traffic distribution in ALOHA networks with fading channels

A perfection of the model, introducing Rayleigh fading and the aspect of interference signal addition, has been presented by Kuperus and Arnbak [35]. The importance of modelling the type of signal addition (coherent or incoherent) has been underlined by Arnbak and Van Blitterswijk [1]. In the latter paper, the throughput arising from traffic offered with the same mean power for all terminals, and the throughput arising from traffic offered with a quasi-uniform spatial distribution over the cell, have been analysed. Verhulst et al. [13] studied the channel capacity by means of characteristic functions of the received power pdf of the dispatched packets.

3.3 The image function approach

To study the relations between spatial distributions of offered and throughput traffic in a cellular area, more powerful mathematical tools are necessary than used in e.g. [1]. In this thesis, the image function approach in [13] is extended and the characteristic functions are interpreted as integral transforms, describing the spatial distribution of the traffic. These three equivalent manners to describe the distribution of the traffic are illustrated in figure 3.1.



Figure 3.1: The spatial distribution, the mean power pdf and its image g(v), form three equivalent manners to specify the distribution of the traffic (to within a multiplicative factor G for the total traffic).

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In chapter 4, the images will be defined and their properties described. In section 4.3, the capture probability will be expressed in terms of image functions. Subsequently, expressions for the traffic throughput of the mobile radio channel will be derived from the appropriate pdf's of the packet power. By using image functions of these pdf's, these expressions can be written in a mathematically more convenient form. For instance, in contrast with [1], summing over the number of interferers will no longer be necessary.

3.4 <u>New methods and their application</u>

To establish a relation between the distribution of the offered and throughput traffic, we will distinguish the analysis and the synthesis problem. An offered traffic distribution $G(\rho)$ can be analysed, giving the throughput distribution. If the offered traffic is known, the statistical properties of the interference are uniquely determined. This gives the capture propability and thus the throughput.

OFFERED TRAFFIC	analysis → → →	THROUGHPUT TRAFFIC
G, G(p)	+ + + synthesis	S, S(ρ)

Figure 3.2: Methods to derive the relation between offered traffic and throughput traffic.

Conversely, the synthesis problem is much harder to solve analytically. We are interested in the offered traffic if the throughput is prescribed. This corresponds to the pratical situation where a certain amount of traffic, S, has to be transferred to the base station. In this case both the offered traffic distribution and the resulting interference have to be found simultaneously from the throughput. For both analysis and synthesis, the prescribed traffic and the traffic to be obtained are shown in figure 3.2. Even in slotted ALOHA (1.3), finding the offered traffic G to synthesise a certain throughput S from S=G $exp\{-G\}$ can only be done numerically. In this thesis, the relation between throughput and offered traffic is more complicated than this exponential function. Furthermore, beside the total traffic, we are also interested in the spatial distribution.

Synthesis might be of interest to control the multiple access channel. The control system can measure the instantaneous power of the received packets, giving the spatial distribution of throughput traffic. A method for this will be given in section 4.1 (see the Taylor expansion (4.42) and figure 3.1). With this throughput distribution, the offered traffic can be synthesised. In this way indications of the saturation of the channel can be derived (or predicted).

The aim of this thesis is to describe a newly developed analysis method. From the capture propability in section 4.3, analysis equations will be derived for incoherent and coherent addition. Examples for specific distributions will be given. General statements on the channel behaviour will be made; more specifically, the behaviour of the mobile ALOHA-channel under high traffic loads will be studied. Methods will be indicated to synthesise the traffic to be offered if the throughput is prescribed. Numerical synthesis results will be obtained for constant throughput per unit area.

The way the analysis equations were originally derived during the preparation of this thesis will be described in appendix C. In the main body of the text, a more elegant and straightforward approach is given.

4. IMAGE FUNCTION EXPRESSION FOR THE CAPTURE PROBABILITY

4.1 Image functions of mean power pdf's

Similar to characteristic functions used by Verhulst et al. [13] to calculate channel capacity, interpretation of these image functions as Laplace transforms proves useful in finding spatial distributions. The advantage of transformation is also observed in [14]. The pdf of the joint interference power is quite easy to find from the pdf of the power of one single transmitter. The problem of reverse transformations is avoided as the actual throughput expressions can be written directly in terms of the image functions. In the last part of this chapter, the receiver capture probability is expressed in terms of image functions.

4.1.1 Laplace transformation

Initially, we will discuss several of the model aspects described in the previous sections by using image functions. First we introduce the Laplace transform pair

$$g(\mathbf{v}) \leftarrow \overset{\mathbf{L}_{\mathbf{I}}}{\overset{\mathbf{I}}{\overset{\mathbf{v}}{\overset{\mathbf{v}}{\mathbf{i}}}}} + f_{\overline{\mathbf{P}}_{\mathbf{S}}}(\overline{\mathbf{p}}_{\mathbf{S}}).$$
 (4.1)

Another notation used is

$$g(\mathbf{v}) \stackrel{\Delta}{=} L_{\mathbf{I}}^{\mathbf{I}} \{ \mathbf{f}_{\mathbf{\overline{P}}}, \mathbf{v} \}, \qquad (4.2)$$

where g(v) is defined as the one-dimensional, one-sided image of the mean power pdf $f_{\overline{P}}$

$$g(\mathbf{v}) \stackrel{\Delta}{=} \int_{0}^{\infty} e^{-\mathbf{v}\mathbf{y}} f_{\overline{P}_{s}}(\mathbf{y}) d\mathbf{y}. \qquad (4.3)$$

The image g(v), together with the multiplicative factor G for the total offered traffic, uniquely describes the spatial distribution of the traffic offered to the channel from the mobile packet transmitters.

The defining integral in (4.3) converges (at least) for $Re(v) \ge 0$. Moreover

$$|g(v)| \leq g(0) = 1 \text{ for } Re(v) \geq 0.$$
 (4.4)

From (4.3) it is also clear that the image and all even derivatives of the image of a pdf of a positive random variable are real, positive, and decreasing functions of their argument v along the positive real axis (v>0), since all odd derivatives are negative and increasing with v (v>0). For k a natural number and v>0:

$$0 < g^{(2k)}(v) < g^{(2k)}(0) \quad v > 0 \quad k \in \mathbb{N}$$

$$g^{(2k+1)}(0) < g^{(2k+1)}(v) < 0 \quad v > 0 \quad k \in \mathbb{N}$$
(4.5)

Furthermore [5,(3.6)], $\lim_{v \to \infty} g(v) = 0$ (4.6)

shows the image g(v) to vanish for real v tending to infinity. More detailed information on the behaviour of Laplace images in the limit $v \rightarrow \infty$ can been found in [5]. A summary of properties of the Laplace transform can be found in appendix A. Furthermore, we refer to [4][5][6][7,(29)].


4.1.2 Characteristic functions

To gain more insight in the image functions, we also refer to the theory of characteristic functions (cf) in statistical mathematics [14][15][16]. The cf is the expectation of $(exp{jvx})$, with j the imaginary unit $\sqrt{-1}$, i.e.,

$$cf(v) \stackrel{\Delta}{=} E(e^{jxv}) \stackrel{\Delta}{=} \int_{min}^{x \max} e^{jxv} f_{\chi}(x) dx. \qquad (4.7)$$

The cf is thus the Fourier transform of the pdf and can also be written as a Laplace transform, namely, in our case

$$cf_{\overline{P}_{s}}(jv) = \int_{0}^{\infty} e^{-vx} f_{\overline{P}_{s}}(x) dx \stackrel{\Delta}{=} L\{f_{\overline{P}_{s}},v\} \stackrel{\Delta}{=} g(v). \quad (4.8)$$

The k-th derivative of g(v) in the point v=0 equals $(-1)^k$ -times the k-th moment μ_t of the original pdf [15, p225]

$$g^{(k)}(0) = \int_{0}^{\infty} (-x)^{k} e^{0} f_{\overline{P}_{s}}(x) dx = (-1)^{k} E(\overline{p}_{s})^{k} = (-1)^{k} \mu_{k}. \quad (4.9)$$

All image functions equal unity for v=0:

$$g(0) = \mu_0 = \int_0^{\infty} f_{\vec{p}_s}(\vec{p}_s) d\vec{p}_s = 1.$$
 (4.10)

The function g(v) can be obtained directly from the spatial distribution of the offered traffic $G(\rho)$ by substituting (1.14) in the definition (4.3) of the image function g(v):

$$G g(v) = \int_{0}^{\infty} 2\pi\rho G(\rho) e^{-v\rho^{-\beta}} d\rho. \qquad (4.11)$$

4.1.3 Examples

Three examples of possible image functions are shown in figure 4.1, for real and positive v. The throughput of the first and second distributions has been studied extensively in [1], while Fronczak [17] obtained analytical and numerical results with the distribution of the third example.

Example 1

A spatial distribution with all mobile terminals transmitting from a circular ring centered on the base station, can be modelled by

$$G(\rho) = \frac{G}{2\pi} \delta(\rho-1)$$
, or, equivalently $G f_{\overline{p}}(\bar{p}_s) = G \delta(\bar{p}_s-1)$. (4.12)

The corresponding image $g_1(v) = e^{-v}$ is found by Laplace transformation of the latter and is exhibited in figure 4.1, curve el. The first derivative g'(v) equals -1 for v=0, corresponding to a mean received signal power of $E(\bar{p}_g) = 1$. The higher order moments are all equal to unity, so the higher order central moments (about the mean μ_1) are all zero, which is in agreement with the fact that a fluctuating behaviour is ruled out by the δ -distribution of mean power.

Example 2

In this example traffic distributed uniformly over the cell is considered. Two distributions are considered. The first, a quasiconstant distribution, yields an image with an simple analytical form, while the second distribution of a truly uniform traffic has a somewhat more complicated form.

Quasi-constant offered traffic

A virtually constant traffic [1] in the area $0 < \rho < 1$ modelled by

$$G(\rho) = \frac{G}{\pi} \exp\{-\frac{\pi}{4}\rho^4\}$$
(4.13)

has, if $\beta=4$, the mean power pdf (see (1.14))

$$f_{\overline{P}_{s}}(p_{s}) = \frac{1}{2} \tilde{P}_{s} \exp\{-\frac{\pi}{4\bar{P}_{s}}\},$$
 (4.14)

which has the transform [7, (29.3.82)]

$$g_2(v) = \exp\{-\sqrt{\pi v}\}.$$
 (4.15)

As can also be seen from figure 4.1, the image $g_2(v)$ has an unbounded derivative g'(0).

$$g_{2}^{i}(0) = \frac{1}{\sqrt{\epsilon}} e^{-\sqrt{\pi\epsilon}} \left|_{\epsilon \neq 0} + \infty \right|_{\epsilon \neq 0}$$
(4.16)

According to (4.9), this indicates that the expectation value μ_1 of the received power is unbounded. The spatial distribution $G(\rho)$ has non-zero values for ρ arbitrarily close to zero. As shown by the attenuation law (1.8), the received power from this area tends to infinity. This phenomenon is responsible for the unbounded moments μ_k . General statements on the rate of increase of moments will be made in section 4.1.4.

Truly-constant offered traffic

Beside this simple form of a quasi-constant distribution, a trulyconstant distribution is of interest. The image of this will now be derived. To avoid unbounded moments we shall assume a mobile station to be at a distance ρ of at least ρ_1 from the base station:

$$G(\rho) = \begin{cases} \frac{G}{\pi} = \frac{G}{\pi(\rho_2^2 - \rho_1^2)} & \text{for } \rho_1 < \rho < \rho_2 \\ 0 & \text{elsewhere} \end{cases}$$
(4.17)

 G_{\bigstar} is introduced for convenience of notation. A constant throughput for $0 < \rho < 1$ can be regarded as the limit for

$$\rho_1 + 0 \text{ and } \rho_2 + 1.$$
 (4.18)

In this limit $G_* \neq G$. The derivative g'(v) can be found from (4.11)

$$G g'(v) = \frac{G_{\star}}{\pi} \int_{\rho_1}^{\rho_2} 2\pi \rho^{1-\beta} \exp\{-v\rho^{-\beta}\} d\rho. \qquad (4.19)$$

In the case $\beta=4$ this becomes

$$G g'(v) = G_* \int_{\rho=\rho_1}^{\rho_2} \exp(-v\rho^{-4}) d\rho^{-2} . \qquad (4.20)$$

Substitution of $v\rho \stackrel{-4\Delta}{=} \lambda^2$ gives

$$G g'(v) = \frac{G_{\star}}{\sqrt{v}} \int_{\rho_1^{-2}/v}^{\rho_2^{-2}/v} e^{-\lambda^2} d\lambda = \frac{\sqrt{\pi}}{\sqrt{v}} \left[\operatorname{erf}\left(\frac{\sqrt{v}}{\rho_2^{-2}}\right) - \operatorname{erf}\left(\frac{\sqrt{v}}{\rho_1^{-2}}\right) \right]$$

using the error function $\operatorname{erf}(z) \stackrel{\Delta}{=} \frac{2}{\sqrt{\pi}} \int_{0}^{z} e^{-t^{2}} dt$, described in

[7,(7.11)] and [8,(8.250)]. The image function can be found by integration and imposing the boundary condition $g(\infty) = 0$, so

$$G g(v) = \lim_{\zeta \to \infty} -\int_{v}^{\zeta} Gg'(\lambda) d\lambda = \lim_{\zeta \to \infty} -\sqrt{\pi} G_{\star} \int_{v}^{\zeta} \frac{\frac{1}{2}}{\sqrt{\lambda}} \left[\operatorname{erf}\left(\frac{\sqrt{\lambda}}{\rho_{1}^{2}}\right) - \operatorname{erf}\left(\frac{\sqrt{\lambda}}{\rho_{2}^{2}}\right) \right] d\lambda$$

Substitution of $\sqrt{\lambda} \stackrel{\Delta}{=} \kappa$ yields

$$G g(v) = \lim_{\zeta \to \infty} -\sqrt{\pi} G \int_{\sqrt{v}}^{\sqrt{\zeta}} \operatorname{erf}(\frac{\kappa}{\rho_1}) - \operatorname{erf}(\frac{\kappa}{\rho_2}) d\kappa, \qquad (4.21)$$

which is given in [8, (5.41)]

$$G g(v) = \frac{\lim_{\zeta \to \infty} \sqrt{\pi} G \left[-\sqrt{\zeta} \operatorname{erf}(\frac{\sqrt{\zeta}}{\rho_2^2}) - \frac{\rho_2^2}{\sqrt{\pi}} e^{-\zeta\rho_2^2} + \sqrt{v} \operatorname{erf}(\frac{\sqrt{v}}{\rho_2^2}) + \frac{\rho_2^2}{\sqrt{\pi}} e^{-v\rho_2^2} + \sqrt{v} \operatorname{erf}(\frac{\sqrt{v}}{\rho_2^2}) + \frac{\rho_1^2}{\sqrt{\pi}} e^{-v\rho_1^2} + \frac{\rho_1^2}{\sqrt{\pi}} e^{-\zeta\rho_1^2} + \sqrt{v} \operatorname{erf}(\frac{\sqrt{v}}{\rho_1^2}) - \frac{\rho_1^2}{\sqrt{\pi}} e^{-v\rho_1^2} \right]$$

Inserting $erf(\infty) = 1$, this yields the image function (4.22)

$$G g(v) = G \left[\sqrt{\pi v} \left\{ erf\left(\frac{\sqrt{v}}{\rho_2^2}\right) - erf\left(\frac{\sqrt{v}}{\rho_1^2}\right) \right\} + \rho_2^2 e^{-v\rho_2^2} - \rho_1^2 e^{-v\rho_1^2} \right].$$

Taking the limit $\rho_1 * 0$, and inserting $\rho_2 = 1$, yields

$$G g(v) = G \left[-\sqrt{\pi v} \operatorname{erfc}(\sqrt{v}) + e^{-v} \right],$$
 (4.23)

where $\operatorname{erfc}(z) \stackrel{\Delta}{=} 1 - \operatorname{erf}(z)$. An unbounded derivative in v=0 cannot be avoided if $\rho_1 = 0$.

Example 3

A third case is the exponential pdf

$$f_{\overline{p}_{s}}(\overline{p}_{s}) = \exp\{-\overline{p}_{s}\}, \qquad (4.24)$$

corresponding to a spatial distribution of the form

$$G(\rho) = \frac{2G}{\pi\rho_6} \exp\{-\rho^{-4}\}, \qquad (4.25)$$

where the traffic is concentrated in a circular belt near the ring with radius $\rho=1$ [17]. The image function

$$g_3(v) = \frac{1}{v+1}$$
 (4.26)

is depicted in figure 4.1 \oplus 3. The k-th derivative in v=0 yields the k-th order moment of the pdf

$$\mu_{k} = (-1)^{k} g^{(k)}(0) = k!. \qquad (4.27)$$

Comparing $g_1(\cdot)$ with $g_3(\cdot)$ in figure 4.1, we note that spreading the distribution of received packet power around a constant μ_1 yields a larger image function (for $\rho > 0$). This agrees with the increase of higher even order moments μ_{2k} . Formal statements on the behaviour of image functions in the event of spreading the power pdf about mean μ_1 are believed to be of interest, but have not been established as the odd moments put obstacles to the derivation.

4.1.4 Bounds on the moments μ_k

The above examples suggest that the moments μ_k of the mean power pdf's may easily become infinite (ex.2) or may increase very rapidly (ex.3: $\mu_k \therefore k!$). The rate of increase of the moments as a function of their order k is a great importance for the convergence of series expansions which will be derived in chapter 6. From (4.11) it follows that any distribution with non-zero traffic $G(\rho) \approx G_0$ for ρ +0, has unbounded moments μ_k , since

$$\mu_{k} = (-1)^{k} g^{(k)}(v) = \int_{0}^{\infty} 2\pi \rho^{1-k\beta} \frac{G(\rho)}{G} d\rho > 2\pi \frac{G_{0}}{G} \int_{0}^{\varepsilon} \rho^{1-k\beta} d\rho, \quad (4.28)$$

where ε is sufficiently small to assume G(ρ) to be constant. This integral diverges for $k \ge 1$ if $\beta \ge 2$, a problem also indicated in [13,(7)].

On the other hand, assuming all traffic to be generated beyond a distance of at least ε , with ε a small number, we can prove the moments to increase no faster than exponentially with k. Taking the k-th derivative of g(v) in (4.11), we find the moments $\mu_{\rm b}$, as

$$\mu_{k} = \int_{\varepsilon}^{\infty} 2\pi \lambda^{1-k\beta} \frac{G(\lambda)}{G} d\lambda. \qquad (4.29)$$

Inserting the inequality $\lambda \geq \varepsilon$, this can be bounded as

$$\mu_{\mathbf{k}} \leq \varepsilon^{-\mathbf{k}\beta} \int_{\varepsilon}^{\infty} 2\pi\lambda \frac{G(\lambda)}{G} d\lambda = \left(\frac{1}{\varepsilon}\right)^{\mathbf{k}\beta}$$
(4.30)

4.1.5 Interpretation of the image function

A second and less abstract interpretation of the image function might be useful for intuitive assessments of results derived later. The integral in (4.11) can be estimated by using the step approximation

$$\exp\{-v\rho^{-\beta}\} \approx \begin{cases} 0 \text{ if } \rho < \beta/v & \text{ i.e. if } v\rho^{-\beta} \text{ is large} \\ 1 \text{ if } \rho > \beta/v & \text{ i.e. if } v\rho^{-\beta} \text{ is small} \end{cases}$$
(4.31)

Thus, equation (4.20) now can be approximated as

$$Gg(\mathbf{v}) \approx \int_{\beta_{\mathbf{v}}\mathbf{v}}^{\infty} 2\pi\rho \ G(\rho) \ d\rho \stackrel{\Delta}{=} G - G_{cr}(\beta_{\mathbf{v}}\mathbf{v}), \qquad (4.32)$$

where we have introduced the critical traffic $G_{cr}(\rho_{\star})$, being the total traffic generated inside a critical circle of radius ρ_{\star} . Thus, the image function g(v) can be approximated by the part of the traffic generated outside the critical circle of radius $\beta_{\star}v$.



Fig.4.2: The factor $\exp\{-vp^{-\beta}\}$ can be interpreted as step function

The factor $\exp\{-v\rho^{-\beta}\}$ depicted in figure 4.2 is an increasing function of ρ for real and positive v. When moving transmitters closer to the base station, g(v) is reduced (if v>0). For real and positive arguments v, it can be concluded that any distribution of traffic within the cell with unity radius (0 < ρ < 1), will yield an image function smaller than $\exp\{-v\}$,

which is the image of the δ -distribution with all transmitters concentrated on the outer cell boundary. This bound is valid for the truly-constant throughput of example 2, which can be seen from (4.23), but not for the quasi-constant distrubution (see (4.15) or figure 4.1•2). In example 3, a very large part of all traffic is generated outside the unity circle, and $g_3(v) \ge \exp\{-v\}$.

If, in addition, one demands all terminals to be at a distance greater than a small number ε from the central receiver, the following bounds are valid:

 $\exp\{-v\varepsilon^{-\beta}\} \leq g(v) \leq \exp\{-v\}$, for any real and positive v. (4.33)

Stronger bounds (e.g. $g(v) \ge exp\{-\mu_1v\}$) probably exist, but have not been found. The inequalities presented in [16, par 13.4] are recommended as starting point for further study.

4.1.6 Image of the mean coherent interference power pdf

While g(v) is the image of the received power pdf of an individual transmitter, we are also interested in the joint interference power distribution. As stated before (in (2.7)), the ensemble mean interference power \overline{P}_n is the sum of n stochastic independent powers \overline{P}_i , so the pdf of \overline{P}_n equals the n-fold convolution of the pdf of \overline{P}_s . Due to the properties of the Laplace transform, the n-th power of g(v) then maps the image of the mean interference power pdf \overline{f}_p_n (see (A.1.3)).

$$g^{n}(u) \leftarrow \overset{L^{1}}{I} \rightarrow \left\{ f_{\overline{P}}(\overline{p}_{n}) \right\}^{*n} = f_{\overline{P}}(\overline{p}_{n}).$$
 (4.34)

In the event of coherent addition, the Laplace transform of the interference power pdf is found by applying the lemma of appendix A (A.2.2) to the pdf of the coherent interference power (2.13).

We find
$$L\{f_{P_n}^c,v\} = \frac{1}{v} \int_{0}^{\infty} \exp\{-\frac{\lambda}{v}\} g^n(\lambda) d\lambda.$$
 (4.35)

4.2 Image of the instantaneous power pdf

4.2.1 Definition and relation with other images

We also introduce an image function $\phi(v)$, which is the Laplace transform of the instantaneous packet power pdf f_P (rather than the transform of the area mean power pdf f_P). As distinct from g(v), $\phi(v)$ thus incorporates the effect of Rayleigh fading.

$$\phi(\mathbf{v}) \stackrel{\Delta}{=} \int_{0}^{\infty} \mathbf{f}_{\mathbf{P}_{s}}(\mathbf{w}) e^{-\mathbf{v}\mathbf{w}} d\mathbf{w} = \int_{0}^{\infty} \int_{0}^{\infty} \mathbf{f}_{\mathbf{P}_{s}}(\mathbf{w} | \mathbf{x}) \mathbf{f}_{\mathbf{P}_{s}}(\mathbf{x}) e^{-\mathbf{v}\mathbf{w}} d\mathbf{x} d\mathbf{w}. \quad (4.36)$$

Here the effects of Rayleigh fading are contained in $f_{P_s}(p_s|\bar{p}_s)$, which gives the conditional pdf of packet power P_s , given an area mean power \bar{P}_s dependant on ρ via the power attenuation law (1.8). More explicitly we insert the exponential distribution (2.1)

$$\phi(\mathbf{v}) = \int_{0}^{\infty} \int_{0}^{\infty} \frac{1}{x} \exp\left\{-\frac{w}{x} - wv\right\} f_{\overline{P}_{S}}(x) dx dw. \qquad (4.37)$$

Analogous to the derivation of (4.35), we find the image of the instantaneous power pdf of a Rayleigh fading signal by applying the lemma of appendix A (A.2.2). Thus the relation between f_{p_s} and f_{p_s} , can be expressed in the Laplace v-domain as

$$\phi(\mathbf{v}) = \frac{1}{\mathbf{v}} \int_{0}^{\infty} \exp\{-\frac{\lambda}{\mathbf{v}}\} g(\lambda) d\lambda. \qquad (4.38)$$

As fading tends to spread out the pdf of received packet power, the function $\phi(v)$ is the image of a smoother pdf than is the case with g(v). In agreement with this, the moments v_k of f_p can be proved to be substantially larger than the moments μ_k of f_p .

After substituting $\lambda/v \stackrel{\Delta}{=} x$ in (4.38), one finds

$$\phi(\mathbf{v}) = \int_{0}^{\infty} g(\mathbf{v}\mathbf{x}) e^{-\mathbf{x}} d\mathbf{x} \quad (\text{if } \mathbf{v} \neq 0). \tag{4.39}$$

The k-th derivative of $\phi(v)$ now becomes

$$\phi^{(k)}(v) = \int_{0}^{\infty} x^{k} e^{-x} g^{(k)}(xv) dx. \qquad (4.40)$$

In the limit v+0 and by applying [8, (3.351.3)], this becomes

$$\phi^{(k)}(0) = g^{(k)}(0) \int_{0}^{\infty} x^{k} e^{-x} dx = k! g^{(k)}(0). \quad (4.41)$$

A formal proof of the existance of the limit is not given as the same result can be obtained by comparing derivatives $g^{(k)}(0)$ obtained from (4.11) and $\phi^{(k)}(0)$ from (4.44). The latter equation will be obtained from the definition (4.36) of $\phi(v)$, written in terms of the spatial distribution of the offered traffic. Equation (4.41) is a trivial result for k=0 and k=1, but shows that higher order moments v_k of the instantaneous power pdf equal k! times the higher order moments μ_k of the mean power pdf. Furthermore, we conclude that $\phi(v)$, which at first glance might appear only "an unfocussed picture" of g(v), uniquely specifies all moments of the mean power pdf. Moreover, as seen via a Taylor expansion of g(v), $\phi(v)$ also uniquely specifies the spatial distribution $G(\rho)$ except the multiplicative factor of total traffic G. [41,(Th 6.10.1)]:

$$g(v) = \sum_{k=0}^{\infty} \mu_k \frac{(-v)^k}{k!} = \sum_{i=0}^{\infty} \frac{\upsilon_k (-v)^k}{(k!)^2}.$$
 (4.42)

In practice this means that the spatial distribution of the (offered) traffic can uniquely be found from the statistical properties of the power of the individual packets. Rayleigh fading does not destroy the unique correspondance.

The definition of $\phi(v)$ as an integral transform (4.36) can be stated in terms of $G(\rho)$ by inserting (1.14)

$$\phi(\mathbf{v}) = \int_{0}^{\infty} \int_{0}^{\infty} 2\pi \lambda^{\beta+1} \exp\{-(\lambda^{\beta}+\mathbf{v})\mathbf{w}\} \frac{G(\lambda)}{G} d\lambda d\mathbf{w}.$$
(4.43)

Interchanging the order of integration, yields

$$\phi(\mathbf{v}) = \int_{0}^{\infty} \frac{2\pi\lambda^{\beta+1}}{\lambda^{\beta} + \mathbf{v}} \frac{G(\lambda)}{G} d\lambda. \qquad (4.44)$$

Many of the properties of g(v) are valid also for $\phi(v)$, e.g.

$$\phi(0) = 1$$
 and $\phi'(v) < 0$ for v real and positive. (4.45)

Example 4

As an example, we give the image $\phi_1(v)$ of the δ -distribution in example 1. Applying the sampling property to (4.44) yields

$$\phi_1(v) = \frac{1}{1+v},$$
 (4.46)

which happens to be equal to $g_3(v)$ of example 3 in section 4.1.3. Thus Rayleigh fading appears to spread the power pdf in the same way as the spatial spreading of example 3.

4.2.2 Images of instantaneous interference power pdf's

The addition (2.7) of stochastic independent powers gives the pdf of the incoherent joint interference power P_n^i (during each slot), as the n-fold convolution (2.8) of the instantaneous signal power pdf f_p . After Laplace transformation of f_p this convolution s corresponds to the n-th power of the image function $\phi(v)$.

$$\phi^{n}(\mathbf{v}) = L_{\mathbf{I}}^{\mathbf{I}} \left(\left\{ f_{\mathbf{P}_{\mathbf{S}}}(\mathbf{w}) \right\}^{*n} \right) = L_{\mathbf{I}}^{\mathbf{I}} \left\{ f_{\mathbf{P}_{\mathbf{n}}}^{i}(\mathbf{w}) \right\} \stackrel{\Delta}{=} \int_{0}^{\infty} f_{\mathbf{P}_{\mathbf{n}}}^{i}(\mathbf{w}) e^{-\mathbf{v}\mathbf{w}} d\mathbf{w} \qquad (4.47)$$

The image $\phi^n(v)$ will prove very useful for the model corresponding to incoherent addition of interferers.

4.3 Capture probability and spatial distribution

Corresponding to [1] we introduce the conditional probability of loss for a packet, given the presence of n other packets:

$$\mathbf{F} \stackrel{\Delta}{=} \operatorname{Prob}\{\operatorname{loss}|n, Z_n\}.$$
(4.48)
z,n

Furthermore, the conditional probability of loss for a packet transmitted from a normalised distance ρ , in the presence of n other packets is defined as

$$I_{z,n}(\rho) \stackrel{\Delta}{=} \Pr{ob\{loss | n, Z_n, \rho\}}.$$
(4.49)

To derive expressions for F and I (ρ) , we define the stochastic variables [1, (15) to (20)]

$$z \stackrel{\Delta}{=} \frac{p_s}{p_n}, \quad 0 \leq z < \infty$$
 (4.50)

and $\mathbf{w} \stackrel{\Delta}{=} \mathbf{p}_n, \quad 0 \leq \mathbf{w} < \infty$ (4.51)

We may write the two-dimensional pdf

$$f_{z,w}(z,w) = f_{P_s,P_n}(p_s,p_n) \left| \frac{\partial(p_s,p_n)}{\partial(z,w)} \right|$$
(4.52)

By virtue of the stochastic independence of P_s and P_n , this becomes for a given type of interference addition (index a)

$$f_{z,w}(z,w) = f_{P_s}(zw) f_{P_n}^a(w) w,$$
 (4.53)

from which the pdf for z

$$f_{z}(z) = \int_{0}^{\infty} f_{P_{s}}(zw) f_{P_{n}}^{a}(w) wdw$$
 (4.54)

and the corresponding distribution function

$$F_{z}(Z) = \int_{0}^{Z} dz \int_{0}^{\infty} f_{P_{s}}(zw) f_{p_{n}}^{a}(w) wdw \qquad (4.55)$$

can be calculated.

Distribution (4.55) gives the probability of satisfying the loss condition of (1.4). The choice of $f_{p,n}^{a}(p_{n})$ is determined by the type of addition (index a) assumed for the interfering signals. The alternatives considered here are (2.8) for incoherent and (2.13) for coherent addition. The pdf $f_{p,s}$ can be replaced by a suitable conditional pdf if constraints are imposed on the test packet.

4.3.1 Capture probability

For the probability of packet loss (4.48), we maintain the unconditional f_p

$$F_{z,n} = \int_{0}^{Z} dz \int_{0}^{\infty} f_{P_{s}}(zw) f_{P_{n}}^{a}(w) wdw$$
(4.56)

Although the equation could be written in the form of a convolution after Mellin transformation (Appendix C) from Z_n to the image domain, Laplace transformation yields a more useful result. In Appendix C it will be shown that in the coherent case, probability (4.56) can be written in terms of the image function g(v), namely, as (C.14)

$$F_{z,n} = 1 + \int_{0}^{\infty} g^{n}(Z_{n}\lambda) g'(\lambda) d\lambda. \qquad (4.57)$$

This probability is less than unity as the derivative g'(v), and hence the integral, is negative (see (4.5)).

4.3.2 Capture probability conditioned on distance ρ

To obtain a similar expression for the conditional probability of loss $I_{z,n}(\rho)$ we consider a test packet transmitted from the normalised distance ρ , so the pdf of the mean packet power is the δ -distribution

$$f_{\overline{P}_{s}}^{\text{test}}(\overline{p}_{s}|\rho) = \delta(\overline{p}_{s} - \rho^{-\beta}). \qquad (4.58)$$

Introducing Rayleigh fading (2.2), we find the instantaneous packet power pdf to be

$$f_{P_{s}}^{\text{test}}(p_{s}|\rho) = \int_{0}^{\infty} \frac{1}{p_{s}} \exp\{\frac{-p_{s}}{p_{s}}\} \delta(\bar{p}_{s}-\rho^{-\beta}) d\bar{p}_{s} = \rho^{\beta} \exp\{-\rho^{\beta}p_{s}\}. \quad (4.59)$$

Inserting this in distribution (4.55) gives

$$I_{z,n}(\rho) = \int_{0}^{Z} dz \int_{0}^{\infty} f_{p}^{\text{test}}(zw|\rho) f_{p}^{a}(w) w dw, \qquad (4.60)$$

or
$$I_{z,n}(\rho) = \int_{0}^{2^{n}} dz \int_{0}^{\infty} \rho^{\beta} exp\{-zw\rho^{\beta}\} f_{P_{n}}^{a}(w) wdw.$$
 (4.61)

Integration over Z_n yields

$$I_{z,n}(\rho) = \int_{0}^{\infty} \left[1 - \exp\{-Z_{n}w\rho^{\beta}\}\right] f_{P_{n}}^{a}(w) \, dw. \qquad (4.62)$$

We divide this into two integrals. The first, being a pdf integrated over its domain, equals unity, the second equals the Laplace transform of the pdf in the image point $v=Z_p \rho^{\beta}$.

Thus,
$$I_{z,n}(\rho) = 1 - L \{f_p^a, v = 2_n \rho^\beta\},$$
 (4.63)

in which either the interference image (4.47) or (4.35) should be inserted, depending on whether the interference adds incoherently or coherently.

Rayleigh fading of the test packet signal is incorporated in (4.63), while the fading of the interference signals is incorporated in (4.47) and (4.35). The Poisson character of the traffic will be introduced later. The probability (4.63) thus applies generally for any statistical behaviour of the traffic. It can for instance also be used to analyse slow-frequency hopping CDMA [13].

Example 5

Assume a test packet transmitted from a normalised distance ρ , and one contender transmitting a packet in the same time slot from a

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normalised distance ρ_i . Both experience uncorrelated Rayleigh fading. The image function $\phi_i(v)$ of the received interference power is

$$\phi_{i}(v) = \frac{\rho_{i}^{p}}{v + \rho_{i}^{\beta}}.$$
(4.64)

Using (4.63), the probability of loss of the test packet becomes

$$I_{z,n}(\rho_{s}) = \frac{Z_{1} \rho_{s}^{\beta}}{Z_{1} \rho_{s}^{\beta} + \rho_{1}^{\beta}},$$
 (4.65)

which is in agreement with a result by Diakoku and Ohdate [25,p219].

4.3.3 Spatial distribution of traffic throughput

The probability of packet loss can be found by summing the conditional probability of loss $F_{z,n}$ over the number of interferers n, weighted by the probability of n contenders in the same time slot [1]. Considering Poisson distributed traffic [43], the probability of being able to capture the receiver in an arbitrary time slot is, using (1.1),

$$P_{\text{capt}} = 1 - \sum_{n=1}^{\infty} R_n F_{z,n},$$
 (4.66)

The total traffic throughput S is [1]

$$S = G P_{capt} = G \left[1 - \sum_{n=1}^{\infty} R_n F_{z,n} \right].$$
 (4.67)

The channel throughput $S(\rho)$ for the packets transmitted from a distance ρ can be written similarly as

$$S(\rho) = G(\rho) \left[1 - \sum_{n=1}^{\infty} R_n I_{z,n}(\rho)\right],$$
 (4.68)

The standard slotted-ALOHA case can be found by inserting a receiver threshold which never allows capture for n>0 $(Z_n \leftrightarrow \infty)$, so $F_{z,n} = 1$ and $I_{z,n} = 1$. For finite receiver thresholds, overlaps will not always destroy all n+1 packets involved, so $F_{z,n}$ and $I_{z,n}$ may be less than one.

5 INCOHERENT ADDITION

5.1 Spatial distribution of traffic throughput.

In this chapter an analysis method for incoherent signals will be derived. Main aspects of the "incoherent model" leading to this equation are: the incoherent addition of interfering signals as described in section 2.2.1, uncorrelated fading for all packets and a universal receiver threshold, independent of the number of interferers n.

In the special case of incoherent addition, the interference power pdf needed in the conditional capture probability (4.63) is given by (4.47). The conditional probability of packet loss I $_{z,n}(\rho)$ becomes

$$I_{z,n}(\rho) = 1 - \phi^{n}(Z_{n}\rho^{\beta}).$$
 (5.1)

To find the spatial distribution of the traffic throughput we insert $I_{z,n}(\rho)$ of (5.1) in the throughput equation (4.68)

$$S(\rho) = G(\rho) \left[1 - \sum_{n=1}^{\infty} \frac{G^{n}}{n!} e^{-G} + \sum_{n=1}^{\infty} \frac{G^{n} \phi^{n} (Z_{n} \rho^{\beta}) e^{-G}}{n!} \right].$$
(5.2)

Interesting results can be obtained if we assume the receiver threshold Z_n to be no longer a function of n:

$$Z_{n} \equiv Z_{0} \text{ for all } n.$$
 (5.3)

Packets now capture the receiver if their power exceeds the joint interference power, averaged over t_w , by at least a factor Z_0 . The receiver threshold is assumed to be independent of the statistical behaviour of the interference signal.

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Recommendation 1
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Further study of the characteristics of the receiver threshold Z_n and application of the results in the throughput calculation, is recommended [40].

Series expansion of the exponential function [7,(4.2.1)] applied in (5.2) gives

$$S(\rho) = G(\rho) \exp \{G\phi(Z_0 \rho^\beta) - G\}.$$
(5.4)

Using $\phi(\mathbf{v})$ as given by (4.44) and writing the total traffic G as an integral (1.9) gives

$$S(\rho) = G(\rho) \exp\left\{-\int_{0}^{\infty} \left[1 - \frac{\lambda^{\beta}}{\lambda^{\beta} + Z_{0}\rho^{\beta}}\right] 2\pi\lambda G(\lambda) d\lambda\right\}.$$
(5.5)

This can be written as

$$S(\rho) = G(\rho) \exp\left\{-\int_{0}^{\infty} W_{Z_{0}}\left(\frac{\lambda}{\rho}\right) - 2\pi\lambda G(\lambda) d\lambda\right\}, \qquad (5.6)$$

which we shall call the incoherent analysis equation. We have introduced the weighting function W_{Z} ($0 \le W_{Z} \le 1$)

$$W_{Z_0}(\frac{\lambda}{\rho}) \stackrel{\Delta}{=} \frac{Z_0 \rho^{\beta}}{\lambda^{\beta} + Z_0 \rho^{\beta}} = \frac{Z_0}{(\frac{\lambda}{\rho})^{\beta} + Z_0}.$$
 (5.7)

 W_1 is shown in figure 5.1. Various values of Z_0 correspond to scaling the argument of the weighting function. It is believed that the throughput for other propagation models can also be described by (5.6), but with a distinct weighting function. The incoherent analysis equation (5.6) is very useful for evaluating the spatial traffic distribution, and several examples will be treated later in this chapter. First, we give an interpretation of this result by distinguishing two different roles of the offered traffic G(ρ) in (5.6). This approach is also used in [2] and [3]. Assume the (partial) traffic

$$S_{p} = G_{p} \exp\{-G_{int}\},$$
 (5.8)

with G the (part of the) traffic being candidate to capture the receiver and contribute to S, while G_{int} is the traffic causing harmful interference.

The probability of being able to capture the receiver thus equals $\exp\{-G_{int}\}$. We see in the analysis equation (5.6) that the G_{int} equals the offered traffic weighted by W_Z and integrated over the total area.

5.2 <u>The critical circle model [3]</u>

An approximation of G_{i} can be made by replacing the soft weighting function by a step function:

$$W_{Z_0}\left(\frac{\lambda}{\rho}\right) \approx \begin{cases} 1 \text{ for } Z_0 \rho^\beta > \lambda^\beta \\ 0 \text{ for } Z_0 \rho^\beta < \lambda^\beta \end{cases}.$$
(5.10)

 $W_1(\frac{\lambda}{\rho})$ is shown in figure 5.1.



Figure 5.1: Weighting function in the incoherent analysis equation

We now find the simple throughput relation

$$S(\rho) = G(\rho) \exp \left\{ -\int_{0}^{a\rho} 2\pi x G(x) dx \right\}, \text{ with } a \stackrel{\Delta}{=} \frac{\beta}{2} \sigma, \quad (5.11)$$

which will be called the critical circle analysis equation. This result has been derived by Abramson in [3]. A factor 4 in his formula [3,(36)] is due to his consideration of unslotted ALOHA. His model assumes that a test packet transmitted at a distance ρ can capture the receiver if no other packet is generated inside a critical circle of radius ap (see fig. 5.2), whereas the competition from one or more packet signals generated outside the circle is not taken into account.

Extra interference, due to active terminals outside the critical circle, introduces an influence of the traffic G(x) outside the circle (ap < $x < \infty$).

Accordingly, the integral in our model (5.6) has its upper limit at infinity, and Rayleigh fading changes the critical circle adopted by Abramson into the softer transition region described by $W_Z(\frac{\lambda}{\rho})$ in the incoherent analysis equation (5.6).

5.2.1 The critical circle model applied to perfect capture

As a special case of the critical surface model, we consider the perfect-capture receiver with $Z_0=1$, and thus a=1. Using integration (1.10) with (5.6), the total throughput S becomes

$$S = \int_{0}^{\infty} 2\pi\rho \ G(\rho) \ \exp\{-\int_{0}^{\rho} 2\pi x \ G(x) \ dx\} \ d\rho.$$
 (5.12)

A solution for the integrals can be found immediately if we introduce the distribution function

$$F(\rho) \stackrel{\Delta}{=} \int_{0}^{\rho} 2\pi \lambda G(\lambda) d\lambda, \qquad (5.13)$$

with F(0) = 0 and $F(\infty) = G$. We find

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$$S = \int_{\rho=0}^{\infty} F'(\rho) \exp\{-F(\rho)\} d\rho = -\exp\{-F(\rho)\} \Big|_{\rho=0}^{\infty} = 1 - e^{-G}$$
(5.14)

In the event of unslotted ALOHA, using Abramson's version [3,(36)] of the analysis equation, one finds a corresponding

$$S = \frac{1}{2} - \frac{1}{2} \exp\{-2G\}.$$
 (5.15)

According to equations (5.14) and (1.1), the perfect-capture receiver accepts on average one packet in every slot occupied by at least one packet. The packet selected will, with the critical circle model, be the one transmitted from the terminal nearest to the base station, as there is no contender in its critical region. From this simple consideration we can conclude that the restriction "on average" may here be replaced by "exactly". In the limit $G \rightarrow \infty$, we find S_{∞} =1 for slotted ALOHA, and S_{∞} = $\frac{1}{2}$ for unslotted ALOHA. Abramson [3] has given two particular examples of the latter limit. For receiver thresholds near or below $Z_0=1$, the traffic loads may become relatively heavy before throughput losses due to collisions start to play an important role. In this event the possibility of more than one contender in the same slot will be relatively high and addition of interfering signals can no longer be neglected.

The critical circle model is then believed to yield too optimistic throughputs. As a striking example it will be shown that for perfect capture ($Z_0=1$), S_{∞} must equal zero (and not unity) for most realistic spatial distributions.



Figure 5.2: The critical circle for a test packet transmitted by the mobile station MS has the radius ap.

On the other hand, for high receiver thresholds (Z₀>4), the fading modelled in this thesis will significantly increase throughput while the critical circle model is believed to yield too pessimistic results. This will be confirmed in the examples of synthesis in section 5.11.

5.2.2 Spatial distribution near the cell boundary

From the critical circle model, one can draw a qualitative conclusion on the behaviour of the traffic distribution near the boundary (ρ +1) of the cell if non-perfect capture (Z_0 >1) is assumed:

For non-perfect capture receiver thresholds $(Z_0 > 1)$ and for large ρ ($\rho \neq 1$), the capture probability becomes independent of the distance at which the test packet is transmitted, and the analysis equation may be approximated with

$$S(\rho) = G(\rho) \exp\{-G\}$$
. (5.16)

This means that the spatial distribution of the throughput traffic has the same shape as the offered traffic, but is reduced by the loss factor $\exp\{-G\}$ for standard ALOHA, where all packets experiencing overlaps are lost. The main reason for this is the cellular approach in this thesis. No traffic is generated outside the unit circle. For $\rho > 1/a$, the integral in the critical circle analysis equation (5.11) is taken over the entire cell surface, and equals the total offered traffic G found from (1.9). For test packets generated in this area, any interfering packet has a power P_{int} high enough to satisfy the loss condition (1.4):

$$P_{\text{test}} < a^{\beta}P_{\text{int}}$$
, since $P_{\text{test}} = \rho^{-\beta} < a^{\beta}$ and $P_{\text{int}} \ge 1$ (5.17)

With the incoherent model, the above inequality is valid as far as area mean powers are concerned. Rayleigh fading will make this effect less pronounced.

The effect described by (5.16) will be confirmed by examples of synthesis in section 5.11 using the critical circle model. Appropriate examples using the incoherent model will be given in sections 5.9 and 5.11.

We now consider several examples of spatial traffic distributions.

5.3 <u>The ring model</u> [1] [13].

In this example we assume all terminals to be located on the circular ring with radius $\rho=1$. Thus, the packets are received with the same mean power.

$$G(\rho) = \frac{G}{2\pi} \delta(\rho - 1) \qquad (5.18)$$

The sampling property of the δ -function applied in the analysis equation (5.6) gives

$$S(\rho) = G(\rho) \exp\{-G(\frac{Z_0}{Z_0+1})\}$$
 (5.19)

and so, by using integrations (1.9) and (1.10) for total traffic,

S = G
$$\exp\{-G(\frac{Z_0}{Z_0+1})\}$$
. (5.20)

The extremum of this throughput curve is found for

G=
$$\frac{Z_0+1}{Z_0}$$
 and S= $\frac{Z_0+1}{Z_0}$ $\frac{1}{e}$, (5.21)

which equals 2/e (0.76) in case of perfect capture ($Z_0 = 1$). Thus, if packet signals add incoherently, the effect of fading simply gives an increase of channel capacity in slotted ALOHA by a

factor of $\frac{Z_0+1}{Z_0}$.

This result has been derived by Verhulst et al. in [13]. Equations (5.19) and (5.20) also describe the throughput if an adaptive power control mechanism compensates for the path loss and shadowing, but not for Rayleigh fading.

The total traffic throughput S tends to zero for G increasing. We shall see in chapter 6 that in the coherent case, a spatial ringdistribution of the traffic leads to non-zero throughput if G increases without limit.

5.4 Homogeneous offered traffic

In this example we drop the idea of a cellular structure and assume a traffic which is constant with distance.

$$G(\rho) = \frac{G_0}{\pi}$$
 for any $\rho > 0$. (5.22)

The traffic offered within the unit circle (0 < ρ < 1) is G₀. The total traffic G (found from (1.9)) is unbounded.

The traffic throughput can be found from the incoherent analysis equation (5.6)

$$S(\rho) = \frac{G_0}{\pi} \exp\{-2G_0 \int_0^\infty \frac{Z_0 \rho^{\beta} x}{x^{\beta} + Z_0 \rho^{\beta}} dx\}.$$
 (5.23)

The Gaussian shape of this spatial distribution, which has been shown by Abramson [3,(42)], appears after substitution of $x \stackrel{\Delta}{=} t\rho \ Z_0^{-1/\beta}$.

$$S(\rho) = \frac{G_0}{\pi} \exp\{-2G_0 Z_0^{2/\beta} \rho^2 \int_0^{\infty} \frac{t \, dt}{t^{\beta} + 1}\}$$
(5.24)

The integral is solved in [8, (3.241.2)]

$$S(\rho) = \frac{G_0}{\pi} \exp\left\{-\frac{2}{\beta}\pi Z_0^{2/\beta} G_0 \rho^2 \operatorname{cosec} 2\frac{\pi}{\beta}\right\}$$
(5.25)

In the event of the propagation law $\beta=4$ we find

$$S(\rho) = \frac{G_0}{\pi} \exp\{-\frac{\pi}{2}G_0 \sqrt{Z_0} \rho^2\}, \qquad (5.26)$$

which is depicted in figure 5.3 for different traffic loads G_0 .



Although the total offered traffic G is unbounded for any G_0 , the total traffic throughput does not tend to zero by collision effects.

$$S_{\infty} = \int_{0}^{\infty} 2\pi\rho S(\rho) d\rho = \frac{2}{\pi\sqrt{2}_{0}} \approx \frac{0.64}{\sqrt{2}_{0}}$$
 for any $G_{0} > 0.$ (5.27)

5.4.1 Throughput for other propagation models

Recommendation 2.1

If a weighting factor $W_Z^*(v)$ exists for other propagation models, the Gaussian shape will now be shown to apply also for these models. The propagation model must at least contain the attenuation law (1.8) for area mean power.

Assuming a constant $G(\rho) = G_0/\pi$, substitution of the integration variable $\lambda \stackrel{\Delta}{=} \nu \rho$ yields

$$S(\rho) = \frac{G_0}{\pi} \exp\{-\rho^2 \frac{G_0}{\pi} \int_0^\infty W_z(v) 2\pi v \, dv\}.$$
 (5.28)

This clearly demonstrates the Gaussian shape of the throughput distribution. Convergence of the integral can be studied from

The integral converges for ε +0 as the weighting function is less than unity, while the convergence for large η is guaranteed if the weighting function decreases more rapidly than inversely proportiional with the square of its argument v.

Derivation of the throughput for Rician fading and/or shadowing is recommended.

5.4.2 Success rate

In a well-functioning multiple access system, one may demand the average probability of capture within a range of transmitter distances ($0 < \rho < 1$), to be larger than a minimum value q. The parameter q ($0 \le q \le 1$) is called the "minimum succes rate". In the event of homogeneous offered traffic,

$$P\{succes|\rho\} = \frac{S(\rho)}{G(\rho)} = exp\{-\frac{\pi}{2} G_0 / Z_0 \rho^2\} \ge q.$$
 (5.30)

So, to meet the specification, the total offered traffic G_0 inside the cell with unity radius must be bounded by

$$G_0 < -\frac{2}{\pi} \frac{\ln q}{\sqrt{Z_0}} = G_{0, \max}.$$
 (5.31)

This is depicted in figure 5.4, where the maximum permitted traffic G_0 is given as a function of the minimum succes rate q, with receiver threshold Z_0 as a parameter.



Figure 5.4: The maximum traffic load $G_{0,\max}$ inside the unit circle expressed in packets per slot as a function of the minimum succes rate q.

Traffic generated outside the unit circle does not necessarily meet the minimum succes-rate specification. In a practical situation this extra-cellular traffic can represent interference from other cells.

5.5 Behaviour under heavy traffic loads.

Throughput equation (5.27) states that S_{∞} remains finite even for $G_0 \rightarrow \infty$. However, a weak point in the physical modelling of the previous example is the convenient mathematical assumption that packets can be transmitted from distances arbitrarily close to the base station, and thus, according to the attenuation law of (1.8), are received with arbitrarily high mean power \overline{P}_{α} .

We assume the results (5.25), (5.27) and (5.31) valid if the amount of traffic G_{ϵ} contributed by terminals located very close ($\rho < \epsilon <<$ 1) to the receiver is relatively small, i.e., if

$$G_{\epsilon} \ll S.$$
 (5.32)

In this case the influence of G_{ϵ} to both candidate traffic G_{p} and interfering traffic G_{int} in (5.8) is negligible. To satisfy this condition in the example of uniform offered traffic, the maximum traffic load has to be bounded by

$$\pi \frac{\varepsilon^2}{\pi} G_0 << \frac{0.64}{\sqrt{Z_0}}.$$
 (5.33)

Inserting typical values $Z_0=10$ and $\varepsilon=0.01$, the traffic G offered inside the unity circle can be increased to more than one thousand packets per slot before (5.33) is violated. If (5.33) is satisfied, we may conclude that packets need not have unlimited power to capture the receiver. Two possible models to cope with the case that the offered traffic exceeds this bound are either ¹) to keep the <u>received</u> mean power constant with distance for transmitters close to the base station ($\rho < \varepsilon_1$, ε_1 small but constant), or ²) to prevent terminals from being closer than a minimum distance ε_2 to the receiving base station.

Ad ¹) This model, suggested in [13], can be regarded as a further elaboration of the propagation power law of (1.8), but the unique correspondance between G(p) and Gg(v) must then be dropped.

In terms of a traffic distribution we can model this with the spatial distribution

$$G(\rho) = \varepsilon_1^2 G_0 \delta(\rho - \varepsilon_1) + \frac{G_0}{\pi} U(\rho - \varepsilon_1), \qquad (5.34)$$

with U(.) the unit step function.

In contrast to the previous result (5.27), the throughput now has the behaviour of a ring model with the traffic on the ring increasing without limit $(\epsilon_1^2 G_0 + \infty)$. As shown in (5.19) this has zero throughput S_{∞} . Additional interference by the traffic $G_0 U(\rho - \epsilon_1)$ can only decrease the capture probability. Consequently, the throughput of packets from the ring and further away tends to zero. The channel has zero throughput if $G_0 + \infty$.

Ad ²) Under this realistic assumption we do not allow mobile stations "to climb up the base station tower". The spatial distribution of offered traffic is simply

$$G(\rho) = \frac{G}{\pi} U(\rho - \varepsilon_2). \qquad (5.35)$$

In a small-cell network with a cell radius r = 5 km and an antenna height H = 50 meter, ε_2 will indeed be in the order of 0.01.

In the discrete Markov-chain model presented by Namislo, the limit S_{∞} greater than zero is no longer achievable if the received power is bounded [24,p588]. With the above model we find a similar result which states that the throughput limit S_{∞} has to be zero. However, it is believed that the offered traffic G has to be raised to extreme values before the channel is completely destroyed by mutual collisions.

5.6 Traffic distributed in a circular band

In this example we deal with spatial distributions constrained by the condition that all traffic is concentrated in a circular band. Thus, the offered traffic per unit area G(ρ) is zero for $\rho < \rho_1$ and $\rho > \rho_2$. The contributing cell now has inner and outer boundaries ρ_1 and ρ_2 . In this case, the total traffic throughput S theoretically tends to zero, if the total offered traffic increases without limit. This can be concluded from the observation that

$$S \leq G \exp\{\frac{-Z_0 G}{\alpha^{\beta} + Z_0}\}, \quad \text{with } \alpha \stackrel{\Delta}{=} \frac{\rho_2}{\rho_1}.$$
 (5.36)

We prove this result by inserting the analysis equation (5.6) in the integral (1.10) and bounding the resulting S. The integral

$$S = \int_{\rho_1}^{\rho_2} 2\pi\rho \ G(\rho) \ \exp\left\{-\int_{\rho_1}^{\rho_2} W_{Z_0}\left(\frac{\lambda}{\rho}\right) \ 2\pi\lambda \ G(\lambda) \ d\lambda\right\} \ d\rho \quad (5.37)$$

can be overbounded by inserting the most favourable value in the weighting function W_{γ} . By doing so, one finds

$$S \leq G \exp\{-W_{Z_0}(\frac{\rho_2}{\rho_1}) G\} = G \exp\{\frac{-Z_0}{\alpha^{\beta}+Z_0} G\}.$$
 (5.38)

This result can be understood by the (physically unrealistic) insertion in the analysis equation (5.6), interpreted as (5.8), of the traffic G_p as if it were concentrated at ρ_1 (strong candidates), and the traffic in G_{int} as if it were concentrated at ρ_2 (weak interference). Stronger bounds appear to be possible, but the desired conclusion can be drawn from this result.

An implication of the bound (5.36) is that achieving a non-zero throughput limit S_{∞} will be possible only by assuming ρ_1 to be zero or by assuming ρ_2 to tend to infinity. The former can lead to infinitely strong received packet signals, while the latter allows the ineffective traffic by terminals far outside the cell to be unbounded without catastrophic results for the traffic closer by.

However, with typical cellular distributions ($\rho_1 = \epsilon \sim 0.01$ and $\rho_2 = 1$), the bound (5.36) becomes

$$S \leq G \exp\{-10^{-8}Z_0G\},$$
 (5.39)

so it no longer is a practical problem, even for high G.

This is in agreement with observations by Namislo [24], who stated that the mobile slotted ALOHA radio network will remain very stable under overload: only for very large numbers of contenders the throughput will eventually tend to zero ("graceful degradation"). This is in sharp contrast to the situation in pure slotted ALOHA.

Recommendation 3

Formal statements on the throughput behaviour under large traffic loads might be obtained by inserting the intermediate result (5.4) in the integral for total throughput traffic (1.10) and applying the asymptotic expansion for Laplace integrals [38].

5.7 Offered traffic distributed homogeneously in a circular band

In this example we assume an offered traffic distributed uniformly with intensity G_0 per unit area between radii ρ_1 and ρ_2 .

$$G(\rho) = \begin{cases} \frac{G}{\pi \left(\rho^2 - \rho^2\right)} \stackrel{\Delta}{=} \frac{G}{\pi} * (\rho_1 < \rho < \rho_2) \\ 0 & \text{elsewhere} \end{cases}$$
(5.40)

The parameter G_{\star} is introduced for convenience of notation. The traffic throughput now becomes

$$S(\rho) = \frac{G_{\star}}{\pi} \exp\{-G_{\star} \int_{\lambda=\rho_{1}}^{\rho_{2}} \frac{Z_{0}\rho^{4} d\lambda^{2}}{\lambda^{4} + Z_{0}\rho^{4}}\}.$$
 (5.41)

After solving the integral and using [8,(1.625.9)] to substract both arctan terms, we find

$$S(\rho) = \frac{G_{\star}}{\pi} \exp\{-\sqrt{Z_0} \ \rho^2 \ G_{\star} \ \arctan\{\frac{\sqrt{Z_0} \ \rho^2(\rho_2^2 - \rho_1^2)}{\sqrt{Z_0}\rho^4 + \rho_1^2 \ \rho_2^2}\}\}.$$
(5.42)

Inserting ρ_2 =1 and taking the limit ρ_1 +0 (thus G=G_{*}), the throughput distribution from a homogeneous offered traffic within the cell is found on the form

$$S(\rho) = \frac{G}{\pi} \exp\{-\sqrt{Z_0} \rho^2 G \arctan(\frac{1}{\rho^2})\}.$$
 (5.43)

For a minimum succes rate q, the total traffic G offered in the unity cell must be bounded by

$$G < \frac{-4}{\pi} \frac{\ln q}{\sqrt{2}_0}$$
, (5.44)

which is twice the maximum allowed traffic in the event of uniform spatial distribution (with infinite extension (5.27)).

5.8 Offered traffic increasing linearly with distance

We next assume unbounded traffic with the spatial distribution

$$G(\rho) = \frac{3}{2\pi} \rho G_0$$
, for any $\rho > 0$. (5.45)

The traffic transmitted from inside the unit circle is G_0 . Assuming $\beta=4$, we find a traffic throughput of

$$S(\rho) = \frac{3}{2\pi} \rho G_0 \exp\{-3G_0 \int_0^\infty \frac{Z_0 \rho^4 \lambda^2}{\lambda^4 + Z_0 \rho^4} d\lambda\}.$$
 (5.46)

We substitute $\lambda \stackrel{\Delta}{=} t \rho \quad 4 \sqrt{Z_0}$. The integral is [8, (3.241.2)]

$$S(\rho) = \frac{3}{2\pi} \rho G_0 \exp\{-\frac{3}{4\pi} G_0 Z_0^{3/4} \rho^3 \operatorname{cosec} \frac{3}{4\pi}\}.$$
 (5.47)

The total traffic throughput S now equals, using (1.10),

$$S_{\infty} = \int_{0}^{\infty} G_{0} \exp\{-\frac{3}{4}\pi G_{0} \rho^{3} Z_{0}^{3/4} \operatorname{cosec} \frac{3\pi}{4}\} d\rho^{3}$$
(5.48)

$$= \frac{2\sqrt{2}}{3\pi} \quad Z_0^{-3/4} \approx 0.300 \ Z_0^{-3/4} \text{ for any } G_0 > 0. \quad (5.49)$$

A perfect-capture receiver will be captured by an average of about 0.300 packets per timeslot, independent of the intensity of traffic. We have thus obtained a constant throughput, independent of the offered traffic per unit area (the dependence on the total traffic G is indefinite as G is infinite for any $G_0>0$).

In the above result, only a fraction S , with

$$S_{\varepsilon} \stackrel{\Delta}{=} \int_{0}^{\varepsilon} 2\pi\rho S(\rho) d\rho < \int_{0}^{\varepsilon} 2\pi\rho G(\rho)d\rho = \varepsilon^{2} G_{0}, \quad (5.50)$$

is contributed by traffic offered inside a small circle of radius ε . This traffic is received with unacceptable high packet power. We may assume the result valid if S_c << S, i.e. for

$$G_0 \ll \frac{0.300}{\epsilon^2} z_0^{-3/4},$$
 (5.51)

which will normally be the case in practical situations.

5.9 Offered traffic increasing quadraticly with distance

$$G(\rho) = \begin{cases} \rho^2 \frac{2}{\pi} G & \text{for } \rho < 1 \\ 0 & \text{for } \rho > 1 \end{cases}$$
(5.52)

The throughput distribution becomes

$$S(\rho) = \frac{2}{\pi} \rho^{2} G \exp\{-G Z_{0} \rho^{4} \int_{0}^{1} \frac{4x^{3}}{x^{4} + Z_{0} \rho^{4}} dx\}$$
(5.53)
$$= \frac{2}{\pi} \rho^{2} G \exp\{-G Z_{0} \rho^{4} \ln\left[\frac{1 + Z_{0} \rho^{4}}{Z_{0} \rho^{4}}\right]\}$$
$$= G(\rho) \left[1 + \frac{1}{Z_{0} \rho^{4}}\right]^{-G} Z_{0} \rho^{4}.$$
(5.54)

Examples of this spatial distribution have been computed and are illustrated in the three figures 5.5, 5.6 and 5.7. The independent variable is ρ (0< ρ <1). In the first figure the offered traffic G is fixed at an average of one packet per slot; the channel is below saturation. The spatial distribution of the offered traffic G(ρ) is also given in this figure, as it has the same dimension as S(ρ): packets per slot per unit area. G(ρ) can be interpreted as S(ρ) for the special receiver that is captured by all packets regardless of overlap (Z₀=0). Figure 5.5 shows that the influence of Z_0 (1 < Z_0 < 10) is not very large if the channel is below saturation. This can be noted also in the throughput relation for total traffic, given in figure 5.8.



figure 5.5: Quadratic offered traffic throughput by various Z_0 for G=1.

In the next figure (5.6), $S(\rho)$ is given for a perfect capture receiver ($Z_0=1$), when the total traffic load G is increased in steps (G=1 + 2 + 4 + 10). The quadratic shape of the curves is clear for small ρ , but for larger ρ the effect of loss due to collisions becomes significant. With a total traffic approaching the average of 10 packets per timeslot, the packet throughput from the boundary ($\rho \approx 1$) of the cell tends to zero, even though the traffic offered from this region is very large.



Figure 5.6: Quadratic offered traffic throughput by a $Z_0=1$ receiver with total traffic G as a parameter.



Figure 5.7: Quadratic offered traffic throughput by a $Z_0=4$ receiver with total traffic G as a parameter.

In figure 5.7, the throughput curves are given for a radio receiver with threshold $Z_0=4$ (6dB). For terminals close to the base station

($\rho < 0.2$), the throughput figures do not show much difference from the previous case where $Z_0=1$. For more distant terminals the saturation effect becomes evident far earlier, and the increase with distance of the traffic throughput is weakened. In some cases (G>2), the curve even decreases with distance. For terminals near the boundary of the cell (ρ +1) and for $Z_0=4$, we recognise the saturation effect described by (5.16). The numerical value of the loss factor in (5.54)

$$\left[1 + \frac{1}{Z_{0}\rho}\right]^{-GZ_{0}\rho^{4}} \approx \left(\frac{5}{4}\right)^{-4G} \approx (2.44)^{-G}$$
 (5.55)

approaches the limit of e^{-G} [7,(4.2.21)]. In this region, nearly all packets experiencing overlaps are lost. Thus, for larger G (2 < G < 4), we see another increase with ρ , caused by G(ρ), of the throughput S(ρ). Combining these opposite effects the throughput curve becomes quite constant in the area 0.3 < ρ < 1, especially for a traffic load of G \approx 3 packets per slot.

For higher traffic loads (G>3), the throughput of packets transmitted relatively far from the base station drops quickly due to collisions. Compared with this, the increase of the throughput of packets from terminals close to the central receiver is relatively small.





In this comparison it should be remembered that in the integral for S (1.10), the throughput per unit area $S(\rho)$ is weighted with $\rho d\rho$.

As a result, the total traffic S is believed to tend to zero for G increasing without limit. The total throughput S is depicted in figure 5.8 as a function of the offered traffic G. As previously noted the influence of the receiver threshold Z_0 becomes more significant, when the total traffic G increases towards saturation of the channel.

Recommendation 3.1

The S versus G relation giving the throughput, can be assessed by inserting $S(\rho)$ in (1.10). A numerical value of the limit S has not been found (see recommendation 3 in section 5.6). We find bounds for S using [7, (4.2.36)]

$$Ge^{-G} < S = G_0^{1} \left[1 + \frac{1}{Z_0 \rho^4}\right]^{-GZ_0 \rho^4} d\rho^4 < G_0^{1} \exp\left\{\frac{-GZ_0 y}{Z_0 y + 1}\right\} dy,$$

with $y \stackrel{\Delta}{=} \rho^4$ substituted. It can be shown by using the asymptotic expansion for Laplace integrals [38] that this bound only yields $0 < S_m < 1/Z_0$.

5.10 Synthesis methods

In our analysis so far, the traffic $G(\rho)$ offered to the channel was assumed to be known. From this the traffic throughput could be calculated. In most practical communications environments, however, a certain transfer of data S has to be guaranteed at the receiver. Packets lost in collisions do not contribute to S and have to be retransmitted. Thus we must address the problem of synthesis of a distribution of $G(\rho)$ resulting in a specified $S(\rho)$, taking account of these retransmissions.

5.10.1 Numerical method of increasing sample distance p

In the critical circle model, the special case of uniform throughput has been derived for the perfect-capture receiver in [3]. In this event ($Z_0=1$), the critical circle has a radius equal to the distance ρ_{test} traversed by the test packet, so a method to calculate the offered traffic required to achieve any prescribed throughput $S(\rho)$ can be obtained from (5.8). The competing traffic G is derived by integrating $G(\rho)$ for traffic originating closer to the base station:

$$G_{\text{int}} = \int_{0}^{\rho} 2\pi\lambda \ G(\lambda) \ d\lambda.$$
 (5.56)

As it is illustrated in figure 5.9, from G_{int} and $S(\rho)$, the traffic G_{p} to be offered from the normalised distance ρ_{test} can be found as

$$G(\rho) = S(\rho) \exp \{G_{int}\}$$
(5.57)

This numerical synthesis approach starts near the base station $(\rho=0)$, where G(0) equals S(0). By increasing ρ_{test} step by step, the traffic to be offered can be found for any distance ρ (0< ρ <1).



This method can only be used for $Z_0 \leq 1$: for higher receiver thresholds the required traffic G(ρ) for ρ larger than ρ_{test} has to be known before it can be calculated.

Abramson derived the analytic solution (3.1) for a uniform throughput S₀ and perfect capture $(Z_0=1)$.

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5.10.2 Iterative numerical method

A general explicit solution for $G(\rho)$, given $S(\rho)$, has not been found, neither with the critical circle model nor with the incoherent model. However, the analysis equation (5.6) is amendable to iterative numerical solution, by rewriting it in the form

$$G_{i+1}(\rho) = S(\rho) \exp\{+ \int_{0}^{\infty} W_{Z}(\frac{\lambda}{\rho}) 2\pi\lambda G_{i}(\lambda) d\lambda\}, \qquad (5.58)$$

where $S(\rho)$ is a prescribed (desired) traffic throughput. Using the i-th trial version $G_i(\rho)$, the next (and hopefully better) estimate $G_{i+1}(\rho)$ can be found.

A simple choice of the starting function is taking $G_0(\rho)$ equal to the desired throughput density $S(\rho)$. In general, it can be stated that if the starting function satisfies

$$0 \leq G_0(\rho) \leq G(\rho) \quad \text{for all } \rho, \tag{5.59}$$

then all estimates $G_i(\rho)$ have values between $S(\rho)$ and the solution $G(\rho)$. This can be proved by induction, as follows:

The lower bound is based on the simple recognition that all estimates are greater than $S(\rho)$ for any ρ , as the integrand in (5.58) is non-negative. The upper bound is derived from the induction step that

if $G_i(\rho) \leq G(\rho)$, then $G_{i+1} \leq G(\rho)$, (5.60)

which follows from

$$\begin{split} G_{i+1}(\rho) &= S(\rho) \, \exp\{ \int W_Z(\frac{\lambda}{\rho}) \, 2\pi\lambda \, G_i(\lambda) \, d\lambda \} \\ &\leq S(\rho) \, \exp\{ \int W_Z(\frac{\lambda}{\rho}) \, 2\pi\lambda \, G(\lambda) \, d\lambda \} = G(\rho). \end{split}$$

An immediate consequence of (5.59) is that a bounded solution $G(\rho)$ can not exist if the sequence of estimates $G_i(\rho)$ diverges. However, in practice this observation is of limited value, as it does not consider the numerical (quantisation) problems of digital computing, which may also be the cause of divergent steps.

5.10.2.1 The computer program

A synthesis computer program has been written to find G(ρ), given S(ρ). It has been applied to both the critical circle and the incoherent model. A very appropriate case is uniform traffic throughput: we assume S(ρ) to be constant within the circular cell of normalised radius ρ =1, i.e.

$$S(\rho) = \begin{cases} S_0 = \frac{S}{\pi} & 0 < \rho < 1 \\ 0 & \text{elsewhere} \end{cases}$$
(5.61)

The spatial distributions are sampled in N points (typical values are between 10 and 50). The iteration is terminated when the integrated relative changes ER in the distribution $G(\rho)$ drops below a certain threshold (e.g. $10^{-4} = 0.01\%)$

$$\operatorname{ER}_{i+1} \stackrel{\Delta}{=} \int_{0}^{\infty} \left| \frac{G_{i+1}(\rho) - G_{i}(\rho)}{G_{i}(\rho)} \right| d\rho \quad \langle \text{ THRESHOLD.} \quad (5.62)$$

The maximum number of iterations is limited to M. The total offered traffic G (found from (1.9)) is monitored to indicate possible divergence of the equation. The starting function $G_0(\rho)$ is taken equal to $S(\rho)$. Convergence is quick (ER₁₊₁ << ER₁) as long as the channel is well below saturation: only four or five iterations are needed. With higher traffic loads the convergence becomes slower. Numerical results will be presented in section 5.11.
5.10.2.2 Simulation of the dynamic behaviour of the channel

The rate and the manner of convergence have a very useful practical interpretation. In the standard ALOHA equation $S = G e^{-G}$, we may distinguish two roles of the offered traffic, namely the candidate and the interference role of the traffic variable G, described by equation (5.8). In our iterations:

$$G_{p} \stackrel{\Delta}{=} G_{i+1}(\rho)$$
 and $G_{int} \stackrel{\Delta}{=} \int_{0}^{1} W_{Z}(\frac{\lambda}{\rho}) 2\pi\lambda G_{i}(\lambda) d\lambda$. (5.63)

In a quasi-static description, assume the momentary value at instant i of interference to be G_{int} . To achieve a throughput S_p , a certain number of packets has to be retransmitted resulting in the offered traffic load

$$G_{p} = S_{p} \exp\{-G_{int}\}.$$
 (5.64)

The increased traffic G_n results in more interference

$$G_{int}^{new}(G_p) > G_{int}$$
 (5.65)

and a new estimate G_p^{new} has to be made.

Slow convergence indicates that the retransmissions result in a significant increase in interference, again causing a substantial increase in additional retransmissions. The channel is thus approaching saturation. The iterative computer programme appears to simulate the modelled dynamic behavior of the channel, as a sequence of steps modelled by quasi-static offered traffic estimates G_p . It should be noted that this interpretation is at odds with the assumption of stationary distributions made in section 1.4.2.

5.11 Uniform throughput

The program described in the previous section is contained in appendix B. The offered traffic distributions are depicted in figures 5.10a, 5.11a and 5.12a. Results by the incoherent model are indicated with solid lines, while the results by the critical circle model are marked.

The first figure (5.10) applies for receiver threshold Z_0 =1 (perfect capture). The traffic G(ρ) to be offered according to the incoherent model is given for various throughput intensities S=0.1, 0.2, up to 0.8. The number of retransmissions, and thus G(ρ), increases rapidly for terminals near the boundary of the cell (ρ +1) as soon as the total traffic S exceeds some 0.6 packets per slot (pps). The program then has to execute nine or more iterations before reaching the ER-criterion in (5.62). A total traffic as high as 0.8 pps can be received, but distant terminals must offer a traffic more than four times higher (more than one pps per normalised unit of area, ppspa) than is successfully received (0.8/ π ~ 0.25 ppspa).

Calculations for S=0.9 (and higher) no longer converge and seem near or beyond the channel capacity. The total offered traffic G is given as a function of S in figure 5.10b.

The results are compared with

- the standard slotted ALOHA curve $S=G \exp\{-G\}$
- S= G exp{ $\frac{-Z_0G}{Z_0+1}$ } of section 5.1
- S=1-exp{-G} for a receiver that can be captured on average by one packet per occupied slot,
- the bound S \leq G for any receiver.

Calculations using the critical circle model confirm the analytic results derived by Abramson for $Z_0=1$. Furthermore, in this event the total offered traffic G closely follows the relation

 $S = 1 - \exp\{-G\},\$

which was predicted in (5.14).

Information on the convergence rate can be found in appendix B by means of computer tables of the variables ER and the total traffic G.

The traffic to be offered if the receiver has a threshold of $Z_0=4$ and $Z_0=10$ is given in figures 5.11 and 5.12. Near the cell boundary (ρ +1) the number of retransmissions increases rapidly with the traffic load if S is larger than S=0.4 pps resp. S=0.3 pps. The channel appears to reach its capacity limit for

0.5 < S < 0.6 pps resp. 0.4 < S < 0.5 pps.

As confirmed by the curves for higher receiver thresholds $(Z_0 > 4)$, the offered traffic can be constant with distance when $\rho \neq 1$. The effect has been explained by (5.18), predicting the existence of a constant $G(\rho) = S_0 \exp[G]$ for $\rho > ({}^{\beta} \sqrt{Z_0})^{-1} = \frac{1}{2}\sqrt{2}$.

Comparing the plots using the critical circle model with the plots using the incoherent model, we note the following:

For low receiver thresholds $(Z_0=1)$, the critical circle model is more optimistic, while for median to large thresholds $(Z_0=4 \text{ and } 10)$ the incoherent model is more optimistic.

For intermediate values of ρ ($\rho \approx 0.5$), high thresholds and large traffic loads, the effect of interference generated outside a circle of radius a ρ is apparent: the incoherent model requires more traffic per area to be offered than according to the critical circle model. On the other hand for the much larger area of relatively large ρ ($\rho > 0.5$) the effect of fading is very favourable.



Figure 5.10a(\uparrow) and 5.11a(\downarrow): Spatial distribution of required offered traffic G(ρ) for uniform throughput S(ρ)=S/ π with S=0.1, 0.2, etc, for a receiver threshold of Z₀=1 and Z₀=4, respectively.





Normalised distance of terminal ho





Figure 5.10b(+) and 5.11b(+):

Total required offered traffic G
for a receiver threshold of Z₀=1 and
Z₀=4, respectively, as function of
the throughput S, compared with
I standard slotted ALOHA: S=G e^{-G}
e² ring model (section 5.3)
e³ capture of one packet every
occupied slot: S=1-R₀
e⁴ capture of all packets: S=G

Incoherent addition receiver threshold: 4.0 (6.0 dB)





Incoherent addition receiver threshold:10.0 (10.0 dB)



Figure 5.12a: Spatial distribution of required offered traffic $G(\rho)$ for uniform throughput $S(\rho)=S/\pi$ with S=0.1, 0.2, ...

Figure 5.12b:

Total required offered traffic G

as function of throughput S, compared with

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- •1 standard slotted ALOHA: S=G e^{-G}
- •2 ring model (section 5.3)
- •3 capture of one packet every occupied slot: S=1-R₀
- •4 capture of all packets: S=G

6 COHERENT ADDITION

6.1 Spatial distribution of the traffic throughput

Coherent signal addition has been described in section 2.2.2. These results are now used to study the channel throughput behaviour. Arnbak and Van Blitterswijk [1] concluded that, compared with incoherent addition, the coherent addition of interfering signals promises a higher channel capacity. The model of propagation (section 2.1) and addition of interference signals will be referred to as the "coherent model". In analogy with the incoherent case we also assume a universal threshold Z_0 independent of n (5.3). The validity of this assumption requires further study.

In this section the spatial distribution is found by inserting the image of the joint mean power pdf (4.35) in the conditional capture probability (4.63)

$$I_{z,n}(\rho) = 1 - \rho^{-\beta} \int_{-\infty}^{\infty} \exp\{-\rho^{-\beta}\lambda\} g^{n}(Z_{0}\lambda) d\lambda, \qquad (6.1)$$

where we have replaced the integration variable λ by $Z_0\lambda$. With (4.68) and (6.1) the channel throughput per normalised unit area, $S(\rho)$, can be written as

$$S(\rho) = G(\rho) \left[1 - \sum_{n=1}^{\infty} R_n + \sum_{n=1}^{\infty} \left[R_n \rho^{-\beta} \int_0^{\infty} \exp\{-\lambda \rho^{-\beta}\} g^n (Z_0 \lambda) d\lambda\right]\right], \quad (6.2)$$

or, after interchanging integration and summation and using the series expansion of the exponential function

$$S(\rho) = G(\rho) e^{-G} \left[1 + \rho^{-\beta} \int_{0}^{\infty} \exp\{-\lambda \rho^{-\beta}\} \left(\exp\{G g(Z_0\lambda)\} - 1\right) d\lambda\right]$$
$$= G(\rho) e^{-G} \rho^{-\beta} \int_{0}^{\infty} \exp\{-\lambda \rho^{-\beta} + Gg(Z_0\lambda)\} d\lambda.$$
(6.3)

Three methods to analyse the spatial distribution of traffic in a mobile ALOHA network with this equation will be proposed. First, $S(\rho)$ can be found using the Gauss-Laguerre numerical integration method; a second method is provided by a formal series expansion, and the third possibility is given by Laplace transformation of the throughput density. For large traffic loads G, an asymptotic expansion of the Laplace integrals may be useful.

6.2 The Gauss-Laguerre numerical integration method

A substitution of $\lambda \rho^{-\beta} \stackrel{\Delta}{=} x$ in (6.3) yields

$$S(\rho) = G(\rho) \int_{0}^{\infty} e^{-x} \exp\{-G + Gg(Z_{0}\rho^{\beta}x)\} dx.$$
 (6.4)

Integrals of this form can be calculated numerically from the Gauss-Laguerre integration method [7,(25.4.45) and table (25.9)

$$\int_{0}^{\infty} e^{-x} f(x) dx = \sum_{j=1}^{m} w_{j} f(x_{j}) + R_{m}$$
 (6.5)

for an m-point integration, where w_j are weight factors in the sampling in the points x_j and R_m is the residual error. An example of the set (w_j, x_j) for a 6-point integration is given in figure 6.1 [7].

> ABSCISSAS AND WEIGHT FACTORS FOR LAGUERRE INTEGRATION $\int_{0}^{\infty} e^{-x} f(x) dx = \sum_{i=1}^{n} w_i f(x_i)$ Abscissas = x_i (Zeros of Laguerre Polynomials) Weight Factors = w_i n=6 x_1 w_1 $0.22284 \ 66041 \ 79 \ (-1)4.58964 \ 673950 \ 1.18893 \ 21016 \ 73 \ (-1)4.17000 \ 830772 \ 2.99273 \ 63260 \ 59 \ (-1)1.13373 \ 382074 \ 5.77514 \ 35691 \ 59 \ (-1)1.13373 \ 382074 \ 5.77514 \ 35691 \ 59 \ (-1)1.13373 \ 382074 \ 5.77514 \ 35691 \ 59 \ (-1)1.13373 \ 382074 \ 5.77514 \ 35691 \ 59 \ (-1)1.13373 \ 382074 \ 5.77514 \ 35691 \ 59 \ (-1)1.13373 \ 382074 \ 5.77514 \ 35691 \ 59 \ (-1)1.13373 \ 382074 \ 5.77514 \ 35691 \ 59 \ (-1)1.13373 \ 382074 \ 5.77514 \ 35691 \ 59 \ (-1)1.13373 \ 382074 \ 5.77514 \ 35691 \ 59 \ (-1)1.13375 \ 382074 \ 5.77514 \ 35691 \ 59 \ (-7)8.98547 \ 906430$

Figure 6.1 [7]

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Applied to (6.3) one finds

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$$S(\rho) \approx G(\rho) \sum_{j=1}^{m} w_j \exp \left\{-G + Gg(Z_0 \rho^\beta x_j)\right\}$$
(6.6)

6.3 Series expansion

A formal series expansion of S(p) can be found from

$$S(\rho) = -G(\rho) e^{-G} \int_{\lambda=0}^{\infty} \exp\{Gg(Z_0\lambda)\} d \exp\{-\rho^{-\beta}\lambda\}.$$
(6.7)

After integrating by parts we can write

$$S(\rho) = G(\rho) \left[1 - Z_0 e^{-G} \rho^{\beta} \int_{\lambda=0}^{\infty} Gg'(Z_0\lambda) \exp\{Gg(Z_0\lambda)\} d \exp\{-\rho^{-\beta}\lambda\} \right].$$

Partial integration can be repeated with integrals of the form

$$S(\rho) = G(\rho) \left[1 + \dots + \int_{\lambda=0}^{\infty} \dots d \exp\{-\rho^{-\beta}\lambda\} \right].$$

This results in the expansion

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$$S(\rho) = G(\rho) [1 + Z_{0}\rho^{\beta} \bar{G}g'(0) + Z_{0}^{2\beta} [Gg''(0) + (Gg'(0))^{2}] + \dots], \quad (6.8)$$

provided the expansion converges and $g^{(k)}(0)$ exists for all k. Writing the expansion (6.8) in terms of the moments μ_k , we find

$$S(\rho) = G(\rho) \left[1 - Z_0 \rho^{\beta} G_{\mu_1} + Z_0^{2\beta} \rho^{2\beta} (G_{\mu_2} + G^2 \mu_1^2) + Z_0^{\beta\beta} G_{\mu_3} - 3G^2 \mu_1 \mu_2 - G^3 \mu_1^3 \right] + \dots \right], \quad (6.9)$$

if all moments μ_k exist. From the normalisation (1.8) of \overline{P}_s , it will be clear that the moments μ_k increase with k, so the expansion must be restricted to sufficiently small values of p. Bounds on the moments are described by (4.28) and (4.30).

Recommendations 4.1 and 4.2

The form of the throughput per unit area S(p) written in terms of the statistical properties (i.e., the moments μ_k) of the unconditional packet power pdf, suggests that Mellin transformation of the mean power pdf might be useful. The Mellin transformation is described in Appendix C.

Writing the expansion (6.9) in terms of central moments m_k (about the mean μ_1) is also recommended for further study. The central moments are defined as

$$\mathbf{m}_{k} \stackrel{\Delta}{=} \mathbf{E} \left(\left(\mathbf{\overline{P}}_{s} - \boldsymbol{\mu}_{1} \right)^{k} \right)$$
 (6.10)

and for instance $m_2 = \mu_2 - \mu_1^2$. The second central moment m_2 is better known as the variance σ^2 .

6.4 The image of the spatial throughput distribution

Analogous to g(v), a Laplace-transformed image function s(v) of the spatial distribution of the traffic throughput can be defined as

$$s(\mathbf{v}) \stackrel{\Delta}{=} L_{I}^{I} \{ S_{\overline{P}_{S}}(\overline{P}_{S}) \} = \int_{0}^{\infty} 2\pi\rho S(\rho) e^{-\mathbf{v}\rho^{-\beta}} d\rho \qquad (6.11)$$

This function is the Laplace image of the traffic throughput per unit of mean packet power given by

$$S_{\overline{P}}(\overline{p}_{s}=\rho^{-\beta}) \stackrel{\Delta}{=} 2\pi\rho \quad S(\rho) \quad \left| \frac{d\rho}{d\overline{p}_{s}} \right| = \frac{2\pi}{\beta}\rho^{\beta+2} \quad S(\rho). \quad (6.12)$$

As distinct from g(v) and $f_{\overline{p}}$, the functions s(v) and $S_{\overline{p}}$ are not

normalised to unity, but to S. So, using integration (1.10),

$$s(0) = S$$
 and $\int_{0}^{\infty} S_{\overline{P}}(x) dx = S.$ (6.13)

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Inserting (6.3) in definition (6.11) of the image s(v), we find

$$\mathbf{s}(\mathbf{v}) = \int_{0}^{\infty} 2\pi\rho \ \mathbf{G}(\rho) \ \mathbf{e}^{-\mathbf{G}} \ \rho^{-\beta} \int_{0}^{\infty} \exp\{-(\lambda+\mathbf{v})\rho^{-\beta} + \mathbf{Gg}(\mathbf{Z}_{0}\lambda)\} \ d\lambda \ d\rho.$$

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By substitution of $\rho^{-\beta} = x$, using (1.14) and interchanging the order of integration

$$\mathbf{s}(\mathbf{v}) = \mathbf{G} \mathbf{e}^{-\mathbf{G}} \int_{0}^{\infty} \int_{0}^{\infty} \mathbf{f}_{\overline{\mathbf{P}}_{s}}(\mathbf{x}) \mathbf{x} \mathbf{e}^{-(\lambda+\mathbf{v})\mathbf{x}} d\mathbf{x} \mathbf{e}^{\mathbf{G}g(Z_{0}\lambda)} d\lambda.$$

The inner integral equals the derivative of the translated Laplace image $-g'(\lambda+v)$, so

$$s(v) = -Ge^{-G} \int_{0}^{\infty} g'(\lambda+v) \exp\{Gg(Z_{0}\lambda)\} d\lambda, \qquad (6.14)$$

which gives the image function of the spatial distribution of the traffic throughput. We shall call equation (6.14) the coherent analysis equation as it provides an expression for the traffic throughput, given the traffic offered.

Recommendation 4.3

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We have not found a general solution for the integral equation (6.14). A substitution of $Gg(v) \stackrel{\Delta}{=} ln\{h(v)\}$ may be useful. We then find

$$\mathbf{s}(\mathbf{v}) = -\int_{0}^{\infty} \frac{\mathbf{h}'(\mathbf{v}+\boldsymbol{\kappa})}{\mathbf{h}(\mathbf{v}+\boldsymbol{\kappa})} \frac{\mathbf{h}(Z_{0}\boldsymbol{\kappa})}{\mathbf{h}(0)} d\boldsymbol{\kappa}.$$
 (6.15)

Boundary conditions are $h(0) = e^{G}$ and $h(\infty) = \frac{1}{(\sec (4.4))}$ and (4.6).

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6.4.1 Special cases of the coherent analysis equation

Although general solutions are difficult to derive, some special cases of the coherent analysis equation are interesting (and easy) to derive.

In case of a light (offered) traffic load (G+O), we find

$$s(v) \neq G g(v),$$
 (6.16)

confirming that the effect of collisions can be neglected in this case. A similar case can be derived from $Z_0 \rightarrow 0$. In this event all packets can capture the receiver, irrespective of any overlap.

With high receiver thresholds $(Z_0 \rightarrow \infty)$, we find from the analysis equation (6.14)

$$s(\mathbf{v}) = -\int_{0}^{\infty} Ge^{-G}g'(\lambda + \mathbf{v}) e^{0} d\lambda$$
$$= -Ge^{-G} \int_{\mathbf{v}}^{\infty} g'(\kappa) d\kappa = Gg(\mathbf{v}) \exp\{-G\} \quad (6.17)$$

With the high-threshold receiver, an overlap will destroy all involved n+1 packets. Only packets transmitted in slots with no interfering packets (n=0) capture the receiver. The probability R_0 of no interference is equal for all transmitters (i.e., independant of distance ρ). So for $Z_0^{+\infty}$ the spatial distribution of $S(\rho)$ has the same shape as $G(\rho)$, but is reduced by the loss factor $exp\{-G\}$ for slotted ALOHA.

Recommendation 4.4

This effect has already been noticed in the incoherent case, where it is of particular influence for traffic from the boundaries of the cell, as packets generated in this region often satisfy the loss criterion (1.4) even with moderate Z_0 . Derivation of a similar observation in the coherent case is recommended. The approximation (4.32) may be useful.

6.5 Asymptotic integral expansion for high traffic loads

An asymptotic expansion for high traffic loads $(G \leftrightarrow \infty)$ of (6.14) can be obtained by integration by parts of the Laplace integrals [38,p258]. The analysis equation is rewritten as

$$\mathbf{s}(\mathbf{v}) = \frac{-\mathbf{G}e^{-\mathbf{G}}}{\mathbf{Z}_0\mathbf{G}} \int_0^\infty \frac{\mathbf{g}'(\lambda+\mathbf{v})}{\mathbf{g}'(\mathbf{Z}_0\lambda)} \frac{\mathrm{d}}{\mathrm{d}\lambda} \exp\{\mathbf{G}\mathbf{g}(\mathbf{Z}_0\lambda)\} \,\mathrm{d}\lambda, \qquad (6.18)$$

with which the partial integration is carried out: (6.19)

$$\mathbf{s}(\mathbf{v}) = \frac{-\mathbf{e}^{-G} \mathbf{g}'(\lambda + \mathbf{v})}{\mathbf{g}'(Z_0 \lambda)} \exp\{Gg(Z_0 \lambda)\} \Big|_{0}^{\infty} + \mathbf{e}^{-G} \int_{0}^{\infty} \exp\{Gg(Z_0 \lambda)\} \frac{\mathrm{d}}{\mathrm{d}\lambda} \frac{\mathbf{g}'(\lambda + \mathbf{v})}{\mathbf{g}'(Z_0 \lambda)} \,\mathrm{d}\lambda.$$

This is permissible if the image function g(v) is at least twice differentiable, i.e., according to (4.5) and (4.9), if at least the first and second moments μ_1 and μ_2 exist. (As can be seen from (4.28), this will be the case for realistic distributions, but for instance not for the (quasi-) constant distribution of example 2 in section 4.1.3.) From (4.5) and (4.9) it then follows that the conditions (3) in [38,p259] are satisfied:

$$g(Z_0\lambda) < 1$$
 (for $0 \le \lambda \le \infty$), $Z_0 \ne 0$, $\mu_1 \ne 0$ and $g'(v) \ne 0$. (6.20)

These conditions are insufficient to ensure that the integral on the right hand of side (6.19) exists, but they can be shown [38] strong enough to ensure that

$$s(v) \approx \frac{g'(v)}{Z_0 g'(0)} = \frac{-g'(v)}{Z_0 \mu_1}$$
 for $G \neq \infty$. (6.21)

Reverse transformation of both sides and applying (A.1.5) yields the distribution of the mean power of the received packets

$$S_{\overline{P}_{s}}(\overline{p}_{s}) \approx \frac{\overline{P}_{s}}{z_{0}\mu_{1}} f_{\overline{P}_{s}}(\overline{p}_{s})$$
 for $G \neq \infty$. (6.22)

The spatial distribution of throughput traffic can now be obtained from (1.14) and (6.12)

$$S(\rho) \approx \frac{\rho^{-\beta}}{Z_0 \mu_1} \frac{G(\rho)}{G}$$
 for $G \neq \infty$. (6.23)

Integration by parts may be continued to obtain higher-order terms. Each step introduces a new factor of 1/G. After some algebra, which is contained in appendix E, we find

$$s(v) = -\frac{g'(v)}{Z_{0}\mu_{1}} - \frac{1}{G} \left[\frac{g''(v)}{Z_{0}^{2} \mu_{1}^{2}} + \frac{\mu_{2}}{\mu_{1}^{2}} \frac{g'(v)}{Z_{0}} \right]$$

$$+ \frac{1}{G^{2}} \left[\left(-\frac{\mu_{3}}{\mu_{1}^{4}} + 3\frac{\mu_{2}^{2}}{\mu_{1}^{5}} \right) \frac{g'(v)}{Z_{0}} - \frac{\mu_{2}}{\mu_{1}^{4}} \frac{g''(v)}{Z_{0}^{2}} - \frac{1}{\mu_{1}^{3}} \frac{g'''(v)}{Z_{0}^{3}} \right] + \dots$$

$$(6.24)$$

After reverse transformation to the ρ domain, the spatial distribution of throughput traffic can be found on the form

$$S_{\rho}(\rho) = G(\rho) \left[a_1 \rho^{-\beta} + a_2 \rho^{-2\beta} + a_3 \rho^{-3\beta} + \cdots \right],$$
 (6.25)

with a_i an expansion in terms of G^{-j} :

$$a_{1} \stackrel{\Delta}{=} \frac{1}{Z_{0}^{G}G_{\mu_{1}}} \begin{bmatrix} 1 + \frac{1}{G}\frac{\mu_{2}}{\mu_{1}^{2}} + \frac{1}{G^{2}}(-3\frac{\mu_{2}^{2}}{\mu_{1}^{2}} + \frac{\mu_{3}}{\mu_{1}^{3}}) + \dots \end{bmatrix}$$

$$a_{2} \stackrel{\Delta}{=} \frac{1}{Z_{0}^{2}G^{2}\mu_{1}^{2}} \begin{bmatrix} -1 - \frac{1}{G}\frac{\mu_{2}}{\mu_{1}^{2}} + \dots \end{bmatrix}$$

$$a_{3} \stackrel{\Delta}{=} \frac{1}{Z_{0}^{3}G^{3}\mu_{1}^{3}} \begin{bmatrix} 1 + \dots \end{bmatrix}.$$

Recommendation 4.5

The above asymptotic expansion was only derived a few weeks before finishing this thesis. A more detailed study is recommended. Derivation of a general form of the factors a_i in (6.25) is recommended. Expansion (6.24) appears to incorporate a factor μ_i in its i-th term. As μ_i can increase exponentially with i, convergence of (6.24) remains to be shown.

6.6 Total traffic throughput S

We now study the special case v=0 in the analysis equation (6.14)

$$s(0) = -Ge^{-G} \int_{0}^{\infty} g'(\lambda) \exp\{Gg(Z_{0}\lambda)\} d\lambda = S, \qquad (6.26)$$

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where the last equality follows from (6.13). We have thus found an expression for the total traffic throughput S. In appendix C this equation will be derived in a different way by transformation of formulas in |1|.

Comparing (6.26) with the standard ALOHA throughput relation, the improvement factor of the channel throughput can be defined as

$$\eta(G,Z_0) = \int_0^\infty -g'(\lambda) \exp\{Gg(Z_0\lambda)\} d\lambda > 1$$
 (6.27)

The improvement factor n increases with G and decreases if the receiver threshold Z₀ increases.

Three special values of the receiver threshold have been found for which the S-G relation is independent of the spatial distribution of the traffic. Moreover, for large traffic loads (G+∞) all realistic distributions will be shown to result in the limit

$$S_{\infty} = \frac{1}{Z_0}$$

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Spatial distributions with unbounded moments may give other limits [1]. It will be shown that with most thresholds Z_0 , the total throughput S depends not only on Z_0 and the total offered traffic G, but also on the shape of the spatial distribution of traffic.

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6.6.1 Spatial cases of the total traffic throughput equation

● High receiver thresholds: Z₀→∞

In this case formula (6.26) correctly returns to the pure ALOHA case as

$$S = G e^{-G} \int_{0}^{\infty} -g'(\lambda)d\lambda = G \exp(-G)$$
 (6.28)

All packets experiencing overlap are lost.

• The perfect-capture receiver: Z₀=1 We find

$$S = -\exp\{-G\} \exp\{Gg(\lambda)\}\Big|_{\lambda=0}^{\infty} = 1 - \exp(-G)$$
(6.29)

The Poisson character of the offered traffic gives an interpretation of this result, as precisely the part $1-e^{-G}$ of all time slots is occupied by one or more packets. Thus <u>all</u> occupied slots contribute, on average, <u>one</u> successful packet. This is an interesting result as it means that, given perfect capture in the coherent case, increasing traffic G never leads to a decrease in channel throughput. Remarkably, the throughput S also equals the throughput (5.14) for the critical circle model. However in (6.29) we may not assume that every occupied slot contributes exactly one received packet. Some occupied slots will contribute none, while other slots may contribute, in principle, more than one packet!

special case Z₀=0

$$S = -Ge^{-G} \int_{0}^{\infty} g'(\lambda) e^{G} d\lambda = G \qquad (6.30)$$

All packets capture the receiver.

These three cases apply for any spatial distribution of the offered traffic.

For other receiver thresholds, results will now be obtained by inserting v=0 in the formal asymptotic expansion (6.24)

$$s = \frac{1}{Z_0} + \frac{1}{G} \frac{\mu_2}{\mu_1^2} \frac{Z_0^{-1}}{Z_0^2} - \frac{1}{G^2} \left[\frac{\mu_3 Z_0^{-1}}{\mu_1^3} + \frac{\mu_2^2 (3Z_0^{+1})}{\mu_1^2}\right] \dots (6.31)$$

Apparently, any spatial distribution with bounded moments has, in the coherent case, the non-zero throughput limit

$$S_{\infty} = \frac{1}{Z_0} \quad \text{for } G + \infty. \tag{6.32}$$

This has been found in a special case in [1]. Writing (6.31) in terms of central moments (6.10) yields

$$S = \frac{1}{Z_0} + \frac{1}{G} \left[\frac{Z_0^{-1}}{Z_0^2} \left(1 + \frac{m_2}{\mu_1^2} \right) \right] + \dots \qquad (6.33)$$

The first-order term clearly confirms an increase in traffic throughput if the differences in received packet power are increased [2] [24].

For non-perfect capture $(Z_0>1)$ saturation effects occur, since S decreases with G for large G. Thus, the S-G throughput curve has an extremum S with max

$$S_{max} > S_{\infty} = \frac{1}{Z_0}$$
 (6.34)

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Recommendation 4.6

Derivation of the general form of the i-th term of the expansion is recommended.

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We now continue with some specific examples of spatial distributions of the offered traffic.

6.7. Ring model

In the ring model the spatial distribution of the traffic is a δ -distribution [1]. All packets are received with the same mean power.

$$G(\rho) = \frac{G}{2\pi} \delta(\rho-1)$$
 and $f_{\vec{P}}(\vec{p}_s) = \delta(\vec{p}_s-1)$. (6.35)

The Laplace transform of the latter is $g(v) \approx \exp\{-v\}$.

6.7.1 Capture probability

Although the intermediate results of the probabilities $F_{z,n}$ and $I_{z,n}$ are no longer necessary to obtain the desired throughput S and its spatial distribution S(ρ), these probabilities are given as an illustration. We apply the formulas (4.57) and (4.63) to find

$$F_{z,n} = 1 + \int_{0}^{\infty} \exp\{-(nZ_{0}+1)\lambda\} d\lambda = \frac{nZ_{0}}{nZ_{0}+1}$$
(6.36)

$$I_{z,n}(\rho) = F_{z,n} \quad \text{for } \rho = 1$$

$$(I_{z,n}(\rho) \quad \text{for } \rho \neq 1 \text{ is of no interest}).$$

These results agree with [1].

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6.7.2 Traffic throughput

The traffic throughput image can be derived by applying the coherent analysis equation (6.14)

$$s(\mathbf{v}) = -Ge^{-G} \int_{0}^{\infty} \exp\{-\lambda - \mathbf{v} + Ge^{-Z_0\lambda}\} d\lambda. \qquad (6.37)$$

The integral is given in [8, (3.331.1) on p308]

$$s(v) = -e^{-v} \frac{Ge^{-G}}{Z_0} (-G)^{-Z_0^{-1}} \gamma(Z_0^{-1}, -G)$$
(6.38)

using the incomplete γ -function $\gamma(a,x) \stackrel{\Delta}{=} \int_{0}^{x} e^{-t} t^{a-1} dt$.

As might be expected we find a spatial ring distribution of the traffic throughput

$$s(v) = S e^{-v}$$
 and thus $S(\rho) = \frac{S}{2\pi} \delta(\rho - 1)$. (6.39)

The total throughput of the channel now becomes

$$S \stackrel{\Delta}{=} G e^{-G} \eta(G, Z_0) = \frac{-G e^{-G}}{Z_0} (-G)^{Z_0^{-1}} \gamma(Z_0^{-1}, -G)$$
 (6.40)

Another standard-form solution is found by substituting $g(\lambda) \stackrel{\Delta}{\simeq} t$ in the expression (6.26) for the total throughput:

$$S = -G \int_{t=0}^{1} t \exp\{G(t^{Z_0}-1)\} d \ln t, \qquad (6.41)$$

which can be written as the integral representation [7,(13.2.1)] of Kummer's function [7,(13.1.2)], after substituting $t^{Z_0} - 1 \stackrel{\Delta}{=} x$

$$S = G \int_{0}^{1} e^{-Gx} \frac{dt}{dx} dx = G \int_{0}^{1} e^{-Gx} \frac{d}{dx} [(1-x)^{Z_{0}^{-1}}] dx. \quad (6.42)$$

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One finds

$$S = G M(1, Z_0^{-1} + 1, -G),$$
 (6.43)

where Kummer's function can be represented by [7, (13.1.2)]

$$M(1,Z_0^{-1}+1,-G) \stackrel{\Delta}{=} \int_0^1 e^{-Gx} x^0 (1-x)^{Z_0^{-1}-1} dx.$$

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A series expansion for the total traffic can be found from the slightly different substitution $G(t^{Z_0}-1) \stackrel{\Delta}{=} -x$ in (6.41). Partial integration then yields

$$S = G - G \int_{0}^{G} e^{-x} \left(1 - \frac{x}{G}\right)^{Z_{0}^{-1}} dx = G - G \int_{0}^{G} e^{-x} d\left[\frac{-G}{Z_{0} + 1} \left(1 - \frac{x}{G}\right)^{Z_{0}^{-1} - 1}\right]$$

Repeating the integration by parts leads to the series expansion

$$S = G - \frac{G^2}{Z_0^{-1} + 1} + \frac{G^3}{(Z_0^{-1} + 1)(Z_0^{-1} + 2)} - \dots$$
 (6.44)

which is the same as [7,(13.1.2)]. The limit $S_{\infty} = 1/Z_0$ is confirmed by [7,(13.1.15)]

$$S = \frac{1}{Z_0} (1 + 0(G^{-1})).$$
 (6.45)

The expansion has the correct limits $S=1-e^{-G}$ for $Z_0=1$ and $S=Ge^{-G}$ for $Z_0 \rightarrow \infty$. As can be seen from figures 6.2 and 6.3, the first terms of the series expansion give a good approximation for G not too large. Other properties of the total throughput traffic S(G) curve, e.g. the extremum, may be found by applying the theory of confluent hypergeometric functions [7,(13)].



Figure 6.2: Expansion for the total traffic throughput S as a function of the offered traffic G for a perfect-capture receiver.



For large G the expansion by partial integration (6.24) is valid

$$S(\rho) = \frac{S}{2\pi} \delta(\rho - 1) = \frac{\delta(\rho - 1)}{2\pi} \left[\frac{1}{Z_0} + \frac{1}{G} \frac{Z_0 - 1}{Z_0^2} - \frac{1}{G} \frac{(Z_0 + 1)(2Z_0 - 1)}{Z_0^2} + \dots \right]. \quad (6.46)$$

The limit S_{∞} is in accordance with results in [1].

6.8 Quasi-constant traffic density

The quasi-constant traffic density $G(\rho) = \frac{G}{\pi} \exp\{-\frac{\pi}{4}\rho^4\}$, described in [1] and example 1 in section 4.1.3, for $\beta=4$ has the area mean power pdf

$$f_{\overline{p}}(\overline{p}_{s}) = \frac{1}{2} \overline{p}_{s} \frac{-\pi}{2} \exp\{\frac{-\pi}{4\overline{p}_{s}}\},$$
 (=4.13)

and its Laplace image has the form [7,(29.3.82)]

$$g(v) = \exp\{-\sqrt{\pi v}\}.$$
 (=4.14)

Although the behaviour of a distribution with unbounded expected received power $(\mu_1 \leftrightarrow \infty)$ has to be regarded with caution, this example does yield instructive results [1].

6.8.1 Capture probability [1]

Using the formula of the capture probability (4.57) we find

$$F_{z,n} = 1 - \int_{0}^{\infty} \sqrt{\pi} \exp\{-\sqrt{\pi} (n\sqrt{Z_{0}}+1) \sqrt{\lambda}\} d\lambda$$
$$= 1 - \frac{\exp\{t\}}{n\sqrt{Z_{0}}+1} \Big|_{t=0}^{\infty} = \frac{n\sqrt{Z_{0}}}{n\sqrt{Z_{0}}+1} . \qquad (6.47)$$

 $F_{z,n}$ here has the same form as in the ring-model, if Z_0 in the latter is replaced by $\sqrt{Z_0}$. This confirms the observation that only in the events $Z_0 = 0$, 1 or ∞ , the throughput relation (S-G) becomes independent of the spatial distribution involved.

6.8.2 Total traffic throughput

The correspondance $Z_0 \neq Z_0$ can also be established for the total throughput S. Applying formula (6.24), we find (6.48)

$$S = G \int_{0}^{1} \exp\{G[t^{\sqrt{Z}_{0}}-1]\} dt = \frac{-G}{G^{Z_{0}} Z_{0}^{\frac{1}{2}}} \int_{0}^{G} e^{-x}(G-x)^{Z_{0}^{\frac{1}{2}}-1} dx$$

where we have substituted $\exp\{-\sqrt{\pi s}\} \stackrel{\Delta}{=} t$ and $G\left[1-t^{2\frac{1}{0}}\right] \stackrel{\Delta}{=} x$. Erdélyi gives the solution for the integral [9,(6) pl37 vol.1], so

$$S = Z_0^{-\frac{1}{2}} Ge^{-G} (-G)^{-Z_0^{-\frac{1}{2}}} \gamma(Z_0^{-\frac{1}{2}}, -G), \qquad (6.49)$$

confirming the correspondence with the ring distribution. The above equation, using Kummer's function, thus equals

$$S = G M(1, Z_0^{-\frac{1}{2}} + 1, -G).$$
 (6.50)

مستم المحاجي والمناصر المراجع والمحاجب والمحاج المحاج ----The expansion suggested in (6.9) can not yield results due to the unbounded moments μ_{L} . In this case, however, application of the expansion method in the previous example yields a valid result, corresponding to (6.44) with Z_0 replaced by $\sqrt{Z_0}$.

$$S = G - \frac{G^2}{Z_0^{-\frac{1}{2}} + 1} + \frac{G^3}{(Z_0^{-\frac{1}{2}} + 1)(Z_0^{-\frac{1}{2}} + 2)} - \cdots].$$
(6.51)

Consequently figures 6.2 and 6.3 correspond to the cases $Z_0=1$ and Z_0 =16, respectively, when the offered traffic has the quasiconstant density of example 1.

The expansion for large traffic loads (6.24) is not valid as μ_1 is unbounded. But according to the $Z_0 + \sqrt{Z_0}$ correspondance, this distribution has the throughput limit [1]

$$S_{m} = 1/\sqrt{Z_{0}}$$
 (6.52)

6.8.3 Conditional capture probability

Spatial properties of the throughput can be derived from (4.63)

$$I_{z,n}(\rho) = 1 - \int_{0}^{\infty} \exp\{-\lambda - n\sqrt{\pi Z_0} \rho^2 / \lambda\} d\lambda.$$
 (6.53)

· · · · We now substitute $\gamma_n^{\Delta} = \frac{1}{2}n \sqrt{\pi Z_0} \rho^2$ and $q^{\Delta} = \sqrt{\lambda} + \gamma_n$. . .

$$I_{z,n}(\rho) = 1 - \int_{0}^{\infty} \exp\{\gamma_{n}^{2} - q^{2}\} 2\{q - \gamma_{n}\} dq. \qquad (6.54)$$

. .

By separating this into two integrals the first cancels with unity, and only the second integral remains: (6.55)

$$I_{z,n}(\rho) = 2\gamma_n \exp\{\gamma_n^2\} \int_{\gamma_n}^{\infty} \exp\{-q^2\} dq = \sqrt{\pi} \gamma_n \exp\{\frac{\gamma_n^2}{\gamma_n}\} \operatorname{erfc}\{\gamma_n\},$$

where
$$\operatorname{erfc}(x) \stackrel{\Delta}{=} 1 - \frac{2}{\sqrt{\pi}} \int_{x}^{\infty} \exp\{-t^2\} dt [7,(7)].$$

These results are similar to those in [1], which were obtained in another way.

6.8.4 Spatial distribution of throughput traffic

Although the image functions have proved convenient to derive $I_{z,n}$, a closed-form solution for the spatial distribution of traffic has not been found, because

$$S(\rho) = G(\rho) e^{-G} \rho^{-4} \int_{0}^{\infty} 2t \exp\{-\rho^{-4}t^{2} + G e^{-\sqrt{\pi Z_{0}t}}\} dt \qquad (6.56)$$

has not been solved. Analytic calculations are difficult, as the image function g(v) has unbounded derivatives for v=0.

6.9 <u>Coherent synthesis</u>

6.9.1 Synthesis using the Gauss-Laguerre method

In the event of coherent addition, a synthesis method using iterative numerical computing with the Gauss-Laguerre analysis method will now be proposed. Results will be presented and discussed for perfect capture $(Z_0=1)$ and for a receiver with threshold $Z_0=4$. The iteration scheme is obtained from the Gauss-Laguerre integration method described by (6.6). Analogous to the synthesis scheme for incoherent signals, the loss factor is obtained from the i-th estimate. Together with the required throughput, this gives the new estimate

$$G_{i+1}(\rho) = S(\rho) \qquad \frac{1}{\sum_{j=1}^{m} w_j \exp\{-G_i + G_i g_i (Z_0 \rho^{\beta} x_j)\}}, \qquad (6.57)$$

where, using (4.11) and (1.9), the image function expression can be written as يعاري الرابية فالعام وفيقه ولايته والتجري يتعار المحمو والمعاري

$$-G_{i} + G_{i} g_{i}(v) = \int_{0}^{1} 2\pi\lambda G_{i}(\lambda) \left(e^{-v\lambda^{-\beta}}-1\right) d\lambda \qquad (6.58)$$

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• •

The starting function is chosen as

. .

$$G_0(\rho) = S(\rho).$$

The spatial distributions are sampled in N points, and from an Npoint integration, the argument

$$-G_i + G_i g(Z_0 \rho x_i)$$

of the exponent in (6.57) is obtained for each specific distance ρ and summation index j. An m-term summation gives the loss factor in (6.57). As the loss factor depends on distance ρ , this has to be executed for all N samples to yield a new estimate $G_{i+1}(\rho)$.

Sufficiently accurate results have been obtained with an 8-term summation, 25 samples of the spatial distributions and up to 30 iteration steps. Synthesising light traffic loads required far less iterations. As in the incoherent synthesis, the iteration is terminated when the required accuracy is reached (see (5.62)); if the sequence of estimates diverges; if the total traffic to be offered G becomes too large (G >30 pps); or if the maximum number of M (M=30) iterations is exceeded. Processing time for coherent synthesis is approximately twenty times larger than for incoherent synthesis, partly due to the extra summation.

فللما ومراجع والمراجع المراجع والمراجع والمراجع والمراجع والمراجع والمراجع والمراجع والمراجع والمراجع والمراجع

6.9.2 Uniform throughput

The programme used to synthesise uniform throughput is contained in appendix B. In figure 6.4a, the offered traffic distribution in the event of perfect capture is depicted for various throughputs

$$S(\rho) = \begin{cases} S/\pi & \text{for } 0 < \rho < 1 \\ 0 & \text{elsewhere} \end{cases}$$

with S= 0.1, 0.2, 0.9 packets per slot.

Comparing this figure with figure 5.10, one can -not surprisinglyconclude that coherent addition requires less traffic to be offered to yield a certain throughput than is required with incoherent addition. In figure 6.6 the required offered traffic distributions for the three models are compared in the event of perfect capture and a uniform throughput S = 0.6 packets per slot.

As can be seen in figure 6.4b, the numerically obtained total traffic relation closely follows

 $S = 1 - \exp\{-G\},$

which was predicted by (6.29). As far as total traffic is concerned, the results of coherent modelling are the same as results from the critical circle model.

However, as can be seen in figure 6.6, the spatial distributions differ for the two models. With coherent addition, for intermediate distances (0.3 < ρ < 0.7), more traffic per unit area has to be offered. This is due to signal addition in the event of more than one interferer outside the critical circle of the test packet. On the other hand, for larger distances (ρ + 1), the offered traffic required by the coherent model is less: in this area the effect of Rayleigh fading appears to have a favourable influence on the capture probability.

Information on the rate of convergence can be found in appendix B.

Results for a receiver threshold of $Z_0=4$ are depicted in figure 6.5. As can be seen in figure 6.5a, near the cell boundary (ρ +1), the required offered traffic G(ρ) becomes rather constant with disctance. Comparing this distribution with G(ρ) in the event of incoherent uniform throughput in section 5.11, coherent addition yields slightly more optimistic results.

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Inaffic $\Im(p)$ to be offered to give a homogeneous spatial distribution of the traffic troughput $\Im(p)$

Figure 6.4a(+) and 6.5a(+): Spatial distribution of required offered traffic G(p) for uniform throughput $S(\rho)=6/\pi$ with S=0.1, 0.2, etc, for a receiver with threshold

Z₀=l and Z₀=4, respectively.

. 4 . 2 ŋ D 7 4

> Figure 6.4b(+) and 6.5b(+): Total required offered traffic G for receiver thresholds $Z_0 = 1$ and $Z_0 = 4$, respectively, as function of throughput S, compared with •l standard slotted ALONA: S=G e^{-G} •3 capture of one packet every occupied slot: S=1-R₀ •4 capture of all packets: S=G

coherent addition receiver threshold: 4.0 (6.0 dB)







Troffic $G(\rho)$ to be offered to give a homogeneous spatial distribution of the troffic troughput $S(\rho)$



Traffic $G(\boldsymbol{\rho})$ to be offered to give a homogeneous spatial distribution of the traffic troughput $S(\boldsymbol{\rho})$

Figure 6.6: Synthesis for various models in the event of perfect capture. Comparison of the traffic $G(\rho)$ to be offered to achieve the uniform throughput

$$S(\rho) = 0.6/\pi ppspa,$$

for, respectively,

- ••• the critical circle model,
- ____ the incoherent model,
- - the coherent model.

7 CONCLUSIONS AND RECOMMENDATIONS

The image-function approach has been shown very fertile in analysing the spatial distribution of packet traffic in a mobile cellular network. Analytic methods for analysis have been found. Extension to the synthesis problem is possible by iterative numerical computing.

In the incoherent case, general analytic results and many examples have been presented and explained. For coherently interfering signals, the analysis method obtained has been applied to a few examples. In this case, closed-form solutions are difficult to find, as integrals of exponents with complicated arguments are often involved. However, coherent transmission of the packets should be explored as the throughput will be larger than when incoherent interference is experienced. Even for heavy coherent traffic loads the theoretical limit of the throughput is non-zero. Stability of the channel is thus guaranteed.

Recommendations for further study have been given throughout this thesis, they are printed with dense characters. A summary of these recommendations is given below:

1) The introduction of a receiver threshold dependent on the number of interfering signals.

²) Derivation of coherent and incoherent analysis equations for more sophisticated propagation models, in particular with shadowing included.

³) Application of the expansion for Laplace integrals, for the incoherent analysis equation, to yield more insight in the behaviour under high traffic loads.

⁴) A more detailed study of the coherent addition channel. In particular:

⁵) Evaluation of the described coherent analysis methods using a typical offered traffic distribution. As an example, the image of the truly-constant distribution has been described in section 4.1.3. The Gauss-Laguerre method yields the throughput distribution in the ρ -domain. For various offered traffic loads G, this can be compared with the Taylor series (6.6) and Laurent series (6.25). Study of the convergence area of both expansions in the ρ and G domain is recommended.

⁶) Implementation of the results in a channel control system. Packet retransmission protocols may be optimised using the developed knowledge of the behaviour of the ALOHA channel. The channel control system can measure the pdf of the received packets. This uniquely specifies the spatial distribution and the image functions. A synthesis technique is useful to gather information on the saturation of the channel and to predict congestion.

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During these past months, I spent a pleasant time working at this subject; it surely excited my interest in mobile communication.

Jean-Paul Linnartz, November 1986

APPENDIX A PROPERTIES OF THE LAPLACE TRANSFORM

A.1 TABLE

operation	image	original		
integration	$\frac{1}{v}$ h(v)	$\int_{0}^{x} f(\lambda) d\lambda$	 (A.1.1)	
differentiation	v h(v)	$f'(v) \stackrel{\Delta}{=} \frac{d}{dv} f(v)$	(A.1.2)	
convolution	h ₁ (v) h ₂ (v)	$\int_{0}^{x} f_{1}(x-\lambda)f_{2}(\lambda)d\lambda$	(A.1.3)	
int of image	$\int_{\mathbf{v}}^{\infty} \mathbf{h}(\lambda) d\lambda$	$\frac{1}{x}$ f(x)	(A.1.4)	
diff of image	$\frac{d}{dv} h(v) \stackrel{\Delta}{=} h'(v)$	-xf(x)	(A.1.5)	
translation	$e^{-\alpha v} h(v)$	f(x-α)U(x-α) α>0	(A.1.6)	
transl. of image	h(v-α)	$e^{\alpha x} f(x)$	(A.1.7)	
scaling	h(av)	$\frac{1}{\alpha}$ f($\frac{x}{\alpha}$)	(A.1.8)	

.

A.2 LEMMA

Assume two functions $f_1(x)$ and $f_2(w)$, with Laplace images, resp., $g_1(q)$ and $g_2(p)$, and given $f_1(x)$, $f_2(w)$ can be found from

$$f_2(w) = \int_0^\infty \frac{1}{x} \exp\{-\frac{w}{x}\} f_1(x) dx.$$
 (A.2.1)

The Laplace image of f₂(w) now becomes

$$g_2(p) = \frac{1}{p} \int_0^\infty \exp\{-\frac{q}{p}\} g_1(q) dq$$
 (A.2.2)

A typical example of f_1 and f_2 is found in formulas concerning Rayleigh fading, e.g. (2.2). Note the different role of independent and dummy variables in (A.2.1) and (A.2.2).

Proof:

or

$$g_2(p) = \int_0^\infty \int_0^\infty \frac{1}{x} exp\{-\frac{w}{x} - wp\} f_1(x) dx dw.$$

Integration over w gives

$$g_2(p) = \int_0^\infty \frac{1}{x} \frac{f_1(x)}{p+1/x} dx.$$

A temporary substitution of $y \stackrel{\Delta}{=} x + \frac{1}{p}$ gives

$$g_2(p) = \int_{1/p}^{\infty} \frac{1}{yp} f_1(y-\frac{1}{p}) dy$$
.

This can be written as a integral over q:

$$g_{2}(p) = \frac{1}{p} \int_{0}^{\infty} \int_{1/p}^{\infty} f_{1}(y-\frac{1}{p}) e^{-yq} dy dq,$$

$$g_{2}(p) = \frac{1}{p} \int_{0}^{\infty} \int_{0}^{\infty} f_{1}(x) exp\{-q(x+\frac{1}{p})\} dx dq \qquad (A.2.3)$$

The integration over q equals a Laplace transformation from x to p domain, so

$$g_2(p) = \frac{1}{p} \int_0^\infty \exp\{-\frac{q}{p}\} g_1(q) dq.$$
 Q.E.D.

APPENDIX B: COMPUTER PROGRAMS FOR SYNTHESIS

100	FILE 2(TITLE="RESULTS", KIND=DISK, PROTECTION=SAVE, NEWFILE="	(RUE)
200	FILE 6(KIND=REMOTE, MYUSE=OUT)	
300	FILE 5(KIND=REMOTE, MYUSE=IN)	
400	FILE 90(KIND=PREVIEWER)	
500	BLOCK GLOBALS	
600	\$ INCLUDE "PLOTTER/FORTRAN/DECLARATION ON APPL"	
700	END	
800	S INCLUDE "PLOTTER/FORTRAN/ALLSUBS ON APPL"	
900		
1000	<u>_</u> ************************************	***
1100	Ċ	С
1200	C This program calculates the TRAFFIC OFFFRED	c
1200	C to an AIOHA mobile radio network	č
1600	C to an Alona mobile radio network	C C
1400	c which gives a homogeneous chroughput so	<u> </u>
1000	\ ^	++C
1700	0	~~C
1/00		
1800		с а
1900	C author: Jean-Paul Linnartz, may 1980	
2000	C Eindhoven University of Technology	- C
2100	C Department of Electrical Engineering	C
2200	C Telecommunications division	С
2300	C	С
2400	C*************************************	**C
2500	C	С
2600	C In the incoherent case, the iteration equation for	С
2700	C synthesis of traffic to be offered is	С
2800	C 2 pi Z r**4	С
2900	C G (r) = SO * exp(+int(1 G (1) d1))	С
3000	C I+1 Z r**4 + 1**4 I	С
3100	C	С
3200	C where the integral is taken from zero to one.	С
3300	C	С
3400	C*************************************	**C
3500	REAL IREAL, NREAL, WEIGHT, BOUND	
3600	REAL GT, ER, EROLD	•
3700	REAL Z, S, PI, POINT, INT, L, A	
3800	REAL G. GNW. R. GABR	
3900	REAL GTOT.STOT.PURE.GAR.RING.PERF	
4000	REAL ABX.ABY	
4100	DIMENSION GTOT(11), STOT(11), GABR(1000)	
4200	DIMENSION ABX(3), ABY(3)	
4300	DIMENSION PURE (50) , GAR (50) , RING (50) , PERF (50)	
4400	DIMENSION $G(100)$, $GNW(100)$, $R(100)$	
4500	INTROFE M N T IT III	
4000	INTEGER K KK PR	
4000	INTECED OB 11 OB 12 OB 13	
4700	PT=3 161502	
4000	C C C C C C C C C C C C C C C C C C C	
4900 5000	UDITE (6 100)	
5000	WKLIE (0,100) UDITE (6,101)	
2100	WKLLE $(0, 101)$ DEAD (5.200) 2	
5200	$\begin{array}{c} \text{KLAD} (5,200) \ \text{Z} \\ \text{UDTTE} (4,104) \end{array}$	
2300	WRITE (0,104)	
5400	(5,210) M	
5500	WRITE (6,106)	
5600		
	READ (5,210) N	
5700	READ (5,210) N IF (N.GT.50) THEN N=50	

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5900		IF (M.GT.30) THEN M=30
6000		WRITE (2,111) Z,K,M,N
6100		WRITE (6,150)
6200		READ (5,151)
6300		NREAL=N*1.
6400	С	
6500	100	FORMAT(" calculation of traffic offered to the channel" /)
6600	101	FORMAT(" receiver/modulation threshold $70 = "/)$
6700	102	FORMAT(" total traffic throughout $S = ", /)$
6800	103	FORMAT(" max number of curves in plot" /)
6900	104	FORMAT(" M. max number of iterations = " ()
7000	106	FORMAT(" N. number of semples in costial distrib = $(1/2)$
7100	111	FORMAT(" $ZO = "FIO_5." K = "T3" M Nm " 2T3 /)$
7200	110	FORMAT("")
7300	113	FORMAT("Fading and power add model")
7400	112	FORMAT("Critical surface model")
7500	150	FORMAT(" Do you want convergence info on terring 12 Volume ()
7600	151	FORMAT(71) FORMAT(71)
7700	200	FORMAT(r_10 , 5)
7800	210	FORMAT(T3)
7900	C	(OMMI(15)
8000	C****	****
8100	C	
8200	Ŷ	κκ=0
8300		
8400		CTOT(1)=0
8500	3000	NN~NNTJ
8600	2000	RR - RR + 1
8700	c	
8800	U	end 10 + VV/or
8000		$S=0.10 \wedge KK/PL$
0000		SIUI(KK+1)=0.1*KK
9000		WKLIE (2,113)
9100	c	WRITE (2,2010) KK, STOT(KK+1), S
9200	C C	
9300	L L	
9400		DU 400 111 = 1, N
9300		
9000	600	K(111)=1REAL/N
9700	400	G(111)=S
9000	L	* ^
9900	1000	
10000	1000	<u>i=i+i</u>
10100		ER=0.
10200	-	GT=0.
10300	C	
10400	C*****	*** calculation of a new distibution of G(r) ************************************
10500	С	
10600	_	DO 900 II=1,N
10700	С	per sample point we calculate the integral
10800		INT=0.
10900	_	A = Z * (R(II) * * 4)
11000	C	
11100	_	DO 800 III=1,N-1
11200	С	N samples of integrand
11300		IREAL=III * 1.
11400		L=IREAL/N
11500		POINT= A*2.*PI*L*G(III)
11600		INT=INT+POINT/(A+L**4)
11700	800	CONTINUE
11800	. .	INT = INT+A*PI*G(N)/(A+1)
11900	С	
12000		INT= INT / N

ì

.

12200	
	GNW(II) = S * EXP(INT)
12300 9	000 CONTINUE
12400 C	
12500 C*	***************************************
12600 C	
12700 C*	**** total traffic and convergence control ************
12800	DO 950 II=1.N-1
12900	IREAL=II * 1.
13000	GT=GT+ (IREAL * G(II) / N)
13100	ER=ER+ABS((GNW(II)-G(II))/G(II))
13200 9	G(II) = GNW(II)
13300	G(N) = GNW(N)
13400	GT=2.*PI*GT/N
13500	GT=GT+PI*G(N)/N
13600	GTOT(KK+1)=GT
13700	ER=ER*100./N
13800	IF(PR.EO.1) WRITE(6,2005) I,ER,GT
13900	WRITE(2,2005) I.ER.GT
14000 C	test on divergence:
14100	IF(ER.GT.EROLD) GOTO 3100
14200	EROLD=ER
14300 C	
14400 C	× ×
14500	IF (I.LT.M .AND. ER.GT.0.001) GOTO 1000
14600 C	make another iteration
14700	IF (1.EO.M) WRITE (2.2006)
14800	IF(PR.EO.1) WRITE(6,2001)
14900	WRITE(2,2001)
15000 C	
15100 C	**************************************
15200 C	
15300	2000 FORMAT(2X, 15, 1X, F10.5, 1X, 4F10.5)
15400	2001 FORMAT(" ")
15500	2005 FORMAT(" iteration ".12," dev", F9.3," % Gtot= ",F10.6)
15600	2006 FORMAT(" MAX NUMBER OF ITERATIONS !")
15700	2010 FORMAT("*** plot ",I3," with total traffic S= ",
15800	\$ F6.3,", distributed ", F6.4," per area ***")
15900	2020 FORMAT(" ! Exponent overflow ! end of calculation")
16000 C	
16100 C	
16200	CALL CURVDZ(90,0,0,15,15,1,N,R,G,
16300	\$ 10.0.1.10.0.1. FALSE FALSE.)
16400 C	
16500	IF (GT.LT.4 .AND. KK.LT.K) GOTO 3000
16600 C	make another plot with higher traffic load
16700 C	
16800 C	******* the total traffic S-G curve ************************************
16900 C	
17000	3100 IF (INT.GT.30) WRITE (2,2020)
17100 C	
17200	CALL CURVDZ(90,15,0,25,15,1,KK,STOT,GTOT,
17300	\$ 10,0.,1.,10,0.,2., .FALSE., .FALSE.)
17400 C	
17500 C	**********************
17600 C	C
17700 0	If fading and power addition are neglected, the C
17800 0	traffic to be offered can be calculated from the C
	critical surface model presented by Abramson. C
17900 C	filledal
17900 C 18000 C	C
17900 C 18000 C 18100 C	C

• 、

18300 С С CG (r) = S0 *18400 exp(+int(2 pi i G (1) dl)) С 18500 С I+1 Ŧ С С 18600 С С 18700 C where the integral is taken from zero to a. 18800 С С C******** CRITICAL SURFACE MODEL BY ABRAMSON *************** 18900 19000 C 19100 WRITE (6,114) 19200 WRITE (2,114) 19300 114 19400 C 19500 REAL GTOTA 19600 DIMENSION GTOTA(11) 19700 KK=0 19800 A=SQRT(SQRT(Z)) 19900 GTOTA(1)=0.20000 6000 KK = KK + 1EROLD=1000000 20100 20200 С new parameter S; new curve 20300 S=0.10 * KK/PI 20400 WRITE (2,112) 20500 WRITE (2,2010) KK, STOT(KK+1), S 20600 С 20700 Ç 20800 DO 3400 III=1,N 20900 IREAL=III*1. 21000 R(III)=IREAL/NREAL 21100 3400 G(III)=S21200 C 21300 I=0 21400 4000 I=I+1 21500 ER=0. 21600 GT=0. 21700 С 21800 21900 С 22000 DO 3900 II=1,N С 22100 per sample point we calculate the integral 22200 BOUND= A*II 22300 IF(BOUND.GT.NREAL) BOUND=NREAL 22400 С No traffic offered outside cell 22500 INT=0. 22600 III=1 22700 IREAL= III *1. 22800 3800 CONTINUE 22900 С samples of integrand 23000 WEIGHT= BOUND - IREAL + 0.5 23100 IF(WEIGHT.GE.1.) WEIGHT = 1. 23200 IF(WEIGHT.LE.O.) GOTO 3850 23300 INT=INT+2.*PI*IREAL*G(III)*WEIGHT 23400 III=III+l 23500 IREAL=III *1. GOTO 3800 23600 23700 3850 CONTINUE C 23800 С 23900 24000 С 24100 С INT= INT /(NREAL**2) 24200 24300 IF (INT.GT.30) GOTO 6100 24400 GNW(II) = S * EXP(INT)

24500	3900	CONTINUE
24600	С	
24700	С	
24800	C*****	*******************
24900	С	
25000	C****	total traffic and convergence control ************
25100		DO 3950 II=1.N-1
25200		TREAL TT * 1.
25300		CT = CT + (TREAL * C(TT) / NREAL)
25/00		$FD_{PD_{1}} = \frac{1}{2} \frac{1}{2$
25500	2050	C(TT) = CMJ(TT)
25500	2920	G(II) = GNW(II)
23000	0	$G(N) \equiv GNW(N)$
25700	C	
25800		GT=Z.*PI*GT/NREAL
25900		GT=GT+ PI*G(N)/NREAL
26000		GTOTA(KK+1)=GT
26100		ER=ER*100./NREAL
26200		IF(PR.EQ.1)WRITE(6,2005) I,ER,GT
26300		WRITE(2,2005) I,ER,GT
26400	С	
26500		IF(ER.GT.EROLD) GOTO 6100
26600		EROLD=ER
26700	С	
26800	-	IF (T.LT.M. AND, ER.GT.0.001) GOTO 4000
26900	С	make another iteration
27000	Ŭ	$TF_{1}(T,FO,M)$ WRITE (2,2006)
27100		TE(PR EO 1) WRITE(6 2001)
27100		$\frac{1}{100} \frac{1}{100} \frac{1}$
27200	<u>^</u>	WAILE(2,2001)
27300		
27400	C	**************************************
27500		DO $3960 111 = 1, N$
27600	3960	GABR((KK-1)*N+III)=G(III)
27700	С	
27800	С	
27900		IF (GT.LT.4AND. KK.LT.K) GOTO 6000
28000	С	make another plot with higher traffic load
28100	6100	IF (INT.GT.30) WRITE (2,2020)
28200	С	
28300		CALL MPNTDZ(90,0,0,15,15,1,N,1,KK*N,R,GABR,
28400	\$	10.0.,1.,10.0.,1.,.FALSE.,.FALSE.)
28500	C.	
28600	C*****	**** the total traffic S-G curve **********************
28700	Ĉ	
28800	•	CALL NEWOBJ(OBJ3)
28900		CALL PNTSDZ(90, 15, 0, 25, 15, 1, KK, STOT, GTOTA.
20000	c	10.0.1.10.0.2., FALSE, FALSE,
29000	r v	10,00,10,10,00,20, TRIDI0, TRIDI0,
29100	U	DO 0000 TT-1 21
29200		$DU 0000 II^{=}1,21$
29300		GI=(11-1)/10
29400		GAR(11)=2.5+5* GI
29500		GAR(21+11)=12.5-5.*GT
29600		PURE(11)=1/.5+5.* GT*EXP(-1.*GT)
29700		PURE(21+11)=1/.5
29800		PERF(II)=22.5 - 5.*EXP(-1.*GT)
29900		PERF(21+11)=22.5
30000		A=-1.*Z*GT/(Z+1.)
30100		RING(II)=17.5+5.*GT*EXP(A)
30200		RING(43-II)=PURE(II)
30300	8888	CONTINUE
30400	С	
30500		ABX(1)=17.5
30600		ABY(1)= 2.5

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30700		ABX(2)=22.5
30800		ABY(2) = 7.5
30900		ABX(3)=22.5
31000		ABY(3) = 2.5
31100	С	
31200		A=10.*ALOG10(Z)
31300		CALL FILPOL(OBJ3, 1, 42, PURE, GAR, "A", 30, 0, 25)
31400		CALL FILPOL(OBJ3, 1, 42, RING, GAR, "A", 0, 0, 35)
31500		CALL FILPOL(OBJ3, 1, 32, PERF, GAR, "D", 30, 0, 25)
31600		CALL FILPOL(OBJ3, 1, 3, ABX, ABY, "B", 30, 0, 25)
31700		CALL POLYGN(OBJ3, 1, 42, PURE, GAR, 1)
31800		CALL POLYGN(OBJ3, 1, 21, PERF, GAR, 1)
31900		CALL POLYGN(OBJ3, 1, 2, ABX, ABY, 1)
32000		CALL POLYGN(OBJ3, 1, 42, RING, GAR, 1)
32100		CALL COTEXT(OBJ3, 16, 3, 2, 5, 90, , 35, 5,
32200	\$	"Total traffic offered G")
32300		CALL COTEXT(OBJ3, 2, 2, 1, 0, ., 32, 5,
32400	\$	"Normalised distance of terminal")
32500		CALL COTEXT(OBJ3.1, 2.2, 90, 32, 5,
32600	\$	"Offered traffic per norm, area S()")
32700		CALL COTEXT(OBJ3, 17, 9, 1, 0, 35, 5,
32800	\$	"Throughput S")
32900		CALL COTEXT(OBJ3.,5.15,0.0.8.0.
33000	\$	"SYNTHESIS")
33100		CALL COTEXT(OBJ3.,52,15,0.0.8.0.
33200	\$	"SYNTHESIS")
33300		CALL COTEXT(OBJ35.14.4 .025.0.
33400	\$	"Traffic G() to be offered to give a homogeneous")
33500		CALL COTEXT(OBJ3.,5,14.0 .0.,25.0.
33600	\$	"spatial distribution of the traffic troughput S()")
33700		CALL COTEXT(OBJ3, 14.5, 14.7, 0, 40.5,
33800	\$	"Incoherent addition")
33900		CALL COTEXT(OBJ3.14.5.14.0 .027.5.
34000	\$	"receiver threshold: (dB)")
34100		CALL CONNUM(OBJ3, 19.6, 14, 0, 0.27, 5, "F4.1", DBLE(Z))
34200		CALL CONNUM(OBJ3,21.4,14,0,0.27,5,"F4.1",DBLE(A))
34300		CALL DRAWOB(90,0BJ3,0,0,25,20)
34400		CALL DISPOB(OBJ3)
34500	С	
34600		CLOSE(2, DISP=CRUNCH)
34700		STOP
34800		END
34900	C****	**************

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DATE & TIME	PRINTED: TUESDAY, OCTOBER 21, 1986 @ 15:20:57.	
100 200 300 400 500 600 700 800	<pre>FILE 2(TITLE="RESULTS",KIND=DISK,PROTECTION=SAVE,NEWFILE=TR FILE 6(KIND=REMOTE,MYUSE=OUT) FILE 5(KIND=REMOTE,MYUSE=IN) FILE 90(KIND=PREVIEWER) BLOCK GLOBALS \$ INCLUDE "PLOTTER/FORTRAN/DECLARATION ON APPL" END \$ INCLUDE "PLOTTER/FORTRAN/ALLSUBS ON APPL"</pre>	UE)
900		
1000	C*************************************	*
1100	C	С
1200	C This program calculates the TRAFFIC OFFERED	С
1300	C to an ALOHA mobile radio network	С
1400	C which gives a homogenoous throughput SO	С
1500	C	С
1600	C*************************************	C
1700	C	С
1800	C	С
1900	C author: Jean-Paul Linnartz, OCTOBER 1986	С
2000	C Eindhoven University of Technology	С
2100	C Department of Electrical Engineering	С
2200	C Telecommunications division	С
2300	C	С
2400	C*************************************	*C
2500	C	С
2600	C In the COHERENT case, the iteration equation for	С
2700	C synthesis of traffic to be offered is obtained	С
2800	C from the Gauss-Laguerre numerical integration	С
2900	C method	С
3000	C	С
3100	C	С
3200	С	С
3300	С	С
3400	C*************************************	*C
3500	REAL IREAL, IIIRL, IMAGE	
3600	REAL GT, ER, EROLD, NREAL	
3700	REAL Z, S, PI, POINT, INT, A, SAREA	
3800	REAL G, GNW, R, GABR, TERM, SUM	
3900	REAL GTOT, STOT, PURE, GAR, RING, PERF	
4000	REAL ABX, ABY, X, W, ARG, GTNEW	
4100	DIMENSION GTOT(11), STOT(11), GABR(1000)	
4200	DIMENSION ABX(3), ABY(3)	
4300	DIMENSION PURE(50), GAR(50), RING(50), PERF(50)	
4400	DIMENSION G(100),GNW(100),R(100),X(20),W(20)	
4500	INTEGER M, N, I, II, III, L, LL	
4600	INTEGER K, KK, PR, NN	
4700	INTEGER OBJ1, OBJ2, OBJ3	
4800	PI=3.141592	
4900	C	
5000	WRITE (6,100)	
5100	WRITE (6,101)	
5200	READ (5,200) Z	
5300	WRITE (6,104)	
5400	READ (5,210) M	
5500	WRITE (6,106)	
5600	READ (5,210) N	
5700	IF (N.GT.50) THEN $N=50$	
5800	K=10	

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5900 IF (M.GT.30) THEN M=30 6000 WRITE (2.111) Z.K.M.N 6100 WRITE (6,150) READ (5,151) PR 6200 IF(S.GT.1) S=1. 6300 NREAL=N*1. 6400 6500 С 6600 NN=0 FORMAT(" calculation of traffic offered to the channel",/) 6700 100 FORMAT(" receiver/modulation threshold ZO = ",/) 101 6800 102 FORMAT(" total traffic throughput S= ",/) 6900 FORMAT(" 103 max number of curves in plot",/) 7000 ´''./) FORMAT(" 7100 104 M, max number of iterations = N, number of samples in spatial distrib.= ",/) 106 FORMAT(" 7200 FORMAT(" ZO= ",F10.5," K= ",I3," M,N= ",2I3,/) 7300 111 FORMAT(" ") 7400 110 FORMAT("COHERENT ADDITION model") 113 7500 FORMAT("") 7600 C112 FORMAT(" S. TOTAL TRAFFIC THROUGHPUT = "./) 7700 114 150 FORMAT(" Do you want convergence info on terminal? Y=1",/) 7800 151 7900 FORMAT(I1) 200 FORMAT(F10.5) 8000 8100 210 FORMAT(13) 8200 220 FORMAT(F10.5) 8300 С 8400 С 8500 8600 С 8700 8800 X(1)=0.1702796323X(2)=0.9037017767 8900 9000 X(3)=2.2510866298X(4) = 4.26670017029100 9200 X(5)=7.0459054023 9300 X(6) = 10.75851601019400 X(7) = 15.74067864129500 X(8)=22.8631317368 W(1)=3.69188589342*.1**1 9600 9700 W(2)=4.18786780814*.1**1 9800 W(3)=1.75794986637*.1**1W(4)=3.33434922612*.1**2 9900 W(5)=2.79453623523*.1**3 10000 10100 $W(6) = 9.07650877336 \times 1 \times 5$ W(7)=8.48574671627*.1**7 10200 W(8)=1.04800117487*.1**9 10300 3000 NN=NN+1 10400 С 10500 10600 STOT(1)=0.10700 GTOT(1)=0.10800 S=NN*0.1 EROLD=1000000 10900 11000 С new parameter S; new curve 11100 SAREA=S/PI 11200 WRITE (2,113) 11300 WRITE (2,2010) NN,S,SAREA 11400 GTNEW=S 11500 STOT(NN+1) = S11600 С 11700 DO 400 III=1,N 11800 IREAL=III*1. 11900 R(III)=IREAL/NREAL 400 12000 G(III)=SAREA

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12100	С	
12200		KK=0
12300	1000	KK=KK+1
12400		ER=0.
12500	C	NEW ITERATION
12600		GT=GTNEW
12700		DO 600 I=1,N
12800	С	For every sample point
12900		IREAL=I*1.
13000		SUM=0.
13100		DO 700 II=1,8
13200	С	summing Gauss-Laguerre
13300		IMAGE=0.
13400		DO 800 III=1,N-1
13500	С	Calculate image function point
13600		IIIRL=III*1.
13700		ARG=-1.*Z * ((IREAL/IIIRL)**4) * X(II)
13800		IMAGE=IMAGE+2.*PI*IIIRL*G(III)*(EXP(ARG)-1.)
13900	800	CONTINUE
14000		ARG=-1.*Z*((IREAL/NREAL)**4)*X(II)
14100		IMAGE=IMAGE+PI*G(N)*(EXP(ARG)-1.)
14200		IMAGE=IMAGE/ (NREAL**2)
14300		TERM= W(II) * EXP(IMAGE)
14400		SUM= SUM + TERM
14500	700	CONTINUE
14600		GNW(I)= SAREA / SUM
14700	600	CONTINUE
14800	С	
14900	С	
15000	C*****	***************************************
15100	С	
15200	C****	total traffic and convergence control **************
15300	С	
15400		GTNEW=0.
15500		DO 950 II=1,N-1
15600		IREAL=II * 1.
15700		GTNEW=GTNEW+ (IREAL * GNW(II) / NREAL)
15800		ER = ER + ABS((GNW(II) - G(II))/G(II))
15900	950	G(II) = GNW(II)
16000		G(N) = GNW(N)
16100		GTNEW=2.*PI*GTNEW /NREAL
16200		GTNEW=GTNEW+P1*GNW(N)/(NREAL)
16300		GTOT(NN+1)=GTNEW
16400		ER=ER*100./NREAL
16500		IF(PR.EQ.1) WRITE(6,2005) KK,ER,GINEW
16600		WRITE(2,2005) KK,ER,GINEW
16700	C	test on divergence:
16800		IF(ER.GT.EROLD) GOTO 3100
16900	_	EROLD≓ER
17000	C	
17100	С	
1/200	~	LF(KK.LT.M.AND.EK.GT.U.001.AND.GINEW.LT.30)GUIU 1000
1/300	C	make another iteration
17400		$\frac{1}{100} \text{ (K.EU.M) WALLE (2,2000)}$
17500		1F(PK.EQ.1) WELLE(0,2001)
1/600	c	WK1TE(2,2001)
1//00	C	
17800	C	**************** ONIGNI OF KEROPID Provide Course
17900	U acco	BODWAW(3V TE 1V E10 5 1V /E10 5)
18000	2000	FUKMAI(2X, 10, 1X, FIU, 0, 1X, 4FIU, 0)
19300	2001	$\frac{1}{1000} = \frac{1}{1000} = \frac{1}{1000} = \frac{1}{1000} = \frac{1}{1000} = \frac{1}{1000} = \frac{1}{1000} = \frac{1}{10000} = \frac{1}{10000} = \frac{1}{100000} = \frac{1}{10000000000000000000000000000000000$
10200	2005	$\mathbf{FORMAT}(\mathbf{I} \cup \mathbf{I} \cup \mathbf{I}$

FORMAT(" MAX NUMBER OF ITERATIONS !" 18300 2006 FORMAT("*** plot ",I3," with total traffic S= ", F6.3,", distributed ", F6.4," per area ***") 18400 2010 18500 Ş. 2020 FORMAT(" ! Exponent overflow ! end of calculation") 18600 18700 С 18800 С 18900 CALL CURVDZ(90,0,0,15,15,1,N,R,G, 19000 \$ 10,0,1,10,0,1,.FALSE.,.FALSE.) 19100 С 19200 IF(NN.LT.10.AND.GTNEW.LT.30.) GOTO 3000 19300 С make another plot with higher traffic load 19400 С C******* 19500 the total traffic S-G curve ***************** 19600 С 19700 3100 IF (INT.GT.30) WRITE (2,2020) 19800 Ç 19900 CALL PNTSDZ(90,15,0,25,15,1,NN,STOT,GTOT, 20000 \$ 10,0.,1.,10,0.,2., .FALSE.,.FALSE.) С 20100 20200 С C****** 20300 20400 С 20500 CALL NEWOBJ(OBJ3) С 20600 20700 С 20800 С 20900 DO 8888 II=1,21 21000 GT=(II-1.)/10. 21100 GAR(II)=2.5+5* GT 21200 GAR(21+11)=12.5-5.*GT 21300 PURE(II)=17.5+5.* GT*EXP(-1.*GT) 21400 PURE(21+II)=17.5 21500 PERF(II)=22.5 - 5.*EXP(-1.*GT) 21600 PERF(21+11)=22.5 21700 8888 CONTINUE 21800 С 21900 ABX(1)=17.5 22000 ABY(1) = 2.522100 ABX(2)=22.5 22200 ABY(2) = 7.522300 ABX(3) = 22.522400 ABY(3) = 2.522500 С 22600 A=10.*ALOG10(Z)22700 CALL FILPOL(OBJ3,1,42, PURE, GAR, "A", 30, 0.25) 22800 CALL FILPOL(OBJ3,1,42,RING,GAR,"A",0.,0.35) 22900 CALL FILPOL(OBJ3, 1, 32, PERF, GAR, "D", 30, 0, 25) 23000 CALL FILPOL(OBJ3,1,3,ABX,ABY,"B",30,0.25) 23100 CALL POLYGN(OBJ3,1,42,PURE,GAR,1) 23200 CALL POLYGN(OBJ3,1,21,PERF,GAR,1) 23300 CALL POLYGN(OBJ3, 1, 2, ABX, ABY, 1) CALL COTEXT(OBJ3, 16.3, 2.5, 90, .35, 5, 23400 23500 Ş "Total traffic offered G") 23600 CALL COTEXT(OBJ3,2.5,1.,0.,.34,5, 23700 \$ "Normalised distance of terminal") 23800 CALL COTEXT(OBJ3,1, 2.4,90,.34,5, 23900 \$ "Offered traffic per norm. area") 24000 CALL COTEXT(OBJ3, 17.9, 1., 0,.35, 5, 24100 \$ "Throughput S") 24200 CALL COTEXT(OBJ3,.5,15 ,0,1.1,0, \$ 24300 "SYNTHESIS") 24400 CALL COTEXT(OBJ3, 525, 15, 0, 1.1, 0,

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24500	\$	"SYNTHESIS")
24600		CALL COTEXT(OBJ3,.5,14.4 ,0,.25,0,
24700	\$	"Traffic G(r) to be offered to give a homogeneous")
24800		CALL COTEXT(0BJ3,.5,14.0 ,0,.25,0,
24900	\$	"spatial distribution of the traffic troughput S(r)")
25000		CALL COTEXT(OBJ3, 14.5, 14.7, 0, .40, 5,
25100	\$	"coherent addition")
25200		CALL COTEXT(OBJ3,14.5,14.0 ,0,.27,5,
25300	\$	"receiver threshold: (dB)")
25400		CALL CONNUM(OBJ3,19.6,14,0,0.27,5,"F4.1",DBLE(Z))
25500		CALL CONNUM(OBJ3,21.4,14,0,0.27,5,"F4.1",DBLE(A))
25600		CALL DRAWOB(90,0BJ3,0,0,25,20)
25700		CALL DISPOB(OBJ3)
25800	С	
25900		CLOSE(2,DISP=CRUNCH)
26000		STOP
26100		END
26200	C*****	***************************************

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. . RESULTS DATE & TIME PRINTED: TUESDAY, NOVEMBER 18, 1986 @ 11:04:48.

5800

iteration 8

dev

0.011 %

Gtot=

0.941102

100 Z0= 1.00000 K= 10 M.N= 30 30 200 300 Fading and power add model 400 *** plot 1 with traffic S= 0.100, i.e. 0.0318 per area 500 iteration 1 dev 3.464 % Gtot≖ 0.100272 600 0.130 % iteration 2 dev Gtot= 0.105167 700 0.005 % iteration 3 dev Gtot= 0.105373 800 0.000 % iteration 4 dev Gtot= 0.105381 900 1000 Fading and power add model 1100 *** plot 2 with traffic S= 0.200, i.e. 0.0637 per area 1200 iteration 1 7.120 % dev Gtot= 0.201133 1300 iteration 2 dev 0.535 % Gtot= 0.221372 1400 iteration 3 9.044 % 0.223190 dev Gtot≖ 1500 iteration 4 dev 0.004 % Gtot= 0.223344 1600 0.000 % iteration 5 dev Gtot= 0.223357 1700 1800 Fading and power add model 1900 *** plot 3 with traffic S= 0.300, i.e. 0.0955 per area 2000 iteration 1 dev 10.980 % Gtot≖ 9.392656 2100 iteration 2 dev 1.245 % Gtot= 0.349776 2200 iteration 3 dev 9.164 % Gtot= 0.356560 2300 0.022 % iteration 4 dev Gtot= 0.357489 2400 0.003 % iteration 5 dev **0.**357614 Gtot= 2509 0.000 % iteration 6 dev 0.357631 Gtot= 2600 2700 Fading and power add model *** plot 2800 0.400, 1.e. 0.1273 per area 4 with traffic S= 2900 iteration 15.056 % 1 dev Gtot= 0.404919 3000 iteration 2 2.297 % 0.491695 dev Gtot= 3100 0.427 % iteration 3 dev Gtot= 0.509563 3200 0.083 % iteration 4 dev Gtot= 0.513103 3300 0.016 % iteration -5 dev Gtot= 0.513797 3400 iteration 6 dev 0.003 % Gtot= 0.513932 3500 iteration 7 dev 0.001 % Gtot= 0.513959 3600 3700 Fading and power add model 3800 *** plot 5 with traffic S= 0.500, i.e. 0.1592 per area 3900 19.362 % iteration 1 dev Gtot≖ 0.508013 4000 iteration 2 dev 3.738 % Gtot= 0.648636 4100 iteration 3 dev 0.925 % Gtot= 0.687639 4200 iteration 4 dev 0.244 % Gtot= 0.698231 4300 iteration 5 dev 0.065 % Gtot= 0.701092 4400 iteration dev 0.018 % 6 Gtot= 0.701863 4500 iteration 7 dev 0.005 % Gtot= 0.702072 4699 iteration 8 dev 0.001 % Gtot= 9.792128 4700 9 iteration dev 0.000 % Gtot= 0.702143 4800 4900 Fading and power add model *** plot 5000 6 with traffic S= 0.600, i.e. 0.1910 per area 5100 iteration dev 23.913 % 1 Gtot= 9.612034 5200 iteration 2 dev 5.629 % Gtot= 0.822356 5300 iteration 3 dev 1.786 % Gtot= 0.898176 5400 iteration 4 0.623 % dev Gtot= 0.925624 5500 iteration 5 0.224 % dev Gtot= **9.935621** 5600 iteration 0.082 % 6 dev Gtot= **9.**939274 57**69** 7 iteration 0.030 % dev Gtot= 0.940612

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5900 iteration 9 0.004 % dev Gtot= 0.941281 6000 iteration 10 0.001 % 0.941347 dev Gtot= 6100 iteration 11 0.001 % 9.941371 dev Gtot= 6200 6300 Fading and power add model 6400 *** plot 7 with traffic S= 0.700, i.e. 0.2228 per area 6500 1 iteration dev 28.724 % Gtot= 0.717092 6600 iteration 2 dev 8.949 % Gtot= 1.014928 6700 3 3.203 % Gtot= iteration dev 1.151445 6800 dev 1.455 % Gtot= iteration 4 1.216557 6900 iteration - 5 dev 0.701 % Gtot= 1.248495 7000 0.347 % iteration 6 dev Gtot= 1.264422 7100 7 iteration dev 0.174 % Gtot= 1.272434 7200 iteration 8 dev 0.088 % Gtot= 1.276483 7300 iteration 9 0.844 % 1.278535 Gtot= dev 7400 iteration 10 0.022 % Gtot= 1.279575 dev 7500 iteration 11 0.011 % dev Gtot≖ 1.280103 7609 iteration 12 dev 0.006 % Gtot= 1.280371 7700 iteration 13 dev 0.003 % Gtot= 1.280507 7800 iteration 14 0.001 % Gtot= 1.280576 dev 7900 iteration 15 0.001 % Gtot= 1.289611 dev 8000 8100 Fading and power add model 8200 0.800, i.e. 0.2546 per area *** plot 8 with traffic S= 8300 iteration 1 dev 33.812 % Gtot= 0.823308 8400 iteration 2 dev 11.100 % Gtot= 1.228858 8500 5.471 % 3 Gtot= iteration dev 1.462178 8600 iteration 4 dev 3.240 % Gtot= 1.608971 8700 2.122 % Gtot= 1.707961 iteration 5 dev 8800 iteration 6 dev 1.479 % Gtot= 1.778146 8900 7 1.075 % iteration dev Gtot= 1.829732 9000 iteration 8 Gtot= **9.805 %** dev. 1.868661 9100 iteration 9 0.616 % Gtot= dev 1.898626 9200 6.479 % Gtot= 1.922042 iteration 10 dev 9300 iteration 11 dev 9.378 % Gtot≠ 1.940557 9400 iteration 12 0.301 % Gtot= 1.955334 dev 9500 iteration 13 0.241 % Gtot= dev 1.967214 9600 iteration 14 0.195 % Gtot= dev 1,976822 9700 0.158 % Gtot= 1.984629 iteration 15 dev 9800 0.129 % iteration 16 dev Gtot≕ 1.990998 9900 iteration 17 0.105 % Gtot≖ 1.996210 dev 0.086 % Gtot= 10000 iteration 18 2.000486 dev iteration 19 10100 0.071 % Gtot= 2.004002 dev 0.058 % Gtot= 10200 iteration 20 dev 2.006898 iteration 21 10300 dev 0.048 % Gtot= 2.009286 10400 iteration 22 dev 0.040 % Gtot= 2.011258 0.033 % Gtot= 10500 iteration 23 dev 2.012888 10600 iteration 24 dev 0.027 % Gtot= 2.014237 0.023 % Gtot= 2.015353 10700 iteration 25 dev iteration 26 0.019 % Gtot≠ 2.016277 10800 dev 10900 iteration 27 dev 0.015 % Gtot≖ 2.017043 0.013 % Gtot= 2.017678 11000 iteration 28 dev 0.011 % Gtot= 11100 iteration 29 dev 2.018205 0.009 % Gtot= 2.018642 11200 iteration 30 dev 11300 MAX NUMBER OF ITERATIONS ! 11400 11500 Fading and power add model 11600 *** plot 9 with traffic S= 0.900, i.e. 0.2865 per area 39.195 % Gtot= 0.930813 11700 iteration 1 dev 14.917 % 2 Gtot= 1.467247 11800 iteration dev iteration 3 9.076 % Gtot= 1.852439 11900 dev 12000 iteration 4 dev 7.119 % Gtot= 2,177232

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12100 iteration 5 dev 2.495494 6.689 % Gtot= 12200 iteration 6 dev 7.366 % Gtot= 2.856995 **** 12300 12490 Critical surface model 12500 *** plot 1 with traffic S= 0.100, i.e. 0.0318 per area 12600 iteration 1 dev 3.263 % Gtot= 0.100351 12700 iteration 2 dev 0.094 % Gtot= 0.105196 iteration 3 12800 0.002 % dev Gtot= 0.105363 12900 iteration 4 dev 0.000 % Gtot= 0.105367 13000 13100 Critical surface model 13200 *** plot 2 with traffic S= 0.200, i.e. 0.0637 per area 13300 iteration 1 dev 6.722 % Gtot= 0.201476 13400 iteration 2 0.388 % dev Gtot= 0.221605 13500 iteration 3 dev 0.020 % Gtot= 0.223094 13600 iteration 4 dev 6.001 % Gtot= 0.223176 13700 13800 Critical surface model *** plot 13900 3 with traffic S= 0.300, i.e. 0.0955 per area 14000 iteration 1 dev 10.393 % Gtot= 9.303499 14100 iteration 2 dev 0.900 % Gtot= 0.350614 14200 iteration 3 0.073 % dev Gtot= 9.356241 14300 iteration 4 0.005 % dev Gtot= 0.356745 14400 iteration 5 dev 0.000 % Gtot= 0.356781 14500 14600 Critical surface model 14700 *** plot 4 with traffic S= 0.400, i.e. 0.1273 per area 14800 iteration 1 dev 14.290 % Gtot= 0.406558 14900 dev iteration 2 1.658 % Gtot= 0.493865 15000 iteration 3 dev 0.189 % Gtot= 0.508914 15100 iteration 4 0.018 % dev Gtot= 9.510872 15200 iteration 5 dev 0.002 % Gtot= 0.511073 15300 iteration 6 0.000 % dev Gtot= 0.511091 15400 15500 Critical surface model 15609 *** plot 5 with traffic S= 0.500, i.e. 0.1592 per area 15700 18.430 % Gtot= iteration 1 dev 0.510812 iteration 2 15800 dev 2.694 % Gtot= 0.653347 15900 0.406 % iteration 3 dev Gtot= 0.686791 16000 0.053 % iteration 4 dev Gtot= 0.692798 16109 iteration 5 9.006 % dev Gtot= 0.693650 16200 0.001 % iteration 6 dev Gtot= 0.693750 16300 16400 Critical surface model *** plot 16500 6 with traffic S= 0.600, i.e. 0.1910 per area 16600 iteration 1 dev 22.831 % Gtot= 0.616442 16700 iteration 2 4.054 % dev Gtot= 9.831532 16800 iteration 3 dev **0.**778 % Gtot= 0.897994 16900 iteration 4 **9.**134 % dev Gtot= 0.914074 17000 iteration 5 0.020 % dev Gtot= 0.917151 17100 iteration 6 0.003 % dev Gtot= 9.917634 17260 iteration 7 0.000 % dev Gtot= 0.917699 17300 17400 Critical surface model 17500 *** plot 7 with traffic S= 9.799, i.e. 9.2228 per area 17600 27.512 % Gtot= iteration 1 dev 0.723654 5.797 % 17700 iteration 2 dev Gtot= 1.031599 17800 3 1.382 % iteration dev Gtot= 1.154696 17900 **0.30**6 % iteration 4 dev Gtot= 1,194556 18000 iteration 5 dev 0.060 % Gtot= 1.204865 18100 iteration 6 dev 0.010 % Gtot= 1.207048 0.002 % 18200 iteration 7 dev Gtot= 1.207440

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18400 Critical surface model 18500 *** plot 8 with traffic S= 0.800, i.e. 0.2546 per area 18600 32.494 % 0.832681 Gtot= 1 dev 18700 iteration 1.257793 8.003 % Gtot= 18800 iteration 2 dev 3 dev 2.339 % Gtot= 1.476384 18900 iteration 0.663 % 1.572337 iteration dev Gtot= 19000 4 0.170 % 1.606849 5 Gtot= dev 19100 iteration 0.039 % 1.617073 Gtot= 6 dev 19200 iteration 0.008 % Gtot= 1.619635 19300 7 dev iteration 1.620195 0.001 % Gtot= 19400 iteration 8 dev 0.000 % Gtot= 1.620305 iteration 9 dev 19590 19690 Critical surface model 19700 9 with traffic S= 0.990, i.e. 0.2865 per area *** plot 19800 0.943788 iteration l dev 37.799 % Gtot= 19900 10.778 % Gtot= 1.516050 2 dev 20000 iteration 3.847 % Gtot= 1.897526 3 dev 20100 iteration 1.406 % 4 Gtot= 2.134865 dev 20200 iteration 0.490 % 2.264832 Gtot= 20300 iteration 5 dev 2.326285 0.158 % 20400 iteration 6 dev Gtot= iteration 7 0.046 % Gtot= 2.351645 dev 20500 2.361034 0.012 % Gtot= 8 dev 20600 iteration 0.003 % 2.364253 Gtot= iteration 9 dev 20700 0.001 % Gtot= 2.365305 iteration 10 dev 20800 20900 Critical surface model 21000 *** plot 10 with traffic S= 0.000, i.e. 0.3183 per area 21100 43.452 % Gtot= 1.057276 dev iteration 1 21200 1.815075 14.270 % Gtot= 21300 iteration 2 dev 6.255 % Gtot= 2.488961 iteration 3 dev 21400 3.040 % 3.164621 Gtot= 21590 iteration 4 dev 5 1.546 % Gtot= 3.967802 iteration dev 21600 0.808 X 5.354789 Gtot= 21700 iteration 6 dev **0.**433 % Gtot= 11.621261 7 dev 21800 iteration Gtot= ******** 0.239 % 8 dev 21900 iteration end of calculation 22000 ! Exponent overflow !

J.

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18300

DATE & TIME PRINTED: TUESDAY, NOVEMBER 18, 1986 @ 11:17:27. 100 ZØ= 10 M,N= 1.00000 K= 30 30 200 300 COHERENT ADDITION model 409 *** plot l with traffic S= 0.100, i.e. 0.0318 per area 500 iteration dev 3.439 % 1 Gtot= 0.105108 600 iteration 2 dev 0.125 % Gtot= 0.105319 700 0.005 % iteration 3 dev Gtot= 0.105327 800 9.909 % iteration 4 dev Gtot= 0.105327 900 COHERENT ADDITION 1000 model 1100 *** plot 2 with traffic S= 0.200, i.e. 0.0637 per area 1200 7.046 % Gtot= iteration 1 dev 0.220999 1300 iteration 2 0.509 % dev Gtot= 0.222827 1400 iteration 3 dev 0.040 % Gtot= 0.222974 1500 0.003 % iteration 4 dev Gtot= 0.222986 1600 iteration 5 dev 0.000 % Gtot≠ 0.222987 1700 1800 COHERENT ADDITION model 1990 *** plot 3 with traffic S= 0.300, i.e. 0.0955 per area 2000 iteration 1 dev 10.828 % Gtot= 348569 2100 iteration 2 dev 1.169 % Gtot= 0.355270 2200 iteration 3 dev 0.144 % Gtot= **0.356130** 2300 iteration 4 dev 0.018 % Gtot= 0.356238 2400 iteration 0.002 % 5 dev Gtot= 0.356252 2500 iteration 6 dev 0.000 % Gtot= 9.356254 2600 2700 COHERENT ADDITION model 2800 *** plot 4 with traffic S= 0.400, i.e. 0.1273 per area 2900 iteration 1 dev 14.795 % Gtot= **0.**488777 3000 iteration 2 dev 2.123 % Gtot= 0.506078 3100 iteration 3 0.363 % dev Gtot= 0.509229 3200 iteration 4 0.064 % dev Gtot= 0.509791 3300 iteration 5 dev 0.011 % Gtot= 0.509891 3400 iteration 6 dev 0.002 % Gtot= 0.509909 3500 iteration 0.000 % 7 dev Gtot= 0.599912 3600 3700 COHERENT ADDITION model *** plot 3800 5 with traffic S= 0.590, i.e. 0.1592 per area 3900 iteration 1 dev 18.956 % Gtot= 0.642650 4000 iteration 2 dev 3.396 % Gtot= 9.679548 4100 iteration 3 0.757 % dev Gtot= 0.688541 4200 0.177 % iteration 4 dev Gtot= 690693 4300 iteration 5 dev 0.042 % Gtot= 0.691205 4400 iteration 6 dev 0.010 % Gtot= 0.691327 4 500 iteration 7 dev 0.002 % Gtot= •.691356 4600 iteration 8 9.801 % dev Gtot= **0.**691362 4700 4800 COHERENT ADDITION model 4900 *** plot 6 with traffic S= 0.600, i.e. 0.1910 per area 5000 iteration 1 dev 23.319 % Gtot≖ 9.811287 5100 iteration 2 5.019 % dev Gtot= 0.881096 520**0** iteration 3 1.398 % dev Gtot≠ 0.903097 5300 iteration 4 0.418 % dev Gtot= 0.909928 5400 iteration 5 dev 0.128 % Gtot= 0.912041 5500 0.039 % iteration 6 dev Gtot= 0.912694 5600 iteration - 7 dev 0.012 % Gtot≖ **0.**912896 5700 iteration 8

dev

dev

9

iteration

5800

0.004 %

0.001 %

Gtot=

Gtot=

0.912958

0.912977

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RESULTS

5900	iteration	10 de	v 0 .000	%	Gtot=	0.912983		
6000								
61 09	COHERENT ADD	DITION	model					
620 0	*** plot 7	/ with	traffic S=	•	0.700,	i.e. 0.2228	per	area
63 00	iteration	l de	v 27.895	%	Gtot=	0.995863		
64 00	iteration	2 de	v 7 .0 26	%	Gtot≕	1.117571		
6500	iteration	3 de	v 2.378	%	Gtot=	1,166145		
6600	iteration	4 de	v 0.888	%	Gtot=	1.185379		
6700	iteration	5 de	v 0.344	%	Gtot=	1.192990		
68 90	iteration	6 de	v 0.135	%	Gtot=	1.196003		
6900	iteration	7 de	v 0.0 53	2	Gtot=	1.197196		
7000	iteration	8 de	v 0.021	%	Gtot≖	1.197669		
7100	iteration	9 de	v 0.00 8	%	Gtot=	1.197856		
7200	iteration	10 de	v 9.00 3	%	Gtot=	1.197930		
7300	iteration	ll de	v 0.001	%	Gtot=	1.197960		
7400	iteration	12 de	v 0.991	%	Gtot=	1.197971		
7500								
7600	COHERENT ADD	DITION	model					
7700	*** plot 8	s with	traffic S=	*	0.800,	i.e. 0.2546	per	area
7800	iteration	l de	v 32.695	%	Gtot=	1.197634		
7900	iteration	2 de	v 9.461	%	Gtot=	1.397677		
8000	iteration	3 de	v 3.813	%	Gtot=	1.497596		
8100	iteration	4 de	v 1.744	z	Gtot=	1.547551		
8200	iteration	5 de	v 0. 844	%	Gtot=	1.572799		
8300	iteration	6 de	v 0.419	7	Gtot≠	1.585591		
8400	iteration	7 de	v 0.211	%	Gtot=	1.592087		
8 500	iteration	8 de	v 0. 107	%	Gtot=	1.595391		
8600	iteration	9 de	v 0.0 54	%	Gtot≖	1.597072		
8790	iteration	10 de	v 0.027	7	Gtot=	1.597928		
8800	iteration	ll de	v 0.914	%	Gtot=	1.598364		
8900	iteration	12 de	V 0.007	76	Gtot=	1.598586		
9000	iteration	13 de	V 0.0 94	76	Gtot≖	1.598699		
9100	iteration	14 de	V 0.002	٦ ~	Gtot=	1.598/56		
9200	iteration	15 de	v 9.6 91	76	Gtot=	1.598785		
9300								
9499	COHERENT ADI	DITION	model	_	0 000	4 - 0 1965		
9500	from plot s	יע ל WICE ל	37 730	= 97	0.900,	1.e. V.2003	per	area
9700	iteration	2 40	v J/•/20	љ 9	GLOL=	1.41/742		
9800	iteration	3 46	v 12+3/4	2	Gtot=	1 927448		
9980	iteration	ah A	v 3.237	ĩ	Gtot=	2.051208		
10000	iteration	S de	v 1.941	ĩ	Gtot	2.131409		
10100	iteration	6 de	v 1.218	ĩ	Gtot#	2,184148		
10200	iteration	7 de	v 9. 785	z	Gtot=	2,219172		
10300	iteration	8 de	v 9.515	7	Gtot=	2.242584		
10400	iteration	9 de	v 0. 341	z	Gtot=	2.258304		
10500	iteration	10 de	v 9 .228	Ľ	Gtot=	2.268889		
10600	iteration	11 de	v 9. 153	7	Gtot=	2.276031		
10700	iteration	12 de	v 9. 103	7	Gtot=	2.289856		
19899	iteration	13 de	v 0.069	%	Gtot=	2.284119		
10900	iteration	14 de	v 0.047	2	Gtot=	2.286327		
11000	iteration	15 de	v 0.0 32	%	Gtot≖	2.287821		
11100	iteration	16 de	v 0.021	Х	Gtot≖	2.288833		
11200	iteration	17 de	v 0.015	7	Gtot=	2.289519		
11300	iteration	18 de	v 0.010	z	Gtot=	2.289983		
11400	iteration	19 de	v 9.99 7	%	Gtot=	2.290297		
11500	iteration	20 de	v 0.005	%	Gtot=	2.290510		
116 00	iteration	21 de	v 0 .90 3	%	Gtot=	2.290654		
11700	iteration	22 de	v 9.00 2	%	Gtot=	2.290752		
11800	iteration	23 de	v 0.001	%	Gtot=	2.290818		
11900	iteration	24 de	v 0.001	%	Gtot=	2.290863		
1 2000								

12000

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12100	COHERENT ADD	LTI	ON	mode1				
12200	*** plot 10	W	ith	traffic S	=	1.000.	i.e. 0.3183	per area
12300	iteration	1	dev	43.006	%	Gtot=	1.658219	F
12400	iteration	2	dev	15.825	2	Gtot=	2.136255	
12500	iteration	3	dev	8.674	%	Gtot=	2.593141	
12690	iteration	4	dev	5.748	z	Gtot=	2.800184	
12700	iteration	5	dev	4.254	%	Gtot=	3.052267	
12800	iteration	6	dev	3,387	%	Gtot=	3.274786	
12900	iteration	7	dev	2.844	%	Gtot=	3.477861	
13990	iteration	8	dev	2.489	%	Gtot=	3.668657	
13100	iteration	9	dev	2.255	2	Gtot≖	3.852674	
13200	iteration]	10	dev	2.105	z	Gtot≖	4.034522	
13300	iteration]	1	dev	2.018	2	Gtot=	4.218452	
13400	iteration 1	2	dev	1.983	%	Gtot=	4.498773	
13500	iteration 1	3	dev	1.994	%	Gtot=	4.610267	

Appendix C ALTERNATIVE DERIVATIONS OF EXPRESSIONS OBTAINED DURING THE PREPARATION OF THIS THESIS

Although not of great additional value, appendix C has a historical value to the author as it describes the (roundabout) way the results of this thesis have been derived.

The image-function approach to find spatial distributions stems from an attempt to formally prove that any spatial distribution of traffic yields a higher throughput than a δ -distribution, for which all packets have the same area mean power. This proof was intended to give the observation that increasing the differences in received packet power increases capacity of the multiple access channel a more formal basis. A proof was not found, but it soon appeared that Laplace transformation provides a very useful method to analyse the spatial distribution of traffic.

One of the first results was the derivation of the probability of loss $F_{z,n}$ in the coherent case, later followed by an analogous expression for $I_{z,n}$. Both original calculations are in appendix C. They start off with expressions used by Arnbak and Van Blitterswijk in [1]. Their model of propagation, spatial traffic distribution and interference signal addition plays a key role in this thesis. The ring and quasi-constant distributions described have been used as verification of equations derived in this paper.

The neat form of the coherent analysis equation giving the relation between images of traffic offered and throughput was surprising. However, despite many efforts to solve the equation, general solutions have not been found. Professor R. Prasad proposed the Gauss-Laguerre numerical integration method which can be used for analysis (find $S(\rho)$, given $G(\rho)$). Eventually its possibility to support iterative computing for synthesis was recognised.

With coherent addition, simple analytic solutions are not likely to be found in both analysis and synthesis, as even simple examples usually result in non-standard integrals. It must, however, be said that a lot of time was lost in trying to solve integrals having a singularity in the point v=0. Only after comparing Laplace transforms with characteristic functions, the background of this problem was understood.

Compared with coherent addition, the incoherent case was more straightforward to derive and image functions could easily be removed in the results. Many examples have been included.

The very neat universal expression found for the conditional probability of loss $I_{z,n}$, containing an image function sampled in a point $v=Z_0\rho^\beta$, explained the succes of using image functions. These appear to be useful to resolve the problem of convolutions in the power domain. The mathematical way of modelling Rayleigh fading by an exponential pdf yields equations which can be transformed quite easily.

Only a few weeks before finishing this thesis, the asymptotic expansion for high traffic loads was found. The derivation has been carried out, but application of the results is left as a recommendation.

In the following sections the relation with [1] is indicated as the expressions were originally derived from [1,(28)] and [1,(40)].

C.1 Incoherent addition

I (ρ) can be expressed in terms of the image function $\phi(v)$ by Laplace transformation from the w to v domain. The variable z will not be transformed. We start off with the relation (4.47) describing the joint interference power pdf and its image

$$\phi^{n}(v) \quad \leftarrow^{L}_{I}^{I} \quad \rightarrow \quad f^{i}_{P_{n}}(w). \tag{C.1}$$

Translation by $z\rho^{\beta}$ in the v domain gives

$$\phi^{n}(v+z\rho^{\beta}) \leftrightarrow^{L_{I}^{I}} \rightarrow f_{p_{n}}^{i}(w) e^{-zw\rho^{\beta}}.$$
 (C.2)

Multiplication by w of the original, corresponds to a $\left(\frac{-d}{dv}\right)$ -differentiation of the image (A.1.5)

$$-\frac{d}{dv}\rho^{\beta}\phi^{n}(v+z\rho^{\beta}) + \stackrel{L^{I}}{I} \rightarrow w\rho^{\beta}f^{i}_{p}(w)e^{-zw\rho^{\beta}}$$
(C.3)

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$$-n\rho^{\beta}\phi^{n-1}(v+z\rho^{\beta})\phi'(v+z\rho^{\beta}) \leftarrow^{L}I \rightarrow w\rho^{\beta}f^{i}_{P_{n}}(w)e^{-zw\rho^{\beta}}$$
(C.4)

Integration over z of both original and image gives

$$-\phi^{n}(v+z\rho^{\beta}) \begin{vmatrix} z_{0} \\ z=0 \end{vmatrix} + \frac{L}{2} + \int_{0}^{2} dz \ w\rho^{\beta} f_{p}^{i}(w) e^{-zw\rho^{\beta}} (C.5)$$

Integration of the original from zero to infinity over w now yields $I_{z,n}(\rho)$, as this integration equals the definition (4.3) of Laplace transforms for v=0

$$I_{z,n}(\rho) = 1 - \phi^n (Z_0 \rho^\beta), \qquad \text{which equals (5.1)}.$$

C.2 Coherent addition

We assume coherent addition of interfering packets. This means that the random phase terms of the signals hardly vary during the capture time t_w , so wideband phase modulation or large Doppler frequency shifts are not incorporated in the model. As Arnbak and van Blitterswijk have shown, for a channel with uncorrelated Rayleigh fading for all packets, the conditional probability of loss for a packet in the presence of n other packets is [1(28)]

$$\mathbf{F} = \operatorname{Prob}\{\operatorname{loss}|n, Z_0\} = \iint_{00}^{\infty} f_{\overline{p}}(\overline{p}_n) f_{\overline{p}}(\overline{p}_s) \frac{Z_0 \overline{p}_n}{Z_0 \overline{p}_n + \overline{p}_s} d\overline{p}_n d\overline{p}_s \cdot (C.6)$$

Given a normalised receiver distance ρ at which the test packet is transmitted with n contenders in the same timeslot, $I_{z,n}(\rho)$ gives the probability that the packet will not capture the common receiver, with threshold Z_0 . Equation [1,(40)] indicates that for a noiseless channel with uncorrelated Rayleigh fading for the n+1 packets, in the coherent case [1,(40)]

$$\operatorname{Prob}\{\operatorname{loss}|n, Z_0, \rho\} \stackrel{\Delta}{=} I_{Z, n}(\rho) = \int_{0}^{\infty} f_{\overline{P}_{n}}(\overline{p}_{n}) \frac{Z_{0}\overline{p}_{n}}{Z_{0}\overline{p}_{n} + \rho^{-\beta}} d\overline{p}_{n}. \quad (C.7)$$

We now concentrate on the calculation of $F_{z,n}$. The double integral in [1,(28)] equals a two-dimensional Laplace transform considered in the origin of the image variables (u,v)=(0,0). The L^{II} -image of the integrand can be written in terms of the image g(v) of the pdf of \tilde{P}_s . In the two-dimensional plane we consider operations imposed upon the Laplace pair

$$g^{n}(u) g(v) \leftarrow \overset{L^{II}}{I} \leftarrow f_{\overline{p}}(y) f_{\overline{p}}(x).$$
 (C.8)

Starting with scaling of the (u*x) variable pair

$$g^{n}(Z_{0}u)g(v) + \overset{L_{I}}{I} + \frac{1}{Z_{0}}f_{\overline{p}}(\frac{x}{Z_{0}})f_{\overline{p}}(y).$$
 (C.9)

Voelker and Doetsch [4,(46) at page 159] give the correspondence

$$\int_{u}^{\infty} g^{n}(Z_{0}\lambda)g(\nu+\lambda+u)d\lambda + \stackrel{L}{I}\stackrel{I}{I} \rightarrow \frac{1}{x+y}\frac{1}{Z_{0}}f_{\overline{P}}(\frac{x}{Z_{0}})f_{\overline{P}}(y). \quad (C.10)$$

Here x can again be scaled to $Z_0 x$

$$Z_{0}\int_{u/Z_{0}}^{\infty} g^{n}(Z_{0}\lambda)g(v+\lambda-\frac{u}{Z_{0}})d\lambda \quad \leftarrow^{L_{I}}I \rightarrow \qquad \frac{Z_{0}}{Z_{0}x+y}f_{\overline{P}}(x)f_{\overline{P}}(y). \quad (C.11)$$

A $\left(\frac{-\partial}{\partial u}\right)$ differentiation in the convergence area of the image corresponds to multiplication (A.1.5) by the variable x of the original. First we differentiate the lower limit of the integral; a second term is generated by differentiating the integrand itself.

$$-g^{n}(u)g(v) + \int_{u/Z_{0}}^{\infty} g^{n}(Z_{0}\lambda)g'(v+\lambda - \frac{u}{Z_{0}})d\lambda + L^{II}_{I} + \frac{Z_{0}x}{Z_{0}x+y}f_{p}f_{p}f_{p}s \cdot (C.12)$$

At this moment F equals the original integrated over the first quadrant. As can be seen from the definition of Laplace transformation, it also equals the image with (u,v)=(0,0)substituted. After applying (4.4) we find

$$\mathbf{F}_{z,n} = 1 + \int_{0}^{\infty} g^{n}(Z_{0}\lambda)g'(\lambda)d\lambda \qquad (C.13a)$$

or, after partial integration,

$$F_{z,n} = -nZ_0 \int_0^\infty g(\lambda)g'(Z_0\lambda)g^{n-1}(Z_0\lambda)d\lambda \qquad (C.13b)$$

From this equation it was first noted that the probability F of z.n a destroying collision, given a receiver threshold Z_0 and a number of n interferers, can be stated purely in terms of the Laplace transform g(.) of the mean packet power pdf f $_{\overline{\mathbf{p}}}$.

special case Z₀=1

For the receiver with perfect capture ($Z_0 = 1$), F_{Z_n} can be calculated quite easily.

$$F_{z,n} = -n \int_{0}^{\infty} g^{n}(\lambda)g'(\lambda)d\lambda = \frac{n}{n+1}$$
(C.14)

In this case F and therefore the average capture z_n probability are independent of the power classification of the individual transmitters, e.g. spatial distribution will not increase channel throughput. The average throughput of packets equals 1/n+1, which is just the probability for a test packet to be selected at random from a set with n other contenders.

With (C.13) we can find the total channel throughput S by using the series expansion of the exponential function after interchanging integration and summation.

$$S = G\left[1 - \sum_{n=1}^{\infty} R_n F_{z,n}\right] = -G e^{-G} \int_{0}^{\infty} g'(\lambda) \exp\{Gg(Z_0\lambda)\} d\lambda \qquad (C.15)$$

• Extreme of the throughput curve (channel capacity) The top of the throughput S(G) curve can be found from $\frac{dS}{dG} = e^{-G} \int_{0}^{\infty} g'(\lambda) \exp[Gg(Z_0\lambda)][G-1-Gg(Z_0\lambda)]d\lambda = 0 \quad (C.16)$ Attempts with examples have not led to an explicit expression for G_{top}.

C2.1.1 Mellin transforms

To consider alternative possibilities to evaluate the throughput equations, we now return to equation (4.56):

$$F_{z,n} = \int_{0}^{Z} \int_{0}^{\infty} f_{p_{s}}(zw) f_{p_{n}}^{a}(w) w dw \qquad (=4.56)$$

The Mellin transformation yields image functions defined as

$$M_{X}(p) \stackrel{\Delta}{=} \int_{0}^{\infty} x^{p-1} f(x) dx. \qquad (C.18)$$

Thus, if p a natural number and f(x) a pdf of a positive random variable, then

$$M_{\chi}(p+1) = \mu_{p}$$
 (C.19)

The integral over w of (4.56) can be written as a convolution [12, par.12 (37)], in the Mellin transform domain.

where M_{P_s} and M_{P_n} are the Mellin transforms of f_{P_s} resp. f_{P_n} .

Integrating the original, with upper limit Z_n gives the transform pair (from Z_n to p domain)

$$-\frac{1}{p} M_{p_{s}}^{(1+p)} M_{p_{n}}^{(1-p)} + F_{z,n}^{M} + F_{z,n}$$
(C.21)

C.2.2 Spatial distribution in the coherent case

For I (ρ) , an expression can be found, containing the Laplace transform $g^{n}(\cdot)$ of the pdf of \overline{P}_{n} . The aim of the next section is to start off with this $\begin{array}{c}I\\I\\I\\I\end{array}$ correspondence and again use mathematical operations upon the original pdf which lead to the integral $I_{z,n}(\rho)$ in [1,(40)].

First the variable x is to be scaled to x/Z_0

$$g^{n}(Z_{0}u)$$
 + L^{I} or II + $\frac{1}{Z_{0}}f_{\overline{P}}(\frac{x}{Z_{0}})$. (C.22)

The original can be translated over a distance $\rho^{-\beta}$. This correspondence can be derived from a $q=y-\rho^{-\beta}$ substitution of the dummy variable in definition (4.3). With this substitution the lower and upper limits are also translated, so the next correspondence is only valid for a two-sided transform where we integrate from -- to ...

$$\exp\{-\rho^{-\beta}u\}g^{n}(Z_{0}u) \qquad \leftarrow^{L}II \rightarrow \qquad \frac{1}{Z_{0}}f_{\overline{p}}(\frac{x-\rho^{-\beta}}{Z_{0}}). \qquad (C.23)$$

At this point we integrate the image

$$\int_{u}^{\infty} \exp\{-\rho^{-\beta}\lambda\} g^{n}(Z_{0}\lambda)d\lambda + \int_{u}^{I} II \rightarrow \frac{1}{Z_{0}x} f_{\tilde{P}_{n}}(\frac{x-\rho^{-\beta}}{Z_{0}}). \quad (C.24)$$

The denominator $x+\rho^{-\beta}$ appears after a translation over $(-\rho^{-\beta})$

As the pdf of $\overline{\mathbf{p}}_n$ is different from zero only for positive mean interference powers, the correspondence is again valid for both one- and two-sided transforms.

A $\left(-\frac{d}{dv}\right)$ differentiation of the image, using the product rule yields

$$e^{0}g^{n}(Z_{0}u) - \rho^{-\beta}\int_{u}^{\infty} e^{x}p\{\rho^{-\beta}(u-\lambda)\}g^{n}(Z_{0}\lambda)d\lambda \xrightarrow{L^{I}}_{\neq I}, II \rightarrow \frac{x/Z_{0}}{x+\rho^{-\beta}}f_{P_{n}}(\frac{x}{Z_{0}})$$

Now by rescaling the variable x, we recover the integrand of $I_{z,n}(\rho)$ according to [1,(40)]

$$g^{n}(u) = \rho^{-\beta} \int_{u/Z_{0}}^{\infty} \exp\{\rho^{-\beta}(\frac{u}{Z_{0}} - \lambda)g^{n}(Z_{0}\lambda)d\lambda \qquad \underset{i=1, II}{\overset{L}{\downarrow}}, II \neq \frac{Z_{0}x}{Z_{0}x + \rho^{-\beta}}f_{p}^{\overline{p}}(x)$$

Taking the value at u=0 of the image gives $I_{z,n}(\rho)$ of (C.7) after applying (4.4) and (4.6)

$$I_{z,n}(\rho) = 1 - \rho^{-\beta} \int_{0}^{\infty} \exp\{-\rho^{-\beta}\lambda\} g^{n}(Z_{0}\lambda) d\lambda \qquad (C.25)$$

For practical calculation, a more often convenient form is

÷ .

$$I_{z,n}(\rho) = 1 - \int_{0}^{\infty} e^{-\nu} g^{n}(Z_{0}\nu\rho^{\beta}) d\nu,$$
 (C.26)

where we have substituted $\lambda = v \rho^{\beta}$. This form can for instance be used with Gauss-Laguerre numerical integration.

Appendix D ANOTHER EXAMPLE OF A SPATIAL DISTRIBUTION

A study by Joanna Fronczak [17] is interesting because the differences in mean power introduced here by spatial distribution are the same as the power differences by Rayleigh fading in the ring model. See section 4.2.1 example 4. Furthermore, this distribution is a valuable addition to the sections 6.7 and 6.8. As distinct from the ring model, in this example packets are received with different mean power, but the moments of the pdf remain bounded. The area mean power has a pdf

$$f_{\vec{P}_{s}}(\vec{p}_{s}) = h \exp\{-h\vec{p}_{s}\}.$$
 (=4.16)

Using (1.14) this corresponds to

$$G(\rho) = \frac{G}{2\pi} \frac{4h}{\rho 6} \exp\{-h\rho^{-4}\}$$
 (=4.17)

As shown in example 3 of chapter 4, the Laplace image of the mean packet power pdf is

$$g(v) = \frac{h}{v+h}$$
(=4.18)

The unconditional mean received power μ_1 equals h. In section 4.1.3 we have chosen h=1.

D.1 Capture probability

We will initially discuss the throughput without assuming G to be large. $F_{2,n}$ can be found by using (4.57)

$$F_{z,n} = 1 - \frac{h^{n+2}}{Z_0^n} \int_0^\infty (x + \frac{h}{Z_0})^n (x + h)^2 dx$$

A Gaussian hypergeometric solution of this integral is given by [8, (3.197) on p 286]. We may calculate the total traffic throughput as given by (6.26)

S = G exp{-G}
$$\int_{0}^{\infty} \frac{h}{(\lambda+h)^2} \exp{\left\{\frac{hG}{Z_0\lambda+h}\right\}} d\lambda$$
.

We substitute the inverse function $x \stackrel{\Delta}{=} g^+(v)$:

$$S = Z_0 G \exp\{-G\} \int_0^1 \frac{\exp\{Gx\} dx}{(1+(Z_0-1)x)^2}$$
$$= -Ge^{-G} \int_0^1 e^{Gx} \frac{d}{dx} \left(\frac{1}{1+(Z_0-1)x}\right) \frac{Z_0 dx}{Z_0-1}$$

After partial integration and applying [8,(3.352.1)] we find

$$S = \frac{Z_0 G}{Z_0 - 1} \left[e^{-G} - \frac{1}{Z_0} + G \frac{\exp\{\frac{-GZ_0}{Z_0 - 1}\}}{Z_0 - 1} \left[E_1 \left(\frac{Z_0 G}{Z_0 - 1}\right) - E_1 \left(\frac{G}{Z_0 - 1}\right) \right] \right],$$

with the exponential integral $Ei(x) \stackrel{\Delta}{=} - \int_{e}^{\infty} e^{-t} t^{-1} dt$.

The total traffic throughput can be written as the series expansion

$$S = G - G^{2}Z_{0}\left[\frac{Z_{0}-1-\ln Z_{0}}{(Z_{0}-1)^{2}}\right] + G^{3}\left[\frac{Z_{0}}{Z_{0}-1}\right]\left(\frac{1}{2} - \frac{\ln Z_{0}-Z_{0}+1}{(Z_{0}-1)^{2}}\right) - \dots$$

The limit $S=1-e^{-G}$ can be derived by expansion of $ln\{l+(Z_0-1)\}$ or by using l'Hôpital's rule.

D.2 Conditional capture probability

The integral

$$I_{z,n}(\rho) = 1 - \int_{0}^{\infty} e^{-\lambda} h^{4} (Z_{0}\rho^{4}\lambda + h)^{-n} d\lambda$$

is solved by using [8,(3.353.2) on p311]:

$$\int_{0}^{\infty} \frac{e^{-x} dx}{\left(x + \frac{h}{Z_{0}\rho^{4}}\right)^{n}} = \frac{1}{(n-1)!} \int_{k=1}^{n-1} (k-1)! (-)^{n-k-1} \left(\frac{h}{Z_{0}\rho^{4}}\right)^{k} - \frac{(-)^{n-1}}{(n-1)!} e^{\frac{h}{Z_{0}\rho^{4}}} Ei\left(\frac{-h}{Z_{0}\rho^{4}}\right)$$

with n>2. With unity written as the n-th term of the summing we find

$$I_{z,n}(\rho) = \frac{h^{n}}{(n-1)!} \left[-\left(\frac{-1}{Z_{0}\rho^{4}}\right)^{n} \exp\left\{\frac{h}{Z_{0}\rho^{4}}\right\} \operatorname{Ei}\left\{\frac{-h}{Z_{0}\rho^{4}}\right\} + \sum_{k=1}^{n} (k-1)! \left(\frac{-1}{Z_{0}\rho^{4}}\right)^{n-k} h^{-k} \right]$$

which has been derived by Fronczak [17,(13)].

D.3 Spatial distribution of the traffic throughput

The throughput per normalised unit area is found directly from (6.3)

$$S(\rho) = Ge^{-G} e^{-h\rho^{-4}} \frac{2h}{\pi \rho^{10}} \int_{0}^{\infty} \exp\{-s\rho^{-4} + \frac{hG}{Z_0(s + \frac{h}{Z_0})}\} ds.$$

A closed-form solution has not been found.

Appendix E 📃

ASYMPTOTIC EXPANSION BY PARTIAL INTEGRATION FOR LAPLACE INTEGRALS

For ease of notation we write: $\xi_n^m \stackrel{\Delta}{=} \{g^{(n)}(\lambda+v)\}^m$ $\zeta_n^m \stackrel{\Delta}{=} \{g^{(n)}(Z_0\lambda)\}^m$ $\chi \stackrel{\Delta}{=} \exp\{Gg(Z_0\lambda) - G\}$

The coherent analysis equation (6.14) becomes

 $s(v) = \frac{-1}{Z_0} \int_{\lambda=0}^{\infty} \frac{\xi_1}{\zeta_1} d\chi.$

Three steps of partial integration yield

$$s(\mathbf{v}) = -\frac{\mathbf{x}}{\mathbf{z}_{0}} \frac{\xi_{1}}{\xi_{1}} \Big|_{0}^{\infty} + -\frac{1}{\mathbf{z}_{0}} \int_{0}^{\infty} \mathbf{x} \frac{d}{d\lambda} \frac{\xi_{1}}{\xi_{1}} d\lambda$$

$$= \frac{1}{\mathbf{z}_{0}} \frac{g'(\mathbf{v})}{g'(\mathbf{0})} + \int_{0}^{\infty} \frac{\xi_{2}\zeta_{1} - \mathbf{z}_{0}\xi_{1}\zeta_{2}}{\mathbf{G} \mathbf{z}_{0}^{2} \mathbf{\zeta}_{1}^{2}} dx$$

$$= -\frac{g'(\mathbf{v})}{\mathbf{z}_{0}\mu_{1}} + \mathbf{x} \frac{\xi_{2}\zeta_{1} - \mathbf{z}_{0}\xi_{1}\zeta_{2}}{\mathbf{G} \mathbf{z}_{0}^{2} \mathbf{\zeta}_{1}^{2}} \Big|_{0}^{\infty} - \frac{1}{\mathbf{G}^{2}\mathbf{z}_{0}^{2}} \int_{0}^{\infty} d\lambda \Big[\frac{\xi_{2}}{\mathbf{z}_{0}\varepsilon_{1}^{2}} + \frac{\xi_{1}\zeta_{2}}{\mathbf{\zeta}_{1}^{2}} \Big] \frac{1}{\xi_{1}} dx$$

$$= -\frac{g'(\mathbf{v})}{\mathbf{z}_{0}\mu_{1}} - \frac{g''(\mathbf{v})}{\mathbf{G}\mathbf{z}_{0}^{2} \mu_{1}^{2}} - \frac{g''(\mathbf{v})}{\mathbf{G}\mathbf{z}_{0}^{2}} \frac{\mu_{2}^{2}}{\mu_{1}^{2}}$$

$$- \frac{1}{\mathbf{G}^{2}\mathbf{z}_{0}^{2}} \int_{0}^{\infty} \Big[\frac{\xi_{3}\zeta_{1}^{2} - 2\mathbf{z}_{0}\xi_{2}\zeta_{1}\zeta_{2}}{\mathbf{z}_{0}\zeta_{1}^{2}} + \frac{\xi_{2}\zeta_{2}\zeta_{1}^{2} + \xi_{0}\xi_{1}\zeta_{3}\zeta_{1}^{2}}{\mathbf{\zeta}_{1}^{2}} - \frac{3\mathbf{z}_{0}\xi_{1}\zeta_{2}^{2}\zeta_{1}^{2}}{\mathbf{\zeta}_{1}^{2}} \Big] dx$$

$$= -\frac{g'(\mathbf{v})}{\mathbf{z}_{0}\mu_{1}} - \frac{g''(\mathbf{v})}{\mathbf{G}\mathbf{z}_{0}^{2} \mu_{1}^{2}} - \frac{g''(\mathbf{v})}{\mathbf{G}\mathbf{z}_{0}^{2} \mu_{1}^{2}} + \frac{\xi_{2}\zeta_{2}\zeta_{2}^{2}}{\mathbf{z}_{1}^{2}} + \frac{g''(\mathbf{v})}{\mathbf{G}^{2}\mathbf{z}_{0}^{2}} \frac{\mu_{2}^{2}}{\mu_{1}^{2}} - \frac{g''(\mathbf{v})}{\mathbf{G}^{2}\mathbf{z}_{0}^{2}} \frac{\mu_{3}^{2}}{\mu_{1}^{4}} - \frac{g''(\mathbf{v})}{\mathbf{G}^{2}\mathbf{z}_{0}^{2}} \frac{\mu_{3}^{2}}{\mu_{1}^{4}} + 3\frac{g''(\mathbf{v})}{\mathbf{G}^{2}\mathbf{z}_{0}^{2}} \frac{\mu_{2}^{2}}{\mu_{1}^{2}} + \int_{0}^{\infty} \dots dx$$

which is used in (6.24)

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